# The Upper and Forcing Fault Tolerant Geodetic Number of a Graph 

T. Jeba Raj ${ }^{1}$<br>K. Bensiger ${ }^{2}$


#### Abstract

A fault tolerant geodetic $S \subseteq V$ is said to be minimal fault tolerant geodetic set of $G$ if no proper subset of $S$ is a fault tolerant geodetic set of $G$ is called the upper fault tolerant geodetic number of $G$ is denoted by $\gamma_{g f t}^{+}(G)$. Some general properties satisfied by this concept are studied. For connected graphs of order $n \geq 3$ with $\gamma_{g f t}^{+}(G)$ to be $n-1$ is given. It is shown that for every pair of $a, b$ with $5 \leq a<b$, there exists a connected graph $G$ such that $\gamma_{g f t}(G)=a$ and $\gamma_{g f t}^{+}(G)=b$, where $\gamma_{g f t}(G)$ is the fault tolerant geodetic number of $G$ and $\gamma_{g f t}^{+}(G)$ is the upper fault tolerant geodetic number of a graph. Let $S$ be a $g f t$-set of $G$. A subset $T \subseteq S$ is called a forcing subset for $S$ if $S$ is the unique $g f t$-set containing T. A forcing subset for $S$ of minimum cardinality is a minimum forcing subset of $S$. The forcing fault tolerant geodetic number of $S$, denoted by $f_{g f t}(S)$, is the cardinality of a minimum forcing subset of $S$. The forcing fault tolerant geodetic number of $G$, denoted by $f_{g f t}(G)$, is $f_{g f t}(G)=\min \left\{f_{g f t}(S)\right\}$, where the minimum is taken over all $f_{g f t}$-sets in $G$. The forcing fault tolerant geodetic number of some standard graphs are determined. Some of its general properties are studied. It is shown that for every pair of positive integers $a$ and $b$ with $0 \leq a \leq b, b \geq 2$ and $b \geq 2 a$, there exists a connected graph $G$ such that $f_{g f t}(G)=a \operatorname{and} g_{f t}(G)=b$.


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## 1. Introduction

By a graph $G=(V, E)$, we mean a finite, undirected connected graph without loops or multiple edges. The order and size of $G$ are denoted by $n$ and $m$ respectively. For basic graph theoretic terminology, we refer to [9]. Two vertices $u$ and $v$ of said to be adjacent in $G$ if $u v \in E(G)$. The neighborhood $N(v)$ of the vertex $v$ in $G$ is the set of vertices adjacent to $v$. The degree of the vertex $v$ is $\operatorname{deg}(v)=|N(v)|$. If $e=\{u, v\}$ is an edge of a graph $G$ with $\operatorname{deg}(u)=1$ and $\operatorname{deg}(v)>1$, then we call $e$ an end edge, $u$ a leaf and $v$ a support vertex. For any connected graph $G$, a vertex $v \in V(G)$ is called a cut vertex of $G$ if $V(G)-v$ is disconnected. The subgraph induced by set $S$ of vertices of a graph $G$ is denoted by $\langle S\rangle$ with $V(\langle S\rangle)=S$ and $E(\langle S\rangle)=\{u v \in E(G): u, v \in$ $S\}$. A vertex $v$ is called an extreme vertex of $G$ if $\langle N(v)\rangle$ is complete.

A vertex $x$ is an internal vertex of an $u-v$ path $P$ if $x$ is a vertex of $P$ and $x \neq$ $u, v$. An edge $e$ of $G$ is an internal edge of an $u-v$ path $P$ if $e$ is an edge of $P$ with both of its ends or in $P$. The distance $d(u, v)$ between two vertices $u$ and $v$ in a connected graph $G$ is the length of a shortest $u-v$ path in $G$. An $u-v$ path of length $d(u, v)$ is called an $u$-vgeodesic. A vertex $x$ is said to lie on an $u-v$ geodesic $P$ if $x$ isa vertex of $P$ including the vertices $u$ and $v$. For a vertex $v$ of $G$, the eccentricity $e(v)$ is the distance between $v$ and a vertex farthest from $v$. The minimum eccentricity among the vertices of $G$ is the radius, $\operatorname{rad}(G)$ and the maximum eccentricity is its diameter, $\operatorname{diam}(G)$. We denote $\operatorname{rad}(G)$ by $r$ and $\operatorname{diam}(G)$ by $d$. The closed interval $I[u, v]$ consists of $u, v$ and all vertices lying on some $u-v$ geodesic of $G$. For a non-empty set $S \subseteq V(G)$, the set $I[S]=\cup_{u, v \in S} I[u, v]$ is the closure of $S$. A set $S \subseteq V(G)$ is called a geodetic set if $I[S]=V(G)$. Thus every vertex of $G$ is contained in a geodesic joining some pair of vertices in $S$. The minimum cardinality of a geodetic set of $G$ is called the geodetic number of $G$ and is denoted by $g(G)$. A geodetic set of minimum cardinalities is called $g$-set of $G$. For references on geodetic parameters in graphs see [4, 5, 6, 7, 10]. Let $S$ be a geodetic set of $G$. $W$ be the set of extreme vertices of $G$. Then $S$ is said to be a fault tolerant geodetic set of $G$, if $S-\{v\}$ is also a geodetic set of $G$ for every $v \in$ $S \backslash W$. The minimum cardinality of a fault tolerant geodetic set is called fault tolerant geodetic number and is denoted by $g_{f t}(G)$. The minimum fault tolerant geodetic dominating set of $G$ is denoted by $g_{f t}$-set of $G$.The following theorem is used in the sequel.

Theorem 1.1. [6] Each extreme vertex of a connected graph $G$ belongs to every geodetic set of G.

## 2.The Upper Fault Tolerant Geodetic Number of a Graph

Definition 2.1. A fault tolerant geodetic $S \subseteq V$ is said to be minimal fault tolerant geodetic set of $G$ if no proper subset of $S$ is a fault tolerant geodetic set of $G$ is called the upper fault tolerant geodetic number of $G$ is denoted by $\gamma_{g f t}^{+}(G)$.

Example 2.2. For the graph $G$ given in Figure 2.1, $S_{1}=\left\{v_{1}, v_{2}, v_{5}, v_{6}\right\}$ is a $\gamma_{g f t}$-setof $G$ so that $\gamma_{g f t}(G)=5$. Let $S_{1}=\left\{v_{1}, v_{5}, v_{6}, v_{7}, v_{8}, v_{9}\right\}$. Then $S_{1}$ is a minimal faulttolerant geodetic set of $G$ and so $\gamma_{g f t}^{+}(G) \geq 6$. It is easily verified that there is no faulttolerant geodetic set of $G$ with cardinality more than six. Therefore $\gamma_{g f t}^{+}(G)=6$.


Figure 2.1
Observation 2.3. (i) For a connected graph of order $n \geq 2,2 \leq \gamma_{g f t}(G) \leq \gamma_{g f t}^{+}(G) \leq$ $n$.
(ii) No cut vertex of $G$ belongs to any minimal fault tolerant geodetic set of $G$.
(iii) Each extreme vertex of $G$ belong to any minimal fault tolerant geodetic set of $G$.

Theorem 2.4. For the complete graph $G=K_{n} n \geq 2, \gamma_{g f t}^{+}(G)=n$.
Proof: This follows from Observation 2.3(iii).
Theorem 2.5. For any non-trivial tree, $\gamma_{g f t}^{+}(G)=$ number of end vertices
Proof: This follows from Observation 2.3(ii) and (iii).
Theorem 2.6. For the cycle $G=C_{n}(n \geq 4), \gamma_{g f t}^{+}(G)=\left\{\begin{array}{l}4 \text { ifnisodd } \\ 5 \text { ifniseven }\end{array}\right.$
Proof: Let n be even. Let $v$ be the antipodal vertex of $u$ and $y$ be the antipodal vertex of $x$, where $u \neq x$. Then $S=\{u, v, x, y\}$ is a minimal fault tolerant geodetic set of $G$ and so $\gamma_{g f t}^{+}(G) \geq 4$. We prove that $\gamma_{g f t}^{+}(G)=4$. On the contrary, suppose that $\gamma_{g f t}^{+}(G) \geq 5$.

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Then there exists a geodetic set $S^{\prime}$ such that $\left|S^{\prime}\right| \geq 5$. Then there exist at least two pair of antipodal vertices of $G$. Hence it follows that $S \subset S^{\prime}$, which is a contradiction. Therefore $\gamma_{g f t}^{+}(G)=4$.
Let $n$ be odd. Let $u$ and $x$ be two adjacent vertices of $G$. Let $v$ and $w$ be antipodal vertices of $u$,wand $y$ be two antipodal vertices of $x$. Then $M=\{u, v, w, x, y\}$ is a minimal fault tolerant geodetic set of $G$ and so $\gamma_{g f t}^{+}(G) \geq 5$. We prove that $\gamma_{g f t}^{+}(G)=5$. On the contrary, suppose that $\gamma_{g f t}^{+}(G) \geq 6$. Then there exists a fault tolerant geodetic set $M^{\prime}$ of $G$ such that $\left|M^{\prime}\right| \geq 6$.Then $M^{\prime}$ contains two pair of antipodal vertices. Which implies $M \subset M^{\prime}$, which is a contradiction. Therefore $\gamma_{g f t}^{+}(G)=5$.

Theorem 2.7. Let $G$ be the complete bipartite graph $K_{r, s},(2 \leq r \leq s), \gamma_{g f t}^{+}(G)$ $=s+2$.
Proof: Let $X=\left\{x_{1}, x_{2}, \ldots, x_{r}\right\}$ and $Y=\left\{y_{1}, y_{2}, \ldots, y_{s}\right\}$ be the two bipartite sets of $G$.
Let $S=Y \cup\left\{x_{i}, x_{j}\right\}$, where $2 \leq i \neq j \leq r$ is a fault tolerant geodetic set of $G$ and so $\gamma_{g f t}^{+}(G) \geq s+2$. We prove that $\gamma_{g f t}^{+}(G)=s+2$. On the contrary, suppose that $\gamma_{g f t}^{+}(G) \geq s+3$. Then there exists a fault tolerant geodetic set of $G$ such that $\left|S^{\prime}\right| \geq$ $s+3$. Which implies $S \subseteq S^{\prime}$, which is a contradiction. Therefore $\gamma_{g f t}^{+}(G)=s+2$.

Theorem 2.8. For every pair of $a, b$ with $5 \leq a<b$, there exists a connected graph $G$ such that $\gamma_{g f t}(G)=a$ and $\gamma_{g f t}^{+}(G)=b$.
Proof: Let $P: v_{1}, v_{2}, v_{3}, v_{4}, v_{5}$ be a path on five vertices and $V\left(K_{b-a-2}\right)=$ $\left\{z_{1}, z_{2}, \ldots, z_{b-a-2}\right\}$. Let $H$ be a graph obtained from $P$ and $V\left(K_{b-a-2}\right)$ by joining each $z_{i}(1 \leq i \leq b-a+2)$ with $v_{1}$ and $v_{5}$. Let $G$ be the graph obtained from $H$ by introducing the vertices $h_{1}, h_{2}, \ldots, h_{a-4}$ and join each $h_{i}(1 \leq i \leq a-4)$ with $v_{3}$. The graph $G$ is shown in Figure 2.2.
First, we prove that $\gamma_{g f t}(G)=a$. Let $X=\left\{h_{1}, h_{2}, \ldots, h_{a-4}\right\}$ be the set of end vertices of $G$. By Observation 2.3(iii), $X$ is a subset of every fault tolerant geodetic set of $G$. It is easily verified that there is no fault tolerant geodetic set of cardinality less than a and so $\gamma_{g f t}(G) \geq a$. Let $S=X \cup\left\{v_{1}, v_{2}, v_{4}, v_{5}\right\}$ is a fault tolerant geodetic set of $G$ so that $\gamma_{g f t}(G)=a$.
Next, we prove that $\gamma_{g f t}^{+}(G)=b$. Let $M=X \cup\left\{z_{1}, z_{2}, \ldots, z_{b-a-2}, v_{1}, v_{4}\right\}$. Then $M$ is a minimal fault tolerant geodetic set of $G$ and so $\gamma_{g f t}^{+}(G) \geq b$. We prove that $\gamma_{g f t}^{+}(G)=$ $b$. On the contrary, suppose that $\gamma_{g f t}^{+}(G) \geq b+1$. Then there existsa fault tolerant geodetic set $M^{\prime}$ of $G$ such that $\left|M^{\prime}\right| \geq b+1$. Since $v_{3} \notin M^{\prime}$ and $|V(G)|=b+3$, it follows that either $S \subset M^{\prime}$ or $M \subset M^{\prime}$, which is a contradiction. Therefore $\gamma_{g f t}^{+}(G)=$ b.


## 3. The Forcing Fault Tolerant Geodetic Number of a Graph

Definition 3.1. Let $S$ be a $g_{f t}$-set of $G$. A subset $T \subseteq S$ is called a forcing subset for $S$ if $S$ is the unique $f_{g f t}$-set containing $T$. A forcing subset for $S$ of minimum cardinality is a minimum forcing subset of $S$. The forcing fault tolerant geodetic number of $S$, denoted by $f_{g f t}(S)$, is the cardinality of a minimum forcing subset of $S$. The forcing fault tolerant geodetic number of $G$, denoted by $f_{g f t}(G)$, is $f_{g f t}(G)=\min \left\{f_{g f t}(S)\right\}$, where the minimum is taken over all $f_{g f t^{-}}$sets in $G$.

Example 3.2. For the graph $G$ given in Figure 3.1, $S_{1}=\left\{v_{1}, v_{3}, v_{4}, v_{5}, v_{6}\right\}, S_{2}=$ $\left\{v_{1}, v_{2}, v_{4}, v_{5}, v_{7}\right\}$ are the only two $g_{f t}$-sets of $G$ so that $f_{g f t}\left(S_{1}\right)=f_{g f t}\left(S_{2}\right)=1$ so that $g_{f t}(G)=1$ and $f_{g f t}(G)=1$.


Figure 3.1

The next theorem follows immediately from the definition of the forcing fault tolerant geodetic number of the graph.

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Theorem 3.3. For any connected graph $G, 0 \leq f_{g f t}(G) \leq g_{f t}(G)$.
In the following we determine the forcing fault tolerant geodetic number of some standard graphs.

Theorem 3.4. For a non-trivial tree $T, f_{g f t}(G)=0$.
Proof: Since for a tree $T$, the set of end vertices of $G$ is the unique $g_{f t}$-set of $G$. Hence it follows that $f_{g f t}(G)=0$.

Theorem 3.5. For the complete graph $G=K_{n}(n \geq 3), f_{g f t}(G)=0$.
Proof: Since $S=V(G)$ is the unique $g_{f t}$-set of $G, f_{g f t}(G)=0$.
Theorem 3.6. For the cycle $G=C_{n}(n \geq 4), f_{g f t}(G)=\left\{\begin{array}{l}0 \quad \text { ifn }=4 \text { or } 5 \\ 1 \text { ifnisevenand } \geq 6 \\ 3 \text { ifnisoddand } \geq 7\end{array}\right.$
Proof: Let $V\left(C_{n}\right)=\left\{v_{1}, v_{2}, \ldots, v_{n}, v_{1}\right\}$.
Case 1. Let $n$ is even. For $n=4, S=V(G)$ is the unique $g_{f t}$-set of $G$ so that $f_{g f t}(G)$ $=0$. So, let $n \geq 6$. letn $=2 k(k \geq 3)$. Let $S_{1}=\{x, y, u, v\}$ be a $g_{f t}$-set of $G$, where $y$ is the antipodal vertex of $x$ and $u$ is the antipodal vertex of $u$. Since $n \geq 6, g_{f t}$-set of $G$ is not unique and so $f_{g f t}(G)=1$. Since $S_{1}$ is the unique $g_{f t}$-set of $G$ containing $S_{1}$, $f_{g f t}\left(S_{1}\right)=1$ so that $f_{g f t}(G)=1$.
Case 2. Let $n$ is odd. For $n=5, S=V(G)$ is the unique $g_{f t}$-set of $G$ so that $f_{g f t}(G)=$ 0 . So, let $n \geq 7$. letn $=2 k+1(k \geq 3)$. Then it is easily verified that no singleton or two element subsets of a $g_{f t}$-set $S_{1}$ is not a forcing subset of $S_{2}$. Let $S_{2}=$ $\left\{v_{1}, v_{k+1}, v_{k+2}\right\} \cup\left\{v_{2}, v_{k+3}\right\}$. Then $S_{2}$ is the $g_{f t}$-set of $G$ containing $\left\{v_{1}, v_{k+1}, v_{k+2}\right\}$. Therefore $f_{g f t}(G)=3$.

Theorem 3.7. For the fan graph $G=K_{1}+P_{n-1}(n \geq 4), f_{g f t}(G)=0$.
Proof: Let $V\left(K_{1}\right)=\{x\}$ and $S=V(G)-\{x\}$ is the unique $g_{f t}$-set of $G$ so that $f_{g f t}(G)=0$.

Theorem 3.8. For the wheel graph $G=K_{1}+C_{n-1}(n \geq 4), f_{g f t}(G)=0$.
Proof: Let $V\left(K_{1}\right)=\{x\}$ and $S=V(G)-\{x\}$ is the unique $g_{f t}$-set of $G$ so that $f_{g f t}(G)=0$.

Theorem 3.9. For the complete bipartite graph $G=K_{m, n}(2 \leq r \geq s)$,
$f_{g f t}(G)=\left\{\begin{array}{cc}0 & 2 \leq r \leq s \leq 3 \\ 3 & r=3, s \geq 4 \\ 4 & 4 \leq r \leq s\end{array}\right.$
Proof: Let $X=\left\{x_{1}, x_{2}, \ldots, x_{r}\right\}$ and $Y=\left\{y_{1}, y_{2}, \ldots, y_{s}\right\}$ be the two partite sets of $G$.
Let $S=2$. Then $G=C_{4}$. By Theorem, $f_{g f t}(G)=0$.

For $r=2$ and $s \geq 3$. Then $S=V(G)$ is the unique $g_{f t}$-set of $G$ so that $f_{g f t}(G)=0$. So let $r=3, s=3$. Then $S=V(G)$ is the unique $g_{f t}$-set of $G$ so that $f_{g f t}(G)=$ 0 .Forr $=3, s \geq 4$, let $S$ be a $g_{f t}$-set of $G$. Then any two element subsets of $S$ is a forcing subset of $G$ and so $f_{g f t}(G) \geq 3$. Let $S=\left\{x_{1}, x_{2}, x_{3}, y_{1}, y_{2}, y_{3}\right\}$. Then $\left\{x_{1}, x_{2}, y_{1}, y_{2}\right\}$ is a forcing subset of $S$ so that $f_{g f t}(G)=3$. Since this is true for al $g_{f t^{-}}$ set of $G, f_{g f t}(G)=3$. Let $m \geq 4$ and $n \geq 4$. Let $S$ be a $g_{f t}$-set of $G$. Then one or two or three element subsets of $S$ is a forcing subset of $S$ and so $f_{g f t}(G) \geq 4$. Let $S=$ $\left\{x_{1}, x_{2}, x_{3}, y_{1}, y_{2}, y_{3}\right\}$. Then $\left\{x_{1}, x_{2}, y_{1}, y_{2}\right\}$ is a forcing subset of $S$ so that $f_{g f t}(G)=4$. Since this is true for all $g_{f t}$-set $\operatorname{Sof} G, f_{g f t}(G)=4$.

Theorem 3.10. For every pair of positive integers $a$ and $b$ with $0 \leq a \leq b, b \geq 2$ and $b \geq 2 a$, there exists a connected graph $G$ such that $f_{g f t}(G)=a$ and $g_{f t}(G)=b$.
Proof: Let $P: x, y, z$ be a path on three vertices. Let $P_{i}: u_{i}, v_{i}, w_{i}(1 \leq i \leq a)$ be a copy of path on three vertices. Let $G$ be the graph obtained from $P$ and $P_{i}(1 \leq i \leq a)$ by adding new vertices $z_{1}, z_{2}, \ldots, z_{b-2 a}$ and introducing the edges $x x_{i}(1 \leq i \leq$ $a), z v_{i}(1 \leq i \leq a)$ and $z z_{i}(1 \leq i \leq b-2 a)$. The graph is shown in Figure 3.2.
First, we prove that $g_{f t}(G)=b$. Let $Z=\left\{z_{1}, z_{2}, \ldots, z_{b-2 a}\right\} \cup\left\{u_{1}, u_{2}, \ldots, u_{a}\right\}$. Then $Z$ is a subset of every $g_{f t}$-set of $G$. Let $H_{i}=\left\{u_{i}, w_{i}\right\}(1 \leq i \leq a)$. Then every $g_{f t}$-set of $G$ contains at least one vertex from each $H_{i}(1 \leq i \leq a)$ and so $g_{f t}(G) \geq b-2 a+a+$ $a=b$. Let $S=Z \cup\left\{u_{1}, u_{2}, \ldots, u_{a}\right\}$. Then $S$ is a $g_{f t}$-set of $G$ so that $g_{f t}(G)=\mathrm{b}$.
Next, we prove that $f_{g f t}(G)=a$. By Theorem $f_{g f t}(G) \leq g_{f t}(G)-|Z|=b-(b-$ $a)=a$. Now since every $Z$ is a subset of every $g_{f t}$-set of $G$ and every $g_{f t}$-set contains at least one vertex from each $H_{i}(1 \leq i \leq a)$, every $g_{f t}$-set $S$ is of the form $S=Z \cup$ $\left\{c_{1}, c_{2}, \ldots, c_{a}\right\}$, where $c_{i} \in H_{i}(1 \leq i \leq a)$. Let $T$ be a forcing subset with $|T|<a$. Then there exists $H_{i}$ for some $i$ such that $T \cap H_{i}=\phi$. Therefore $f_{g f t}(G)=a$.


Figure 3.2

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[^0]:    ${ }^{1}$ Assistant Professor, Department of Mathematics, Malankara Catholic College, Mariagiri, Kaliyakkavilai - 629 153, India, Email: jebaraj ${ }_{\text {math }}$ @ gmail.com
    ${ }^{2}$ Register Number. 20123082091004, Research Scholar, Department of Mathematics, Malankara Catholic College, Mariagiri, Kaliyakkavilai - 629 153, India. Email: bensigerkm83@gmail.com
    (Affiliated to Manonmaniam Sundaranar University, Abishekapatti, Tirunelveli - 627 012, Tamil Nadu, India.)
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