Optimization of Cutting Parameters to Minimize Tooling Cost in High Speed Turning of SS304 Using Coated Carbide Tool using Genetic Algorithm Method

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ABSTRACT

High speed turning (HST) is an approach that can be used to increase the material removal rate (MRR) by higher cutting speed. Increasing MRR will lead to shortening time to market. In contrast, increasing the cutting speed will lead to increasing the flank wear rate and then the tooling cost. However, the main factor that will justify the best level of cutting speed is the tooling cost which merges all in one understandable measurable factor for manufacturer. The aim of this paper is to determine experimentally the optimum cutting levels that minimize the tooling cost in machining AISI 304 as a work piece machined by a coated carbide tool using one of the non-conventional methods: Genetic Algorithm (GA). The experiments were designed using Box Behnken Design (BBD) with three input factors: cutting speed, feeding speed and depth of cut and three machining levels.

Keywords: High speed turning, tooling cost, AISI 304, MRR

1 INTRODUCTION

The development of advanced manufacturing technology has been growing up rapidly. One of the advanced approaches is by increasing the machining speed to increase material removal rate and then shortening time to market, lowering cost, high accuracy and better quality. One approach for reducing the machining time in machining is by increasing the speed turning. High speed turning is difficult to define due to the fact of materials are varied for their hardness. Therefore, high speed turning for one material may still be a low speed for another for example; the high speed for titanium is a low speed for aluminium [1]. However, these technologies should be justified by economic study. One of the most effective tools for economic study is by developing a cost model.

In high speed turning the machining zone will be under high temperature and high sliding velocity. Therefore, the wear progress will be difficult to estimate and predict. However, the wear rate of the cutting tool may give unacceptable outputs and that will result a low quality of surface roughness [2]. However, estimating the tool wear is highly valuable to estimate the tooling cost due to the relationship of tool life and material removal during the life of tool. However, tool insert may reaches its life and should be removed and changed before the tool insert edge cannot give the desired and accepted roughness. If the cutting tool reaches its life very fast then this will lead to increase the tooling cost becomes. Therefore, the manufacturer needs to determine the best cutting levels that minimize the tooling cost. Thus, estimating and then determining the best levels of the independent factors in machining becomes critical and important.

Determining the input level that can give the optimum values in machining process for one output response is very useful if the need for that response is important for one application but needs a validate and reliable mathematical model. In this research a regression empirical model will be developed and then the genetic algorithm method will be used to determine the minimum tooling cost of high speed turning of AISI 304 using coated carbide insert.

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2 METHODOLOGY

The methodology was three related integrated parts: firstly, the experimental work based on the theoretical study, then developing the cost model based on the experimental work. Finally, using the genetic algorithm in order to determine the best cutting levels that will give the minimum tooling cost. Box Behnken design (BBD) has been used in this research to conduct the experimental work for three independent factors: cutting speed, feeding speed and depth of cut. Three levels: -1, 0, and 1. However, BBD is easy to conduct in addition to the ability of sequentially. Figure 1 concluded the activities and tasks need to be done in order to achieve the objective of the research in developing tooling cost and then determine the optimum cutting parameters to minimize the tooling cost in high speed turning for \$\$304 Using Coated Carbide Tool.





3 EXPERIMENT PROCEDURE

Experimental works was conducted on CNC turning machine type Power Path 15 HS – High Speed Version (spindle ASA A 2-5") and the insert chosen for this study was a coated cemented carbide type (TNGA 16 04 08 T1020) to turn work piece of AISI 304. Under dry cutting conditions with cutting speed from 500 up to 700 m/ min, feed speed of 1000 to 2000 mm/min and depth of cut 0.1 to 0.3 mm. Based on BBD with three centre points, fifteen run have been conducted. Table 1 shows the machining levels.

Table 1: Ma	achining	g levels.	

	Max	Min
Cutting speed (m/min)	500	700
Feeding speed (mm/min)	1000	2000
Depth of cut (mm)	0.1	0.3

4 DEVELOPMENT OF TOOLING COST MODEL

Tooling cost model developed based and is limited in this research to the cost of tool holder and tool insert. The model was developed based on calculating the cost of removal one cubic centimetre. Actually, tooling cost is inversely proportional with tool life and proportional with the machining time Therefore, the tooling cost is calculated based on the work of [4-7]. The machining time components used in this research was based on machining time model developed by [6]. However, the final tooling cost was calculated based on the following equation [3]: However, all the experimental results is concluded in Table 2. The results was analysed using the DoE 6.0.8. The analysis of variance (ANOVA) was conducted to develop an empirical model that can be used to estimate the tooling cost. Analysis of variance (ANOVA) is concluded in Table 3 which shows significant with value of 0.002 and lacks of fit of 0.9574. Therefore, the model can be used to navigate the design space. The following model has been used to determine the optimum cutting levels in the boundary of the design that can minimize the tooling cost.

5 GENETIC ALGORITHM

The genetic algorithm has been implemented using the developed model in the previous section in order to minimize the total tooling cost using three different independent decision variables: cutting speed, feed speed and depth of cut. Table 4 concluded the objective functions decision variables, constrains. In the implementation, the chromosome values of each individual are generated randomly from the ranges of these values. However, the simulation has been repeated for four different runs, each for 1000 iterations. The optimum results was concluded in Table 5. Finally Figure 2 shows the results for different runs that give the minimum tooling cost. The results show for different runs that after 100 iterations the values of the objective function become stable and only few points are giving results far from the final one.

$$Cost (Rm / Cm^{3}) = \frac{C_{Tc}(Rm)}{MRV (cm^{3})}$$

No. of Run	Cutting Speed [Vc] (m/min)	Feeding Speed Depth of Cut [Vf] (mm/min) [d] (mm)		Tooling Cost (RM/cm³)
1	700.00	1500.00	0.30	0.051136
2	700.00	1500.00	0.10	0.273389
3	500.00	2000.00	0.20	0.157189
4	600.00	1500.00	0.20	0.053346
5	500.00	1500.00	0.10	0.193171
6	700.00	2000.00	0.20	0.267183
7	600.00	2000.00	0.10	0.100728
9	600.00	1000.00	0.10	0.096816
10	600.00	1500.00	0.20	0.177876
11	600.00	1500.00	0.20	0.592315
12	600.00	2000.00	0.30	0.078657
13	600.00	1000.00	0.30	0.588838
14	700.00	1000.00	0.20	0.176317
15	500.00	1000.00	0.20	0.160914
17	500.00	1500.00	0.30	0.173868

 Table 2: Result of experiment.

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	Sum of		Mean	F		
Source	Squares	DF	Square	Value	Prob > F	
Model	0.30711	9	0.034123	20.18702	0.0020	significant
A	0.060565	1	0.060565	35.82974	0.0019	
В	0.038284	1	0.038284	22.64872	0.0051	
С	0.088878	1	0.088878	52.57925	0.0008	
A2	0.016824	1	0.016824	9.952853	0.0252	
B2	0.062186	1	0.062186	36.78888	0.0018	
C2	0.008493	1	0.008493	5.024655	0.0751	
AB	0.033702	1	0.033702	19.93782	0.0066	
AC	0.138012	1	0.138012	81.64661	0.0003	
BC	0.04324	1	0.04324	25.58052	0.0039	
Residual	0.008452	5	0.00169			
Lack of Fit	6.82E-06	1	6.82E-06	0.003231	0.9574	not significant
Pure Error	0.008445	4	0.002111			
Cor Total	0.315562	14				

 Table 3: ANOVA table for tooling cost.

Tooling cost = +1.47020-9.44817E-003* Cutting speed+4.16756E-003 * feed speed-9.82922* depth of cut+7.34688E-006* Cutting speed2-6.96458E-007 * feed speed2 +5.22014* depth of cut2-2.80425E-006* Cutting speed * feed speed+0.018575* Cutting speed * depth of cut-3.17638E-003* feed speed * depth of cut

Table 4: GA objectives, decision variables, constrains and parameters.

Objective function	Decision variables	constrains	
Minimize Tooling cost	Cutting speed	500≥Vc≥700	Number of Individuals in Population= 20
	Feeding speed	1000≥Vc≥2000	Number of generation = 1000
	Depth of cut	0.1≥Vc≥0.3	Crossover Rate = 35%
			Mutation Rate = 8%

 Table 5: GA optimization results.

Run	Cutting speed	Feeding speed	Depth of cut	Tooling cost
1	500	2000	0.3	0.35779
2	500	1989	0.3	0.035988
3	500	1467	0.3	0.046178
4	500	1276	0.3	0.049914



Figure 2: four different runs for 1000 iteration.

6 CONCLUSIONS

Results concluded in table 5, show that the main flexible factor is the feeding speed which varied from 1276 to 2000 mm/min. In contrast, the cutting speed and depth of cut is constant with the values of 500 m/min and 0.3 mm. The results show that to minimize tooling cost, the cutting speed should be in the lowest level while the depth of cut should be in the maximum level. In addition the lowest tooling speed will be achieved in the highest feeding speed.

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