

## ANALYSIS OF SOLUTIONS AND DISEASE PROGRESSIONS FOR A WITHIN-HOST TUBERCULOSIS MODEL

WENJING ZHANG, FEDERICO FRASCOLI, AND JANE M HEFFERNAN

ABSTRACT. *Mycobacterium tuberculosis* infection can lead to different disease outcomes, we analyze a within-host tuberculosis infection model considering interactions among macrophages, T lymphocytes, and tuberculosis bacteria to understand the dynamics of disease progression. Four coexisting equilibria that reflect TB disease dynamics are present: clearance, latency, and primary disease, with low and high pathogen loads. We also derive the conditions for backward and forward bifurcations and for global stable disease free equilibrium, which affect how the disease progresses. Numerical bifurcation analysis and simulations elucidate the dynamics of fast and slow disease progression.

### 1. INTRODUCTION

*Mycobacterium tuberculosis* (Mtb) is a bacterium that causes an ancient and deadly infectious disease in humans, called tuberculosis (TB) [9]. Currently, TB affects approximately one third of the world's population [10, 6]. In 2018, the World Health Organization (WHO) estimated approximately 10 million infections globally, and 1.2 million deaths among HIV-negative people [12]. It has also been found that TB susceptibility and disease are increased in HIV-AIDS infected individuals, resulting in higher mortality rates [8, 1, 14, 16].

The pathological outcomes of TB infection include clearance, latent infection, and primary disease with fast or slow progression [13]. After initial infection, 5–10% of infected subjects can clear the disease. Of the remaining individuals, 5–10% will progress to primary disease, and the rest will remain in a latently infected state with no clinical symptoms, with the possibility of re-activation to primary disease later in their life. A large number of mechanisms have been proposed to explain TB disease progression considering individual factors, including bacterial and immune response mechanisms. However, the most influential factors for TB outcomes are not currently known. Motivated by this, we analyze a TB host-pathogen model first proposed in Ref. [3]. The model incorporates known mechanisms of host-pathogen interaction in TB dynamics, and includes all realistic disease outcomes. Analysis is performed to determine the driving factors behind disease progression and outcome, especially fast or slow progression to primary disease.

The paper is organized as follows. In Section 2, we introduce the established tuberculosis progression model. In Section 3, model dynamics are shown through the proofs of the well-posedness of solutions, the existence of equilibrium solutions, and analyses of the disease free equilibrium. The basic reproduction number  $R_0$  and the vector field on the center manifold for the disease free equilibrium when  $R_0 = 1$  are derived analytically. The conditions for the occurrence of the backward and forward bifurcations

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are also derived. In Section 4, numerical continuations are carried out for the infected equilibrium to confirm the existence of a backward bifurcation. The corresponding numerical simulations show the fast and slow disease progressions to latency and primary diseases. Finally, conclusions are drawn in Section 5.

## 2. MODEL

The 4-dimensional model (2.1) includes the MTb ideal target cell population, macrophages (their uninfected  $M_u$  and infected  $M_i$  populations). It also includes the Mtb bacterial population  $B$ , and a population of CD4 T cells, which aid in TB clearance. The model is as follows:

$$\begin{aligned}
\frac{dM_u}{dt} &= s_M - \mu_M M_u - \beta M_u B \\
\frac{dM_i}{dt} &= \beta M_u B - b M_i - \gamma M_i \frac{T/M_i}{T/M_i + c} \\
\frac{dB}{dt} &= \delta B \left(1 - \frac{B}{K}\right) + M_i \left(N_1 b + N_2 \gamma \frac{T/M_i}{T/M_i + c}\right) - M_u B (\eta + N_3 \beta) \\
\frac{dT}{dt} &= s_T + \frac{c_M M_i T}{e_M T + 1} + \frac{c_B B T}{e_B T + 1} - \mu_T T.
\end{aligned} \tag{2.1}$$

Briefly, uninfected macrophages  $M_u$  enter the system with constant rate  $s_M$ , and can die naturally ( $\mu_M$ ), or be infected by the pathogen  $B$  ( $\beta M_u B$ ). It is assumed that infected macrophages can release new bacteria into the system in two different ways: (1) through cell death and bursting  $b$ , producing  $N_1$  new bacteria, and (2) through cytotoxic T-lymphocyte killing (represented by the ratio  $T/M_i$ ) with rate  $\gamma$  and saturating factor  $c$ , which releases  $N_2$  new bacteria into the system. It is assumed that the bacteria population can divide ( $\delta B(1 - B/K)$ ) and that bacteria can be lost due to interaction with macrophages. This occurs through immune system neutralization  $\eta B M_u$  or macrophage infection  $\beta B M_u$  involving, on average,  $N_3$  individual bacteria. Finally, it is assumed that T-cells are produced at a constant rate  $s_T$  by the thymus, can be stimulated to proliferate through interactions with the infected macrophage  $c_M M_i T / (e_M T + 1)$  and bacteria  $c_B B T / (e_B T + 1)$ , and can die naturally, with rate  $\mu_T$ . Infection is initiated with an initial pathogen load. We refer the reader to Du et al. [3] for more detail on the biology and model assumptions. Parameters and their values are listed in Table 1.

In previous work, Du et al. [3] found four biologically realistic equilibria and determined the basic reproduction number. Note that, in the original contribution, there is no mention of the driving factors behind the different outcomes of disease (namely, clearance, latency, and primary disease with fast or slow progression) and only an asymptotic version of the model that neglects the effects of the CD4 T-cell population is used/analyzed. In the following, we expand and elaborate on the four disease outcomes and other interesting aspects of the model using the full model system Eq. 2.1.

## 3. MODEL DYNAMICS

### 3.1. Well-posedness of solutions. Let

$$\mathcal{D} = \{(M_u, M_i, B, T) \in \mathbb{R}_+^4 : M_u + M_i \leq M_{max}, B \leq B_{max}, T \leq T_{max}\}, \quad \text{where}$$

$$\begin{aligned}
M_{max} &= \frac{s_M}{\min\{\mu_M, b\}}, & T_{max} &= \frac{1}{\mu_T} \left( s_T + \frac{c_M}{e_M} M_{max} + \frac{c_B}{e_B} B_{max} \right), \\
B_{max} &= \frac{K}{2} + \frac{\sqrt{(4K\delta M_{max}(N_1 b + N_2 \gamma) + K^2 \delta^2)}}{2\delta}.
\end{aligned} \tag{3.1}$$

**Proposition 3.1.** *Under the flow of (2.1), there exists a positive invariant set  $\mathcal{D}$  that attracts all solutions in  $\mathbb{R}_+^4$  as time moves forward.*

*Proof.* The smoothness of the right hand side of model (2.1) guarantees the local existence and uniqueness of the solution of the initial value problem of model (2.1). The trajectories starting from positive initial values never cross the boundary of  $\mathbb{R}_+^4$ , since

$$\frac{dM_u}{dt}|_{M_u=0} = s_M > 0, \quad \frac{dM_i}{dt}|_{M_i=0} = \beta M_u B \geq 0,$$

and

$$\frac{dB}{dt}|_{B=0} = M_i \left( N_1 b + N_2 \gamma \frac{T}{T + cM_i} \right) \geq 0, \quad \frac{dT}{dt}|_{T=0} = s_T > 0.$$

Next, we show that positive solutions are bounded. Due to the positiveness, we have

$$\frac{d}{dt}(M_u + M_i) < s_M - \mu_M M_u - bM_i \Rightarrow \lim_{t \rightarrow +\infty} \sup(M_u + M_i)(t) = \frac{s_M}{\min\{\mu_M, b\}} := M_{max}.$$

Moreover,

$$\begin{aligned} \frac{dB}{dt} &< \delta B \left( 1 - \frac{B}{K} \right) + M_i (N_1 b + N_2 \gamma) - M_u B (\eta + N_3 \beta), \quad \frac{T}{T + cM_i} \in (0, 1) \\ &< -\frac{\delta}{K} B^2 + \delta B + M_{max} (N_1 b + N_2 \gamma) \\ &\Rightarrow B(t) = K/2 + \tanh \left[ \sqrt{(4K\delta M_{max}(N_1 b + N_2 \gamma) + K^2 \delta^2)}(C_0 + t)/(2K) \right] \\ &\quad \times \sqrt{(4K\delta M_{max}(N_1 b + N_2 \gamma) + K^2 \delta^2)/(2\delta)}, \end{aligned}$$

where  $C_0$  is determined by initial condition and  $C_0 + t > 0$  for sufficiently large  $t$ . We have

$$B(t) = \frac{K}{2} + \frac{\sqrt{(4K\delta M_{max}(N_1 b + N_2 \gamma) + K^2 \delta^2)}}{2\delta} := B_{max}.$$

Then, the last equation in (2.1) satisfies

$$\frac{dT}{dt} < s_T + \frac{c_M M_{max} T}{e_M T + 1} + \frac{c_B B_{max} T}{e_B T + 1} - \mu_T T < s_T + \frac{c_M}{e_M} M_{max} + \frac{c_B}{e_B} B_{max} - \mu_T T.$$

It hence follows that

$$T(t) < \frac{1}{\mu_T} \left( s_T + \frac{c_M}{e_M} M_{max} + \frac{c_B}{e_B} B_{max} \right) := T_{max},$$

and the proposition is proven.  $\square$

**3.2. Equilibrium Solutions.** Denote model (2.1) as  $M'_u = f_1$ ,  $M'_i = f_2$ ,  $B' = f_3$ ,  $T' = f_4$ . The corresponding steady states are derived as follows:

$$f_1 = 0; \Rightarrow \bar{M}_u(B) = \frac{s_M}{\beta B + \mu_M}. \quad (3.2)$$

Case 1: If  $(b + \gamma)M_i - \beta M_u B \neq 0$  or  $\beta s_M B - (b + \gamma)(\beta B + \mu_M)M_i \neq 0$ , we have

$$\begin{aligned} f_2 = 0 &\Rightarrow \bar{T}(\bar{M}_u) = cM_i \left[ \frac{\gamma M_i}{(b + \gamma)M_i - \beta \bar{M}_u B} - 1 \right] \xrightarrow{(3.2)} \\ \bar{T}(B) &= \frac{[\beta s_M B - (\beta B + \mu_M)bM_i]cM_i}{\beta s_M B - (b + \gamma)(\beta B + \mu_M)M_i}, \quad (3.3) \\ \bar{T}(B) > 0 &\text{ if } \beta s_M B < (\beta B + \mu_M)bM_i \text{ or } \beta s_M B > (b + \gamma)(\beta B + \mu_M)M_i. \end{aligned}$$

Considering the preceding results (3.2) and (3.3), we obtain

$$\begin{aligned} f_3 &= c\gamma M_i^2 f_{3a} f_{3b} = 0, \quad \text{where} \\ f_{3a} &= (b + \gamma)(\beta B + \mu_M)M_i - \beta s_M B \\ f_{3b} &= Kb(\beta B + \mu_M)M_i + ((\beta B + \mu_M)\delta + s_M[(N_2 - N_3)\beta - \eta])KB - B^2\delta(\beta B + \mu_M). \end{aligned}$$

The existence of  $\bar{T}$  in (3.3) implies  $f_{3a} \neq 0$ . Further,  $M_i = 0$  induces that  $f_4(M_u = \bar{M}_u(B), M_i = 0, B, \bar{T}(B) = 0) = s_T \neq 0$ . This indicates that the equilibrium does not exist. Therefore  $f_3 = 0$  only implies  $f_{3b} = 0$  followed by

$$\begin{aligned} \bar{M}_i(B) &= \left( \frac{B\delta}{K} - \frac{\delta + s_M(N_2 - N_3)\beta - s_M\eta}{\beta B + \mu_M} \right) \frac{B}{b(N_1 - N_2)}, \\ \bar{M}_i(B) > 0 &\quad \text{if} \quad \frac{B\delta}{K} > \frac{\delta + s_M(N_2 - N_3)\beta - s_M\eta}{\beta B + \mu_M} \quad \text{and} \quad N_1 > N_2. \end{aligned} \quad (3.4)$$

The  $B$  in (3.4) satisfies  $f_4(\bar{M}_u(B), \bar{M}_i(B), B, \bar{T}(B)) = 0$ , the following is true:

$$\begin{aligned} F(B) &= -e_B e_M \mu_T \bar{T}^3(B) + [(c_M \bar{M}_i(B) + e_M s_T - \mu_T)e_B + e_M(c_B B - \mu_T)]\bar{T}^2(B) \\ &+ [c_B B + c_M \bar{M}_i(B) + e_B s_T + e_M s_T - \mu_T]\bar{T}(B) + s_T = 0. \end{aligned} \quad (3.5)$$

Then, we find the infected equilibrium  $E^* = (\bar{M}_u(B), \bar{M}_i(B), B, \bar{T}(B))$ . We note that there could be more than one solution, and up to three feasible infected equilibria.

Case 2: If  $\beta s_M B - (b + \gamma)(\beta B + \mu_M)M_i = 0$ , we have

$$f_2 = 0 \Rightarrow \bar{M}_{i0} = \frac{\beta s_M B}{(b + \gamma)(\beta B + \mu_M)}. \quad (3.6)$$

Then substituting  $\bar{M}_u(B)$  in (3.2) and  $\bar{M}_{i0}$  in (3.6) into  $f_3(\bar{M}_u(B), \bar{M}_{i0}) = 0$ , yields

$$\bar{B}_0 = 0. \quad (3.7)$$

This is followed by  $f_4(\bar{M}_u(B), \bar{M}_{i0}, \bar{B}_0) = 0$ , which yields

$$\bar{T}_0 = \frac{s_T}{\mu_T}. \quad (3.8)$$

We thus find the disease free equilibrium (DFE)  $E_0 = (\bar{M}_u(\bar{B}_0), \bar{M}_{i0}(\bar{B}_0), \bar{B}_0, \bar{T}_0)$ , where  $\bar{M}_u(\bar{B}_0) = s_M/\mu_M$  and  $\bar{M}_{i0}(\bar{B}_0) = 0$ .

### 3.3. Analysis of the disease free equilibrium.

3.3.1. *Calculation of the basic reproduction number.* Following the next-generation matrix approach in Ref. [11], the basic reproduction number  $R_0$  is the spectral radius of  $FV^{-1}$ , where

$$FV^{-1} = \begin{bmatrix} 0 & \frac{\beta s_M}{\mu_M} \\ N_1 b + N_2 \gamma & \delta \end{bmatrix} \begin{bmatrix} b + \gamma & 0 \\ 0 & \frac{s_M}{\mu_M}(N_3 \beta + \eta) \end{bmatrix}^{-1} = \begin{bmatrix} 0 & \frac{\beta}{N_3 \beta + \eta} \\ \frac{N_1 b + N_2 \gamma}{b + \gamma} & \frac{\mu_M \delta}{s_M(N_3 \beta + \eta)} \end{bmatrix},$$

and

$$R_0 = \rho(FV^{-1}) = \frac{\delta \mu_M}{2s_M(N_3 \beta + \eta)} + \frac{1}{2} \left[ \frac{\delta^2 \mu_M^2}{s_M^2(N_3 \beta + \eta)^2} + \frac{4\beta(N_1 b + N_2 \gamma)}{(N_3 \beta + \eta)(b + \gamma)} \right]^{1/2}. \quad (3.9)$$

The Jacobian matrix of model (2.1) at the disease free equilibrium is:

$$J_0 = \begin{bmatrix} -\mu_M & 0 & -\frac{\beta s_M}{\mu_M} & 0 \\ 0 & -b - \gamma & \frac{\beta s_M}{\mu_M} & 0 \\ 0 & N_1 b + N_2 \gamma & \delta - \frac{s_M}{\mu_M} (N_3 \beta + \eta) & 0 \\ 0 & \frac{c_M s_T}{e_M s_T + \mu_T} & \frac{\mu_M c_B s_T}{e_B s_T + \mu_T} & -\mu_T \end{bmatrix}, \quad (3.10)$$

and gives the following characteristic equation

$$(z + \mu_T)(z + \mu_M)(z^2 + Pz + Q) = 0, \quad (3.11)$$

where

$$P = b + \gamma - \delta + \frac{s_M}{\mu_M} (N_3 \beta + \eta),$$

$$Q = [(-N_2 + N_3)\gamma\beta - b(N_1 - N_3)\beta + \eta(b + \gamma)] \frac{s_M}{\mu_M} - \delta(b + \gamma).$$

Equation (3.11) admits at least two negative roots,  $z = -\mu_T$  and  $z = -\mu_M$ . The third root,  $z = \delta - b - \gamma - \frac{s_M}{\mu_M} (N_3 \beta + \eta)$ , is negative if  $b + \gamma + \frac{s_M}{\mu_M} (N_3 \beta + \eta) > \delta$ . The last root is zero, if

$$[(-N_2 + N_3)\gamma\beta - b(N_1 - N_3)\beta + \eta(b + \gamma)] \frac{s_M}{\mu_M} - \delta(b + \gamma) = 0, \quad (3.12)$$

which is equivalent to  $R_0 = 1$ .

**Theorem 3.1.** *Under the condition  $b + \gamma + \frac{s_M}{\mu_M} (N_3 \beta + \eta) > \delta$ , the disease free equilibrium  $E_0$  is locally asymptotically stable if  $R_0 < 1$  and unstable if  $R_0 > 1$ .*

**3.3.2. Existence of a backward bifurcation.** Following Theorem 4.1 in Ref. [2], we first shift the disease free equilibrium to the origin by letting  $x_1 = M_u - \frac{s_M}{\mu_M}$ ,  $x_2 = M_i - 0$ ,  $x_3 = B - 0$ ,  $x_4 = T - \frac{s_T}{\mu_T}$ , and  $\phi = \beta - \beta_T$ . Here  $R_0(\beta_T) = 1$  and

$$\beta_T = \frac{(-\delta\mu_M + \eta s_M)(b + \gamma)}{s_M \gamma (N_2 - N_3) \gamma + s_M b (N_1 - N_3)}.$$

Then we compute the approximated center manifold for the system near the origin with one simple zero eigenvalue at  $R_0 = 1$ , and three negative eigenvalues. We choose a right eigenvector associated with the simple zero eigenvalue,  $w$ , and the left eigenvector,  $v$ , satisfying  $vw = 1$  as follows:

$$w = \frac{1}{n} \begin{bmatrix} \frac{(\delta\mu_M - \eta s_M)(b + \gamma)}{\mu_M^2 \tilde{w}} \\ \frac{\delta\mu_M - \eta s_M}{\mu_M \tilde{w}} \\ 1 \\ \frac{s_T \{[(\tilde{w} c_B - \delta c_M)\mu_T + (e_M \tilde{w} c_B - \delta c_M e_B) s_T] \mu_M + \eta c_M s_M (e_B s_T + \mu_T)\}}{(e_B s_T + \mu_T)(e_M s_T + \mu_T) \mu_M \mu_T \tilde{w}} \end{bmatrix},$$

$$v = \left[ 0, \frac{N_1 b + N_2 \gamma}{b + \gamma}, 1, 0 \right],$$

where

$$n = \frac{(N_2 - N_3)\mu_M\gamma + [(N_1 + N_2 - 2N_3)b - N_2\delta]\mu_M\gamma + N_2s_M\eta\gamma}{\mu_M(b + \gamma)\tilde{w}} + \frac{(N_1 - N_3)b^2\mu_M - N_1\delta b\mu_M + N_1s_M\eta b}{\mu_M(b + \gamma)\tilde{w}}$$

and

$$\tilde{w} = (N_2 - N_3)\gamma + b(N_1 - N_3).$$

Further, the flow of the center manifold  $y(t)$  truncated at the quadratic term is written as

$$\dot{y} = \mathcal{A}y^2 + \mathcal{B}\phi y, \quad (3.13)$$

$$\begin{aligned} \mathcal{A} &= \frac{v}{2} \left[ w' \left( \frac{\partial f_1}{\partial x_i \partial x_j} \right) \Big|_{E_0} w, w' \left( \frac{\partial f_2}{\partial x_i \partial x_j} \right) \Big|_{E_0} w, w' \left( \frac{\partial f_3}{\partial x_i \partial x_j} \right) \Big|_{E_0} w, w' \left( \frac{\partial f_4}{\partial x_i \partial x_j} \right) \Big|_{E_0} w \right]' \\ &= \frac{A_n}{A_d}, \end{aligned}$$

$$\begin{aligned} A_n &= ((\tilde{A} - [\mu_T c s_M (N_1 - N_2)] b \gamma) K \delta - s_M [(N_2 - N_3)\gamma + b(N_1 - N_3)]^2 (b + \gamma) s_T) \mu_M^2 \delta, \\ &\quad - s_M \delta K \eta \mu_M \tilde{A} + K \mu_T \gamma b c s_M^3 \eta^2 (N_1 - N_2), \end{aligned}$$

$$\begin{aligned} \tilde{A} &= -s_T (N_2 - N_3) \gamma^3 - b s_T (N_1 + 2N_2 - 3N_3) \gamma^2 - b^3 s_T (N_1 - N_3) \\ &\quad - (2N_1 + N_2 - 3N_3) s_T b^2 \gamma + 2(N_1 - N_2) \mu_T c s_M b \gamma, \end{aligned}$$

$$A_d = s_M \mu_M^2 [(N_2 - N_3)\gamma + b(N_1 - N_3)]^2 (b + \gamma) s_T K,$$

and

$$\mathcal{B} = v \left( \frac{\partial f_i}{\partial x_i \partial \beta} \right) \Big|_{E_0} w = \frac{[(N_2 - N_3)\gamma + b(N_1 - N_3)] s_M}{(b + \gamma) \mu_M},$$

where  $i, j = 1 \dots 4$ . The non-zero terms in  $\left( \frac{\partial f_k}{\partial x_i \partial x_j} \right) \Big|_{E_0}$ , where  $i, j, k = 1 \dots 4$ , are

$$\frac{\partial f_1}{\partial x_1 \partial x_3} \Big|_{E_0} = \frac{\partial f_1}{\partial x_3 \partial x_1} \Big|_{E_0} = -\frac{\partial f_2}{\partial x_1 \partial x_3} \Big|_{E_0} = -\frac{\partial f_2}{\partial x_3 \partial x_1} \Big|_{E_0} = \frac{(\delta \mu_M - \eta s_M)(b + \gamma)}{[(N_2 - N_3)\gamma + b(N_1 - N_3)] s_M},$$

$$\frac{\partial f_3}{\partial x_1 \partial x_3} \Big|_{E_0} = \frac{\partial f_3}{\partial x_3 \partial x_1} \Big|_{E_0} = N_3 \frac{\partial f_1}{\partial x_1 \partial x_3} \Big|_{E_0} - \eta,$$

$$\frac{\partial f_2}{\partial x_2 \partial x_2} \Big|_{E_0} = \frac{2\gamma \mu_T c}{s_T}, \quad \frac{\partial f_3}{\partial x_2 \partial x_2} \Big|_{E_0} = -N_2 \frac{2\gamma \mu_T c}{s_T}, \quad \frac{\partial f_3}{\partial x_3 \partial x_3} \Big|_{E_0} = -2 \frac{\delta}{K},$$

$$\frac{\partial f_4}{\partial x_2 \partial x_4} \Big|_{E_0} = \frac{\partial f_4}{\partial x_4 \partial x_2} \Big|_{E_0} = \frac{c_M \mu_T^2}{(e_M s_T + \mu_T)^2}, \quad \frac{\partial f_4}{\partial x_3 \partial x_4} \Big|_{E_0} = \frac{\partial f_4}{\partial x_4 \partial x_3} \Big|_{E_0} = \frac{c_B \mu_T^2}{(e_B s_T + \mu_T)^2}.$$

**Theorem 3.2.** *Under the condition  $\mathcal{B} > 0$ , we have  $A_d > 0$ . Then the model (2.1) at the disease free equilibrium  $E_0$ , when  $R_0 = 1$  undergoes (1) a backward bifurcation if  $A_n > 0$  and (2) a forward bifurcation if  $A_n < 0$ . Furthermore,  $A_n(c = 0, \beta = \beta_T, b = b_b) = 0$ , where*

$$b_b = \gamma \frac{[(N_2 - N_3)s_M + K\delta]\mu_M - \eta K s_M}{[(N_3 - N_1)s_M - K\delta]\mu_M + \eta K s_M}. \quad (3.14)$$

**3.3.3. Global stability analysis for the disease free equilibrium  $E_0$ .** Proposition 3.1 shows that state variables  $M_u, M_i, B$ , and  $T$  are bounded for sufficiently large time. That is, there exists a time  $T > 0$  such that  $M_u < M_{max}$ ,  $M_i < M_{max}$ ,  $B < B_{max}$ , and  $T < T_{max}$ . Applying the ‘‘fluctuation lemma’’ [5], there exists time sequences  $\tau_n \rightarrow \infty$  and  $\sigma_n \rightarrow +\infty$  such that

$$\begin{aligned} M_i^\infty &:= \limsup_{t \rightarrow \infty} M_i(t) = \lim_{n \rightarrow +\infty} M_i(\tau_n) \quad \text{and} \quad \lim_{n \rightarrow +\infty} \frac{dM_i(\tau_n)}{dt} = 0, \\ B^\infty &:= \limsup_{t \rightarrow \infty} B(t) = \lim_{n \rightarrow +\infty} B(\sigma_n) \quad \text{and} \quad \lim_{n \rightarrow +\infty} \frac{dB(\sigma_n)}{dt} = 0. \end{aligned} \quad (3.15)$$

The preceding equations are followed by

$$\begin{aligned} &\beta M_u(\tau_n)B(\tau_n) - bM_i^\infty - \gamma M_i^\infty \frac{T(\tau_n)}{T(\tau_n) + cM_i^\infty} = 0 \\ \implies &\beta M_u(\tau_n)B(\tau_n) = \left( b + \gamma \frac{T(\tau_n)}{T(\tau_n) + cM_i^\infty} \right) M_i^\infty \leq \beta M_{max} B^\infty \\ \longrightarrow &M_i^\infty \leq \frac{\beta M_{max} B^\infty}{b + \gamma \frac{T(\tau_n)}{T(\tau_n) + cM_i^\infty}} < \frac{\beta}{b} M_{max} B^\infty, \end{aligned} \quad (3.16)$$

and

$$\begin{aligned} &\delta B^\infty \left( 1 - \frac{B^\infty}{K} \right) + M_i(\sigma_n) \left( N_1 b + N_2 \gamma \frac{T(\sigma_n)}{T(\sigma_n) + cM_i} \right) - M_u(\sigma_n) B^\infty (\eta + N_3 \beta) = 0 \implies \\ &-\delta B^\infty \left( 1 - \frac{B^\infty}{K} \right) + M_u(\sigma_n) B^\infty (\eta + N_3 \beta) = M_i(\sigma_n) \left( N_1 b + N_2 \gamma \frac{T(\sigma_n)}{T(\sigma_n) + cM_i} \right) \leq M_i(\sigma_n) (N_1 b + N_2 \gamma) \\ &\implies [M_u(\sigma_n) (\eta + N_3 \beta) - \delta] B^\infty \leq M_i(\sigma_n) (N_1 b + N_2 \gamma) \implies \\ &B^\infty \leq M_i(\sigma_n) \frac{N_1 b + N_2 \gamma}{M_u(\sigma_n) (\eta + N_3 \beta) - \delta} \leq \frac{N_1 b + N_2 \gamma}{M_u(\sigma_n) (\eta + N_3 \beta) - \delta} M_i^\infty, \end{aligned} \quad (3.17)$$

where  $\frac{T(\tau_n)}{T(\tau_n) + cM_i^\infty} \leq 1$ . Subsequently,

$$M_i^\infty \leq \frac{\beta}{b} M_{max} B^\infty \leq \frac{\beta}{b} M_{max} \frac{N_1 b + N_2 \gamma}{M_u(\sigma_n) (\eta + N_3 \beta) - \delta} M_i^\infty. \quad (3.18)$$

If

$$\frac{\beta}{b} M_{max} \frac{N_1 b + N_2 \gamma}{M_u(\sigma_n) (\eta + N_3 \beta) - \delta} \leq 1,$$

or equivalently

$$M_u(\sigma_n) \geq \frac{1}{\eta + N_3 \beta} \left[ \frac{\beta s_M}{b \mu_M} (N_1 b + N_2 \gamma) + \delta \right] := M_u^{max}, \quad (3.19)$$

then  $M_i^\infty = 0$ , implying  $B^\infty = 0$ , and the disease free equilibrium  $E_0$  is globally stable.

**Theorem 3.3.** *If  $b + \gamma + \frac{s_M}{\mu_M} (N_3 \beta + \eta) > \delta$  and  $R_0 < 1$ , the uninfected macrophage population  $M_u$  should satisfy  $M_u \geq M_u^{max}$  to completely eliminate TB infection.*

Symbol	Description (Unites)	Value (Range)	Source
$s_M$	recruitment rate of $M_u$ (1/ml day)	5000 (0.33, 33)	[13] [7] [4]
$s_T$	recruitment rate of $T$ (1/ml day)	6.6 (3300, 7000)	[13] [7] [4]
$\mu_M$	death rate of $M_u$ (1/day)	0.01 (0.01, 0.011)	[13] [7] [4]
$b$	loss rate of $M_i$ (1/day)	0.11 (0.05, 0.5)	[13] [7] [4]
$\mu_T$	death rate of $T$ (1/day)	0.33 (0.05, 0.33)	[13] [7] [4]
$\beta$	infection rate by $B$ (1/day)	$2 \times 10^{-7}$ ( $10^{-8}$ , $10^{-5}$ )	[13] [7] [4]
$\eta$	bacteria killing rate by $M_u$ rate (1/ml day)	$1.25 \times 10^{-8}$ ( $1.25 \times 10^{-9}$ , $1.25 \times 10^{-7}$ )	[13] [7] [4]
$\gamma$	cell-mediated immunity rate (1/day)	0.5 (0.1, 2)	[13] [7] [4]
$\delta$	proliferation rate of $B$ (1/day)	$5 \times 10^{-4}$ (0, 0.26)	[13] [7] [4]
$c_M$	expansion rate of $T$ induce by $M_i$ (1/day)	$10^{-3}$ ( $10^{-8}$ , 1)	Estimated
$c_B$	expansion rate of $T$ induce by $B$ (1/day)	$5 \times 10^{-3}$ ( $10^{-8}$ , 1)	Estimated
$e_M$	saturation factor of $T$ expansion related to $M_i$	$10^{-4}$ ( $10^{-6}$ , $10^{-2}$ )	Estimated
$e_B$	saturation factor of $T$ expansion related to $B$	$10^{-4}$ ( $10^{-6}$ , $10^{-2}$ )	Estimated
$c$	half-saturation ratio for $M_i$ lysis ( $T/M_i$ )	3 (0.3, 30)	Estimated
$K$	carrying capacity of $B$ (1/ml)	$10^{-8}$ ( $10^6$ , $10^{10}$ )	Estimated
$N_1$	max MOI of $M_i$ ( $B/M_i$ )	50 (50, 100)	[13] [7] [4]
$N_2$	max No. of $B$ released by apoptosis ( $T/M_i$ )	20 (20, 30)	[13] [7] [4]
$N_3$	$N_3 = N_1/2$ ( $B/M_i$ )	25 (25, 50)	[13] [7] [4]
$M_u$	uninfected macrophages		
$M_i$	infected macrophages		
$B$	extra and intra-cellular bacteria		
$T$	CD4 T-cells		

TABLE 1. Parameter Symbol, Descriptions, Values, and Sources [3]

The occurrence of a backward bifurcation destabilizes the globally stable disease free equilibrium  $E_0$  under the condition  $R_0 < 1$  and an extra condition to regain stability is needed, i.e.  $b + \gamma + \frac{s_M}{\mu_M} (N_3\beta + \eta) > \delta$ , as shown in Theorem 3.3. In the next section, we verify the existence of a backward bifurcation computationally and investigate the associated dynamical behaviors by numerical simulations.

#### 4. BIFURCATION ANALYSIS AND NUMERICAL SIMULATIONS

Consider the  $n$ -dimensional nonlinear system with  $m$  parameter values

$$\frac{dx}{dt} = f(x, p), \quad x \in R^n, \quad p \in R^m, \quad f : R^{n+m} \rightarrow R^n. \quad (4.1)$$

The equilibrium solutions  $x_e = x_e(p)$  are derived from the equilibrium condition

$$f(x_e(p), p) = 0, \quad x \in R^n, \quad p \in R^m. \quad (4.2)$$

The local stability of the equilibrium points  $x_e(p)$  is determined by the eigenvalues of the Jacobian  $J(p) = [\partial f_i(x_e(p), p)/\partial x_j]$ , which are the roots of the corresponding characteristic polynomial equation

$$P_n(\lambda) = \det[\lambda I - J(p)] = \lambda + a_1(p)\lambda^{n-1} + a_2(p)\lambda^{n-2} + \dots + a_{n-1}(p)\lambda + a_n(p). \quad (4.3)$$

The necessary and sufficient conditions for zero-eigenvalue bifurcation (zero-singularity) are given in Ref. [15].



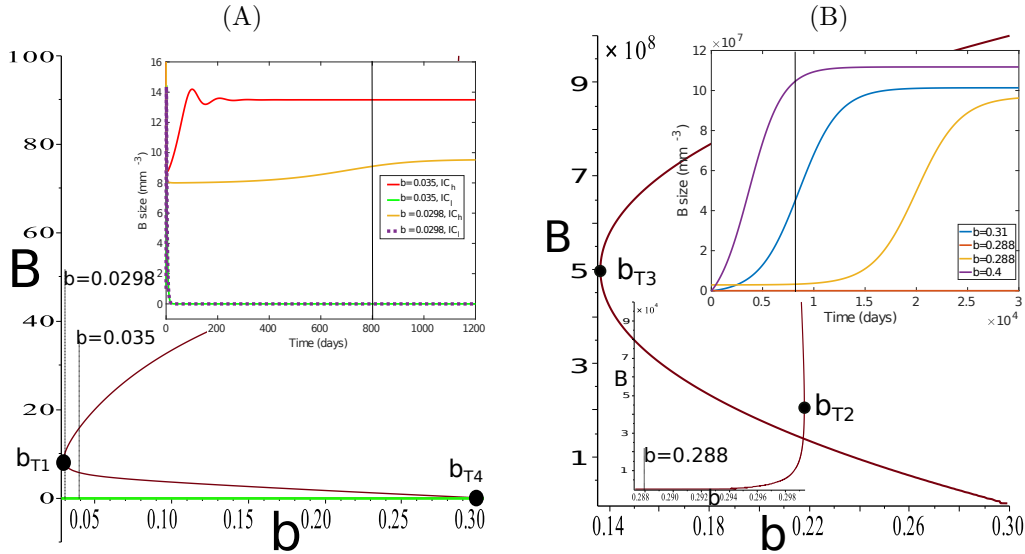


FIGURE 1. Bifurcation diagrams of model (2.1) with  $B$  vs  $b$  and simulations.  $E_0$  and  $E_1$  are in green and red curves. Four zero-eigenvalue bifurcation are denoted as black points as  $b_{T1}$ ,  $b_{T2}$ ,  $b_{T3}$ , and  $b_{T4}$ . Simulations are carried out for five fixed  $b$  values as  $b = 0.0298$ ,  $b = 0.035$ ,  $b = 0.288$ ,  $b = 0.31$ , and  $b = 0.4$ . The first three  $b$  values shows bistability. The last three  $b$  values show different progression speed for the bacterial population  $B$ .

**Theorem 4.1.** *The necessary and sufficient conditions for system (4.1) to have a  $k$ -zero singularity at a fixed point (equilibrium),  $x = x_e(p)$ , of the system are given by*

$$a_n(p) = a_{n-1}(p) = \cdots = a_{n+1-k}(p) = 0, \quad (4.4)$$

which  $a_i(p)$ 's are the coefficients of the characteristic polynomial (4.3). Further, if the remaining coefficients  $a_1, a_2, \dots, a_{n-k}$  still obey the Hurwitz conditions for order  $n - k$ , then all the remaining eigenvalues of the Jacobian have negative real parts.

Based on the results of the uncertainty and sensitivity analysis in Ref. [3], the model is significantly affected by the change of macrophage loss rate  $b$ , the infection rate  $\beta$ , cell-mediated immunity rate  $\gamma$ , and bacterial killing rate  $\eta$ . We thus choose the macrophage loss rate  $b$  as a bifurcation parameter to verify the analytical result for the backward bifurcation discussed in Theorem 3.1. The other parameter values are fixed and shown in Table 1.

Using Theorem 4.1, we numerically find four zero-eigenvalue bifurcation critical points at  $b_{T1} = 0.0295$ , with  $E_{T1} = (497833, 122, 8.7, 40)$ ,  $b_{T2} = 0.2993$ , with  $E_{T2} = (21089, 2664, 45417, 6952168)$ ,  $b_{T3} = 0.1363$ , with  $E_{T3} = (20, 3055, 49998972, 7575684467)$ , and  $b_{T4} = 0.300036$ , which yields  $E_{T4} = (500000, 0, 0, 20)$ . The summarized bifurcation, equilibria, and their stability are shown in Figure 1. Two values, i.e.  $b = 0.0298$ ,  $b = 0.035$ , are chosen near  $b_{T1}$  and time series show that bistability occur for both  $b$  values, with solutions landing onto different equilibria depending on their initial conditions (see panel (A)). This is of interest because it means that the disease can die out or persist to latency depending on the initial infection status. Interestingly, the progression to latency shows different dynamics and lasts different periods of time for the chosen  $b$  values. The red and yellow curves take different time to stabilize at their latency levels.

We then take three  $b$  values, i.e.  $b = 0.288$ ,  $b = 0.31$ , and  $b = 0.4$ , close to  $b_{T_2}$  (see panel (B)). Again, bistability occurs when  $b = 0.288$  on the left of  $b_{T_2}$ . There is an obvious difference in the speed of disease progression for the three different  $b$  values, as shown by the curves in the inset of Figure 1(B). These examples of fast and slow disease progression dynamics seem to confirm the numerical findings in Ref. [3] and are the object of current investigation.

## 5. CONCLUSION

In this paper, we analyze a four-dimensional within-host model (2.1) for tuberculosis infection, which has been previously proposed and studied numerically in Ref. [3].

We carry out analyses for the well-posedness and boundedness for solutions, existence of the disease free and infected equilibriums and local and global stability analysis. A bifurcation analysis for the disease free equilibrium is also conducted, and a numerical continuation for the infected equilibrium shows when a backward bifurcation occurs. Numerical simulations finally show how fast and slow disease progressions take place close to the bifurcation, with examples of bistability behaviour. This is important because different initial infections can lead to different disease progressions, with considerable differences among latency times.

An in-depth analysis of the bifurcation scenario of this model is currently under progress, with the aim of characterising the different, possible behaviours towards infection that TB shows.

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CORRESPONDING AUTHOR, DEPARTMENT OF MATHEMATICS AND STATISTICS, TEXAS TECH UNIVERSITY, BROADWAY AND BOSTON, LUBBOCK, TX 79409-1042.

*E-mail address:* [wenjing.zhang@ttu.edu](mailto:wenjing.zhang@ttu.edu)

DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, ENGINEERING AND TECHNOLOGY, SWINBURNE UNIVERSITY OF TECHNOLOGY, JOHN ST, 3122, HAWTHORN, VIC, AUSTRALIA.

*E-mail address:* [ffrascoli@swin.edu.au](mailto:ffrascoli@swin.edu.au)

DEPARTMENT OF MATHEMATICS AND STATISTICS, CENTRE FOR DISEASE MODELLING, YORK UNIVERSITY. 4700 KEELE ST, TORONTO, ON, CANADA, M3J 1P3.

*E-mail address:* [jmheffer@yorku.ca](mailto:jmheffer@yorku.ca)