# Geodesically compatible metrics. Existence of commutative conservation laws 

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Abstract
We give a natural geometric condition called geodesic compatibilitythat implies the existence of integrals in involution of the geodesicflow of a (pseudo)Riemannian metric. We prove that if two metricssatisfy the condition of geodesic compatibility then we can produce ahierarchy of metrics that also satisfy this condition. A tot of metricsstuded in Riemannian and Kählerian geometry satisfy such condi-tions. We apply our results for obtaining an infinite family (hierar-chy) of completely integrable flows on the complex projective plane$\mathrm{CP}^{n}$.
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## 1 Introduction

The main purpose of the present paper is to prove that if a pair of (pseudo) Riemannian metrics $g$ and $\bar{g}$ satisfies a natural geometric condition called geodesic compatibility (or $P Q^{\epsilon}$-projectivity) then the geodesic flows of the metrics $g$ and $\bar{g}$ admit integrals in involution of a special form. The integrals we find usually have singularities that can be localized out of every arbitrary taken open set $D$ with compact closure (Theorem 1). If the manifold is compact then the integrals can be taken smooth. We prove a Kählerian analog of the results proved in [11].

In what follows we call (pseudo)Riemannian metrics simply metrics. Positively definite metrics are called Riemannian metrics. All tensor object and manifolds we consider are smooth $\left(C^{\infty}\right)$. If $E \rightarrow M$ is a vector bundle over a manifold $M$ then $\Gamma(E)$ denotes the space of the smooth sections of $E \rightarrow M$.

Let us consider some examples of metrics that satisfy the condition of the geodesic compatibility.
(a) Geodesic equivalence

A classical example of geodesic compatibility is the so-called geodesic equivalence. Recall the main definitions.

Let $g$ and $\bar{g}$ be (pseudo)Riemannian metrics given on the manifold $M^{n}$, $n=\operatorname{dim} M^{n}$.

Definition 1. The metrics $g$ and $\bar{g}$ are called geodesically equivalent iff they have the same geodesics (considered as unparametrized curves on $M^{n}$ ).

We say that the metric $g$ admits non-trivial geodesic equivalence iff there exists a metric $\bar{g} \neq$ const $g$ such that $g$ and $\bar{g}$ are geodesically equivalent. The first theorems concerning the existence of integrals of the geodesic flows of the metrics admitting non-trivial geodesic equivalence were proved by $U$. Dini, P. Painlevé, T. Levi-Civita and R. Liouville (see [1]). The Liouville integrability of the corresponding geodesic flows in the case when one of the
metrics $g$ and $\bar{g}$ is Riemannian is proved in [4] (see also [ $3,5,6,8,9,6,10$ ). The (pseudo)Riemannian analogs of these theorems are proved in [11].

## (b) h-projectivity

Another example of geodesic compatibility appears about a century later in the papers of $\bar{O}$ tsuki and Tashiro $([15,16])$.

Let $M^{2 n}$ be a $2 n$-dimensional real manifold endowed with a complex structure $J, J^{2}=\mathbf{- 1}$, where 1 denotes the identity operator of the tangent bundle $T M^{2 n}$. Recall that, a metric $g$ on $M^{2 n}$ is called Kählerian iff the next two conditions are satisfied: 1) $g$ is hermitian metric, i.e., $g(J \xi, J \eta)=$ $g(\xi, \eta), \xi, \eta \in T_{x} M^{2 n}$, and 2) the Kähler form $\Omega(\xi, \eta) \stackrel{\text { def }}{=} g(J \xi, \eta)$ is a symplectic form (i.e., $\Omega$ is non-degenerate and closed, $d \Omega=0$ ).

Denote by $\nabla$ the Levi-Civita connection corresponding to the Kählerian metric $g$. Following [15] we give:

Definition 2. A smooth curve $\left(t_{1}, t_{2}\right) \ni t \rightarrow \gamma(t) \in M^{2 n}, t_{1}<t_{2}$, is called holomorphically planar (with respect to the Kählerian metric $g$ ) iff

$$
\begin{equation*}
\frac{\nabla \dot{\gamma}}{d t}(t)=a(t) \dot{\gamma}(t)+b(t) J \dot{\gamma}(t) \tag{1}
\end{equation*}
$$

where $a$ and $b$ are smooth functions of the parameter $t$.
Holomorphically planar curves always exist. For example, the geodesic lines of the metric $g$ are holomorphically planar curves. More generally, fixing any smooth functions $a, b \in C^{\infty}\left(t_{1}, t_{2}\right)$, a point $x_{0} \in M^{2 n}$ and a tangent vector $\gamma_{0} \in T_{x_{0}} M^{2 n}$, we can find a small $\epsilon_{0}>0$ and a unique solution $\gamma:\left(-\epsilon_{0}, \epsilon_{0}\right) \rightarrow M^{2 n}$ of equation (1) with initial data $\gamma(0)=x_{0}, \dot{\gamma}(0)=\gamma_{0}$.

Let $g$ and $\bar{g}$ be Kählerian metrics on $M^{2 n}$.
Definition 3 (see [16]). The Kählerian metrics $g$ and $\bar{g}$ are called holomorphically projective (or h-projective) iff every holomorphically planar with respect to the metric $g$ curve $\gamma(t)$ is holomorphically planar with respect to the metric $\bar{g}$ as well, and vice versa.

It is not hard to prove (see for example $[16,17]$ ) that the condition that the Kählerian metrics $g$ and $\bar{g}$ are $h$-projective is equivalent to a non-linear partial differential equation on the "deformation" tensor of the Levi-Civita
connections of the metrics $g$ and $\bar{g}$. In coordinates $\left\{\left(x^{1}, \ldots, x^{2 n}\right)\right\}$, the equation is

$$
\begin{equation*}
\bar{\Gamma}_{j k}^{i}-\Gamma_{j k}^{i}=\delta_{j}^{i} \phi_{k}+\delta_{k}^{i} \phi_{j}-\phi_{\alpha} J_{j}^{\alpha} J_{k}^{i}-\phi_{\alpha} J_{k}^{\alpha} J_{j}^{i}, \tag{2}
\end{equation*}
$$

where $\phi_{l}(\mathrm{l}=1, \ldots, 2 \mathrm{n})$ are the components of a globally defined on $M^{2 n} 1$ form, $\Gamma_{j k}^{i}$ and $\bar{\Gamma}_{j k}^{i}$ are the Christoffel symbols of the metrics $g$ and $\bar{g}$ respectively, $\delta_{j}^{i}$ is the Kronecker delta and $J_{j}^{i}$ are the components of the complex structure $J$. As usual, we use the standard tensor conventions and omit the summation symbols in the formulas. It can be easily seen that $\phi_{k}=\partial_{k} \phi$, where $\partial_{k}$ stands for the partial derivative $\frac{\partial}{\partial x^{k}}$ and $\phi$ is a globally defined on $M^{2 n}$ function (see Sect.2.1). Remark that equation (2) cannot be obtained without using the condition that the metrics $g$ and $\bar{g}$ are Kählerian.

## (c) $P Q^{\epsilon}$-projectivity

Here we give the definition of the geodesic compatibility that generalize the both previous notions.

Consider two metrics $g$ and $\bar{g}$ given on the manifold $M^{m}, m=\operatorname{dim} M^{m}$. Let $P, Q \in \Gamma\left(\operatorname{End}\left(T M^{m}\right)\right)$ satisfy the next properties:
(i) $P$ and $Q$ are antisymmetric with respect to the both metrics $g$ and $\bar{g}$;
(ii) $P Q=\epsilon \mathbf{1}$, where $\epsilon$ is a fixed real constant such that $\epsilon \neq m+1$ and $\epsilon \neq 1$.

Denote by $\chi$ the number $\chi \stackrel{\text { def }}{=} m+1-\epsilon$. It follows from (ii) that $\chi \neq 0$.
Definition 4. The metrics $g$ and $\bar{g}$ are called $P Q^{\epsilon}$-projective (or geodesically compatible) iff their Christoffel symbols satisfy the equation

$$
\begin{equation*}
\bar{\Gamma}_{j k}^{i}-\Gamma_{j k}^{i}=\phi_{(j} \delta_{k)}^{i}-\phi_{\alpha} P_{(j}^{\alpha} Q_{k)}^{i}, \tag{3}
\end{equation*}
$$

where $\phi_{k}$ are the components of a globally defined on $M^{m} 1-$ form and the operators $P$ and $Q$ satisfy relations (i) and (ii).

As usual, equation (3) is written in a fixed coordinate chart $\left\{\left(x^{1}, \ldots, x^{m}\right)\right\}$ and $P_{j}^{i}$ and $Q_{j}^{i}$ are the components of the operators $P$ and $Q$. The brackets ( $i \ldots j$ ) in formula (3) denote symmetrization with respect to the pointed indices. For example, the tensor field $T_{\alpha(i j) \beta}$ stands for $T_{\alpha i j \beta}+T_{\alpha j i \beta}$. It is not hard to give an invariant definition of $P Q^{¢}$-projectivity.

Remark 1. If $\epsilon \neq 0$ then the operators $P$ and $Q$ are non-degenerate on $M^{m}, Q=\epsilon P^{-1}$ and the dimension $m$ of the manifold is even.

Remark 2. Suppose that $g$ and $\bar{g}$ are Kählerian metrics given on the complex manifold $M^{2 n}$ with complex structure $J$. Taking $P=Q=J$ and $\epsilon=-1$ we see that $h$-projectivity is a particular case of $P Q^{\epsilon}$-projectivity. Taking $P=Q=0$ and $\epsilon=0$ we obtain the notion of the geodesic equivalence.

Let us give a brief description of the results proved in the paper. Suppose that the metrics $g$ and $\bar{g}$ given on the manifold $M^{m}$ are $P Q^{\epsilon}$-projective. Define the endomorphism $A \in \Gamma\left(\operatorname{End}\left(T M^{m}\right)\right)$ of the tangent bundle $T M^{m}$ by the formula

$$
\begin{equation*}
A_{j}^{i}(g, \bar{g}) \stackrel{\operatorname{def}}{=}\left|\frac{\operatorname{det} \bar{g}}{\operatorname{det} g}\right|^{\frac{1}{x}} \bar{g}^{i \alpha} g_{\alpha j} . \tag{4}
\end{equation*}
$$

Consider the locally defined one-parameter family of quadratic forms

$$
\begin{equation*}
K_{c}(g, \bar{g})(\xi) \stackrel{\operatorname{def}}{=}|\operatorname{det}(A+c \mathbf{1})|^{1 /(1-\epsilon)} g\left((A+c \mathbf{1})^{-1} \xi, \xi\right) \tag{5}
\end{equation*}
$$

where $\xi \in T M^{m}$ and $c$ is an appropriately chosen real parameter.
Following [11] define the rank of the pair $g$ and $\bar{g}$. Denote by $r(g, \bar{g})(x)$ the degree of the minimal polynomial of the operator $\left.A(g, \bar{g})\right|_{x}$.

Definition 5. The number $r(g, \bar{g})(x)$ is called rank of the pair $g$ and $\bar{g}$ of $P Q^{c}$-projective metrics at the point $x \in M^{m}$. The number $r(g, \bar{g}) \stackrel{\text { def }}{=}$ $\max _{x \in \mathbb{M}^{m}} r(g, \bar{g})(x)$ is called rank of the pair of $P Q^{\epsilon}$-projective metrics.

Recall that the smooth functions $F_{1}, \ldots, F_{k}$ given on a smooth manifold $V$ are called functionally independent in $V$ iff the set of the points $x \in V$ where the differentials $d_{x} F_{1}, \ldots, d_{x} F_{k}$ are linearly independent is dense in $V$.

Theorem 1. Suppose that the manifold $M^{m}$ is connected and let the rank of the pair of $P Q^{\epsilon}$-projective metrics $g$ and $\bar{g}$ be $r$. Denote by $\omega_{g}$ the symplectic structure on $T M^{m}$ given by the pull-back $\mathrm{FL}_{g}^{*} \omega$ where $\omega$ is the canonical symplectic structure on $T^{*} M^{m}$ (the form " $d p \wedge d q$ ") and $F L_{g}: T M^{m} \rightarrow$ $T^{*} M^{m}$ denotes the Legendre transformation corresponding to the metric $g$. Then for every open set $D \subset M^{m}$ with compact closure in $M^{m}$ there exist $r$ quadratic in velocities functions $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi), \xi \in T D$, such that:
(a) $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi)$ are smooth functionally independent pairwise commuting integrals of the geodesic flow of the metric $g$ on $D$;
(b) if the integral $K_{c}(g, \bar{g})(\xi), c=$ const, is correctly defined on some open set $U \subset D$ then there exist constants $\alpha_{1}, \ldots, \alpha_{r}$ such that $K_{c}(\xi)=$ $\sum_{k=1}^{r} \alpha_{k} B_{k}^{D}(\xi)$ on $D$.
The integrals $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi)$ can be taken in the form $B_{k}^{D}(\xi) \stackrel{\text { def }}{=} K_{c_{k}}(\xi)$, where the constants $c_{1}, \ldots, c_{r}$ are appropriately chosen.

Remark 3. Actually, the constants $c_{1}, \ldots, c_{r}$ in Theorem 1 are taken"sufficiently big", i.e. $\left|c_{k}\right|>m_{D}, m_{D} \stackrel{\text { def }}{=} \sup _{x \in D} \max _{\lambda \in \operatorname{Sect}(A \mid x)}|\lambda|$.

As a simple corollary of this theorem we obtain the next statement.
Corollary 1. The set of the points $x \in M^{m}$ where $r(g, \bar{g})(x)=r$ is open and dense in $M^{m}$.

We prove Theorem 1 in Sect. 4 .
A hermitian version of Theorem 1 is given in Sect. 5 (see Theorem 4). An important corollary is the next Kählerian analog of the proved in [11] Theorem 2. Suppose that the Kählerian metrics $s$ and $\tilde{s}$ are $h$-projective. Denote by $r$ the hermitian rank of the pair $s$ and $\tilde{s}$ (see Definition 9).

Theorem 2. If two Kählerian metrics $s$ and $\tilde{s}$ are $h$-projective then their geodesic flows admit $r$ functionally independent integrals in involution.

The paper is organized as follows.
In Sect. 2 we prove that the quadratic forms given by formula (5) are integrals of the geodesic flow of the metric $g$ (Proposition 3, Sect.2.3). In Sect.2.4 we prove Proposition 4. As in [11] the existence of hierarchies is a crucial point proving the commutativity of the integrals given by formula (5). We prove the commutativity of these integrals in Sect.3, Theorem 3. Sect. 4 is devoted to the proof of Theorem 1. The hermitian analog of this theorem is proved in Sect.5. The last section is devoted to the applications of the results. A simple geometrical construction allows us to find an infinite family ("CP ${ }^{n}$-hierarchy") of completely integrable Hamiltonian systems on the complex projective plane $\mathbf{C P}^{n}$ (see Theorem 6). Our integrals don't coincide with the integrals obtained by Thimm in [12].

In what follows, if a coordinate chart is fixed, we usually identify the tensor fields we consider with their coordinate ("index") representations and denote the corresponding objects by the same letters. We use also the common tensor notations and conventions and omit the summation symbols in the formulas. An endomorphism $L \in \Gamma\left(\operatorname{End}\left(T M^{n}\right)\right)$ is called invertible or non-degenerate on $M^{n}$ iff $\operatorname{det} L \neq 0$ on $M^{n}$.

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## 2 Properties of $P Q$-projectivity

The present section establishes the main properties of the $P Q^{\epsilon}$-projective metrics.

### 2.1 Existence of an integral

Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. Here we prove that the geodesic flow of the metric $g$ admits an integral (Proposition 1).

Contracting the indices $i$ and $j$ in formula (3) and using that trace $Q=0$ we get $\bar{\Gamma}_{i k}^{i}-\Gamma_{i k}^{i}=\chi \phi_{k}$ where $\chi \stackrel{\text { def }}{=} m+1-\epsilon$. Using that $\Gamma_{i k}^{i}=\partial_{k} \ln \sqrt{|\operatorname{det} g|}$ we obtain

$$
\begin{equation*}
2 \chi \phi_{k}=\frac{\partial}{\partial x^{k}}\left(\ln \left|\frac{\operatorname{det} \bar{g}}{\operatorname{det} g}\right|\right) . \tag{6}
\end{equation*}
$$

Therefore, $\phi_{k}=\partial_{k} \phi$, where $\phi$ is a smooth function on $M^{m}$.
The next technical lemma is needed for the sequel.
Lemma 1. The metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective if and only if their components satisfy the next equation in covariant derivatives

$$
\begin{equation*}
\nabla_{k} \bar{g}_{i j}=2 \phi_{k} \bar{g}_{i j}+\phi_{(i} \bar{g}_{j) k}-\phi_{\alpha} P_{(i}^{\alpha} \bar{g}_{j) \beta} Q_{k}^{\beta} \tag{7}
\end{equation*}
$$

where $\nabla$ denotes the Levi-Civita connection of the metric $g$ and the operators $P$ and $Q$ satisfy conditions (i) and (ii).

Proof of Lemma 1. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. In coordinates, we obtain

$$
\begin{aligned}
\nabla_{k} \bar{g}_{i j} & =\partial_{k} \bar{g}_{i j}-\Gamma_{i k}^{\alpha} \bar{g}_{\alpha j}-\Gamma_{j k}^{\alpha} \bar{g}_{i \alpha} \\
& =\bar{\nabla}_{k} \bar{g}_{i j}+\left(\phi_{(i} \delta_{k)}^{\alpha}-\phi_{l} P_{(i}^{l} Q_{k)}^{\alpha}\right) \bar{g}_{\alpha j}+\left(\phi_{(j} \delta_{k)}^{\alpha}-\phi_{l} P_{(j}^{l} Q_{k)}^{\alpha}\right) \bar{g}_{i \alpha} \\
& =2 \phi_{k} \bar{g}_{i j}+\phi_{(i} \bar{g}_{j) k}-\phi_{l} P_{(i}^{l} \bar{g}_{j) \alpha} Q_{k}^{\alpha}-\phi_{l} P_{k}^{l} Q_{(i}^{\alpha} \bar{g}_{j) \alpha} \\
& =2 \phi_{k} \bar{g}_{i j}+\phi_{(i} \bar{g}_{j) k}-\phi_{l} P_{(i}^{l} \bar{g}_{j) \alpha} Q_{k}^{\alpha} .
\end{aligned}
$$

The inverse statement immediately follows from the classical fact that the Levi-Civita connection of some metric is the unique torsion free connection that preserves the considered metric. Lemma 1 is proved.

Equations (7) are equivalent to

$$
\begin{equation*}
2 \mu \bar{g}_{i j, k}=-2 \mu_{k} \bar{g}_{i j}-\mu_{(i,} \bar{g}_{j) k}-\mu_{l} P_{(i}^{l} \bar{\Omega}_{j) k}^{Q}, \tag{8}
\end{equation*}
$$

where $\mu \stackrel{\text { def }}{=}\left|\frac{\operatorname{det} g}{\operatorname{det} \overline{\bar{g}}}\right|^{\frac{1}{x}}, \mu_{k} \stackrel{\text { def }}{=} \frac{\partial \mu}{\partial x^{k}}(k=1, \ldots, 2 n)$, and $\bar{\Omega}_{k j}^{Q}$ are the components of the 2 -form $\bar{\Omega}^{Q}(\xi, \eta) \stackrel{\text { def }}{=} \bar{g}(Q \xi, \eta), \xi, \eta \in T_{x} M^{m}$. The equivalence of equations (7) and (8) easily follows from the relation $2 \phi_{k}=-\frac{\mu_{k}}{\mu}$.

Proposition 1. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. Then the quadratic form

$$
\begin{equation*}
K(\xi) \stackrel{\operatorname{def}}{=}\left|\frac{\operatorname{det} g}{\operatorname{det} \bar{g}}\right|^{\frac{2}{x}} \bar{g}(\xi, \xi) \tag{9}
\end{equation*}
$$

is an integral of the geodesic flow of the metric $g$.
Proof of Proposition 1. In coordinates, we have $K_{i j} \stackrel{\text { def }}{=} \mu^{2} \bar{g}_{i j}$. Following Levi-Civita, a quadratic form $Q(\xi, \xi)=Q_{i j} \xi^{i} \xi^{j}, Q_{i j}=Q_{j i}$, is an integral of the geodesic flow of the metric $g$ if and only if $Q_{(i j k)} \stackrel{\text { def }}{=}\left(Q_{i j, k}+Q_{j k, i}+\right.$ $\left.Q_{k i, j}\right) / 3=0$, where $Q_{i j, k} \stackrel{\text { def }}{=} \nabla_{k} Q_{i j}$ and $\nabla$ is the Levi-Civita connection of the metric $g$. Indeed, let $\gamma(s)\left(\gamma(0)=x_{0}, \dot{\gamma}(0)=\xi\right)$ be a geodesic line of the metric $g$. We have $0=\left.\frac{d}{d s}\right|_{s=0}\left(Q_{i j} \dot{\gamma}^{i} \dot{\gamma}^{j}\right)=Q_{i j, k}\left(x_{0}\right) \xi^{k} \xi^{i} \xi^{j}=Q_{(i j k)}\left(x_{0}\right) \xi^{k} \xi^{i} \xi^{j}$ and therefore $Q_{i j, k}+Q_{j k, i}+Q_{k i, j}=0$. Conversely, if $Q_{i j, k}+Q_{j k, i}+Q_{k i, j}=0$ then $Q$ is an integral of the geodesic flow of the metric $g$.

We have

$$
\begin{aligned}
& 2 K_{i j, k}=4 \mu \mu_{k} \bar{g}_{i j}+2 \mu^{2} \bar{g}_{i j, k}, \\
& 2 K_{j k, i}=4 \mu \mu_{i} \bar{g}_{j k}+2 \mu^{2} \bar{g}_{j k, i} \\
& 2 K_{k i, j}=4 \mu \mu_{j} \bar{g}_{k i}+2 \mu^{2} \bar{g}_{k i, j} .
\end{aligned}
$$

Summing these equations and using (8) we obtain that

$$
\begin{aligned}
2\left(K_{i j, k}+K_{j k, i}+K_{k i, j}\right) & =-\mu\left(\mu_{\alpha} P_{i}^{\alpha} \bar{\Omega}_{j k}^{Q}+\mu_{\alpha} P_{j}^{\alpha} \bar{\Omega}_{i k}^{Q}+\right. \\
& +\mu_{\alpha} P_{j}^{\alpha} \bar{\Omega}_{k i}^{Q}+\mu_{\alpha} P_{k}^{\alpha} \bar{\Omega}_{j i}^{Q}+ \\
& \left.+\mu_{\alpha} P_{k}^{\alpha} \bar{\Omega}_{i j}^{Q}+\mu_{\alpha} P_{i}^{\alpha} \bar{\Omega}_{k j}^{Q}\right)=0
\end{aligned}
$$

This completes the proof of Proposition 1.
Remark 4. In the case of geodesically equivalent metrics the integral given by formula (9) coincides with the classical Painlevé integral (see [1, 11]). The existence of the integral (9) in the case of h-projective Kählerian metrics is a new fact.

### 2.2 Existence of a family of $P Q$-projective metrics

Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. Consider the endomorphism $A$ of the tangent bundle $T M^{m}$ defined by formula (4). It is clear that $A$ is self-adjoint with respect to the both metrics $g$ and $\bar{g}$. Condition (i) imposed on the operators $P$ and $Q$ (see Sect. 1) yields that $A$ commutes with $P$ and $Q$. The next important technical lemma is needed for the sequel.

Lemma 2. If the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective then the metric $a_{i j} \stackrel{\text { def }}{=}$ $g_{i a} A_{j}^{\alpha}$ satisfies the equation

$$
\begin{equation*}
a_{i j, k}=\lambda_{(i} g_{j) k}-\lambda_{l} P_{(i}^{l} g_{j) q} Q_{k}^{q} \tag{10}
\end{equation*}
$$

where $\lambda_{i} \stackrel{\text { def }}{=}-\phi_{l} A_{i}^{l}$. The operators $P$ and $Q$ are antisymmetric with respect to the metric $a$. Inversely, consider a metric $g$ and two antisymmetric with respect to $g$ operators $P$ and $Q$ such that $P Q=\epsilon 1$. Suppose that $P$ and $Q$ are antisymmetric with respect to a non-degenerate symmetric form $a_{i j}$ and let $a_{i j}$ satisfies equation (10) for some globally defined on $M^{2 n} 1$-form $\lambda_{k}$. Then the metrics $g$ and $\bar{g} \stackrel{\operatorname{def}}{=}\left|\frac{\operatorname{det} \dot{g} g}{\operatorname{det} g}\right|^{\frac{1}{1-\epsilon}} \check{g}$, are $P Q^{\epsilon}$-projective, where $\dot{g}_{i j} \stackrel{\text { def }}{=} g_{i a} a^{\alpha \beta} g_{\beta j}, a_{i \alpha} a^{\alpha j}=\delta_{i}^{j}$.

Proof of Lemma 2. Suppose that $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. Denote $\check{g}_{i j} \stackrel{\text { def }}{=} \exp (-2 \phi) \bar{g}_{i j}$. Using formula (7) we obtain

$$
\begin{aligned}
\check{g}_{i j, k} & =-2 \phi_{k} \check{g}_{i j}+\exp (-2 \phi) \bar{g}_{i j, k} \\
& =\phi_{(i} \check{g}_{j) k}-\phi_{l} P_{(i}^{l} \check{g}_{j) \alpha} Q_{k}^{\alpha}
\end{aligned}
$$

For the inverse tensor $\check{g}^{i j}\left(\check{g}_{i \alpha} \breve{g}^{\alpha j}=\delta_{i}^{j}\right)$ we have

$$
\begin{aligned}
\check{g}_{, k}^{i j} & =-\check{g}^{i \alpha} \check{g}_{\alpha \beta, k} \check{g}^{\beta j} \\
& =-\phi_{l} \check{g}^{l(i} \delta_{k}^{j)}+\phi_{l} P_{s}^{l} \check{g}^{s(i} Q_{k}^{j)}
\end{aligned}
$$

Finally, taking $a_{\alpha \beta} \stackrel{\text { def }}{=} g_{\alpha i} \breve{g}^{i j} g_{j \beta}$ obtain

$$
\begin{aligned}
a_{\alpha \beta, k} & =-\phi_{l} g^{l i} g_{i(\alpha} g_{\beta) k}+\phi_{l} P_{r}^{l} A_{(\alpha}^{r} g_{\beta) j} Q_{k}^{j} \\
& =\lambda_{(\alpha} g_{\beta) k}-\lambda_{l} P_{(\alpha}^{l} g_{\beta) q} Q_{k}^{q},
\end{aligned}
$$

where $\lambda_{\alpha} \stackrel{\text { def }}{=}-\phi_{l} A_{\alpha}^{l}$.
Let us prove the inverse part of the proposition. Suppose that the nondegenerate symmetric tensor $a_{i j}$ satisfies equation (10) where $P$ and $Q$ are antisymmetric with respect to $g$ and $a, P Q=\epsilon 1$, and $\lambda_{k}$ are the components of a globally defined on $M^{m} 1$-form. Consider the tensor $\check{g}^{i j} \stackrel{\text { def }}{=} g^{i \alpha} a_{\alpha \beta} g^{\beta j}$. For the inverse tensor $\breve{g}_{p q}\left(\check{g}_{p \alpha} \breve{g}^{\alpha q}=\delta_{p}^{q}\right)$ we have

$$
\begin{aligned}
\check{g}_{p q, k} & =-\check{g}_{p i} \check{g}_{k}^{i j} \check{g}_{j q} \\
& =-\lambda_{\alpha} g^{\alpha i} \check{g}_{i(p}\left(\check{g}_{q) k}+\lambda_{l} P_{\alpha}^{l} g^{\alpha i} \check{g}_{i(p}\left(\check{g}_{q) j} Q_{k}^{j}\right.\right.
\end{aligned}
$$

Denoting $\phi_{p} \stackrel{\text { dof }}{=}-\lambda_{\alpha} g^{\alpha i} \check{g}_{i p}$ we obtain

$$
\begin{equation*}
\check{g}_{p q, k}=\phi_{(p} \check{g}_{q) k}-\phi_{l} P_{(p}^{l} \check{p}_{q) j} Q_{k}^{j} . \tag{11}
\end{equation*}
$$

Lemma 3. $2 \phi_{k}=\partial_{k} \ln \left|\frac{\operatorname{det} \tilde{g}}{\operatorname{det} g}\right|^{\frac{1}{1-\epsilon}}$.
Proof of Lemma 3. Denote by $\check{\Gamma}_{j k}^{i}$ the Christoffel symbols of the metric $\check{g}$. Using formula (11) we obtain

$$
\check{\Gamma}_{\alpha k}^{\alpha}=\frac{1}{2} \check{g}^{\alpha \beta} \frac{\partial \check{g}_{\alpha \beta}}{\partial x^{k}}
$$

$$
\begin{aligned}
& =\frac{1}{2} \check{g}^{\alpha \beta}\left(\check{g}_{\alpha \beta, k}+\check{g}_{l(\alpha} \Gamma_{\beta) k}^{l}\right) \\
& =\frac{1}{2} \check{g}^{\alpha \beta}\left(\left(\phi_{(\alpha} \check{g}_{\beta) k}-\phi_{l} P_{(\alpha}^{l} \check{g}_{\beta) j} Q_{k}^{j}\right)+\check{g}_{l(\alpha} \Gamma_{\beta) k}^{l}\right) \\
& =(1-\epsilon) \phi_{k}+\Gamma_{\alpha k}^{\alpha} .
\end{aligned}
$$

Therefore, $(1-\epsilon) \phi_{k}=\breve{\Gamma}_{\alpha k}^{\alpha}-\Gamma_{\alpha k}^{\alpha}=\partial_{k} \ln \left|\frac{\operatorname{det} \tilde{g} g}{\operatorname{det} g}\right|^{\frac{1}{2}}$. Lemma 3 is proved.
Finally, taking $\bar{g}_{i j} \stackrel{\text { def }}{=} \exp (2 \phi) \check{g}_{i j}$ we obtain that $g_{i j, k}=2 \phi_{k} \bar{g}_{i j}+\phi_{(i} \bar{g}_{j) k}-$ $\phi_{l} P_{(i}^{l} \bar{g}_{j)} Q_{k}^{\alpha}$. Using Lemma 1 we complete the proof of Lemma 2.

Proposition 2. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective and let c be a real constant such that the operator $A+c \mathbf{1}$ is invertible. Then the metrics $g$ and

$$
\begin{equation*}
\bar{g}_{c}(g, \bar{g}) \stackrel{\text { def }}{=}|\operatorname{det}(A+c \mathbf{1})|^{-1 /(1-\epsilon)} g(A+c \mathbf{1})^{-1} \tag{12}
\end{equation*}
$$

where $A=A(g, \bar{g})$ is given by formula (4), are $P Q^{\epsilon}$-projective.
Proof of Proposition 2. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective and let $c$ be the constant given in the statement of the corollary. It follows from Lemma 2 that the metric $a \stackrel{\text { def }}{=} g A$ satisfies equation (10). Hence, the metric $a+c g=g(A+c)$ also satisfies equation (10). Using the inverse part of Lemma 2 we obtain that the metrics $g$ and $\bar{g}_{c} \stackrel{\operatorname{def}}{=}\left|\frac{\operatorname{det} \check{g}_{g}}{\operatorname{det} g}\right|^{\frac{1}{1-\epsilon}} \check{g}_{c}, \check{g}_{c} \xlongequal{\text { def }}$ $g(a+c g)^{-1} g=g(A+c \mathbf{1})^{-1}$. This completes the proof of Proposition 2.

### 2.3 Existence of a family of integrals

Here we prove that the geodesic flows of a pair of $P Q^{\epsilon}$-projective metric locally admit a family of integrals.

Proposition 3. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective and let $c$ be a real constant such that the operator $A+c \mathbf{1}$ is non-degenerate on $M^{m}$. Then the quadratic form

$$
\begin{equation*}
K_{c}(g, \bar{g}) \stackrel{\text { def }}{=}|\operatorname{det}(A+c \mathbf{1})|^{1 /(1-\epsilon)} g(A+c \mathbf{1})^{-1} \tag{13}
\end{equation*}
$$

is an integral of the geodesic flow of the metric $g$.

Remark 5. Let $D \subset M^{m}$ be an open set with compact closure in $M^{m}$. Taking $|c| \geq m_{D}, m_{D} \stackrel{\text { def }}{=} \sup _{x \in D} \max _{\lambda \in \text { Spect }\left.A\right|_{z}}|\lambda|$, we obtain a one-parameter family of integrals of the geodesic flow of the metric $g$.

Proof of Proposition 3. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. It follows from Proposition 2 that $g$ and $\bar{g}_{c}$ (given by formula (12)) are $P Q^{\epsilon}$-projective. Applying Proposition 1 to these metrics we obtain that the quadratic form

$$
\begin{aligned}
K_{c} & \stackrel{\text { def }}{=}\left|\frac{\operatorname{det} g}{\operatorname{det} \bar{g}_{c}}\right|^{\frac{2}{x}} \bar{g}_{c} \\
& =|\operatorname{det}(A+c \mathbf{1})|^{1 /(1-\epsilon)} g(A+c \mathbf{1})^{-1}
\end{aligned}
$$

is an integral of the geodesic flow of the metric $g$. Proposition 3 is proved.

### 2.4 Existence of hierarchies

In the present section we prove the next proposition.
Proposition 4. If the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective then the metrics $a \stackrel{\text { def }}{=} g A$ and $\bar{a} \stackrel{\text { def }}{=} \bar{g} A$ are $P_{1} Q_{1}^{\epsilon}$-projective, where $P_{1} \stackrel{\text { def }}{=} P A, Q_{1} \stackrel{\text { def }}{=} A^{-1} Q$, and $A=A(g, \bar{g})$ is given by formula (4).
Proof of Proposition 4. It follows from Lemma 2 that $a_{\alpha \beta, k}=\lambda_{(\alpha} g_{\beta) m}-$ $\lambda_{l} P_{(\alpha}^{l} g_{\beta) q} Q_{k}^{q}$, where $\lambda_{\alpha} \stackrel{\text { def }}{=}-\phi_{l} A_{\alpha}^{l}$. We have

$$
\begin{aligned}
-\frac{\partial a_{\alpha \beta}}{\partial x^{k}}+\Gamma_{k(\alpha}^{l} a_{\beta) l} & =-\lambda_{(\alpha} g_{\beta) k}+\lambda_{l} P_{(\alpha}^{l} g_{\beta) q} Q_{k}^{q} \\
\frac{\partial a_{\alpha k}}{\partial x^{\beta}}-\Gamma_{\beta(\alpha}^{l} a_{k) l} & =\lambda_{(\alpha} g_{k) \beta}-\lambda_{l} P_{(\alpha}^{l} g_{k) q} Q_{\beta}^{q} \\
\frac{\partial a_{\beta k}}{\partial x^{\alpha}}-\Gamma_{\alpha(\beta}^{l} a_{k) l} & =\lambda_{(\beta} g_{k) \alpha}-\lambda_{l} P_{(\beta}^{l} g_{k) q} Q_{\alpha}^{q}
\end{aligned}
$$

Summing these equations, and using the relations $\lambda_{l} \stackrel{\text { def }}{=}-\phi_{\alpha} A_{l}^{\alpha}, P A=$ $A P, g(Q \xi, \eta)=-g(\xi, Q \eta)$, we obtain the next formula for the Christoffel symbols $A_{j k}^{i}$ of the metric $a_{i j}$

$$
\begin{align*}
A_{\alpha \beta}^{k} & =\Gamma_{\alpha \beta}^{k}+\lambda_{l} a^{l k} g_{\alpha \beta}+\lambda_{l} P_{(\alpha}^{l} g_{\beta) q} Q_{r}^{q} a^{r k} \\
& =\Gamma_{\alpha \beta}^{k}-\phi_{l} g^{l k} g_{\alpha \beta}+\phi_{s} P_{l}^{s} A_{(\alpha}^{l} Q_{\beta)}^{q} \bar{A}_{q}^{k}, \tag{14}
\end{align*}
$$

where $\tilde{A}_{q}^{k}$ are the components of the inverse operator $A^{-1}$.
By definition, $\bar{a}_{i j} \stackrel{\text { def }}{=} \bar{g}_{i k} A_{j}^{k}=\exp (2 \phi) g_{i j}$. Using this relation we immediately obtain the next relation between the Christoffel symbols of the metrics $\bar{a}$ and $g$

$$
\begin{equation*}
\bar{A}_{i j}^{k}=\Gamma_{i j}^{k}+\phi_{(i} \delta_{j)}^{k}-\phi_{l} g^{l k} g_{i j} . \tag{15}
\end{equation*}
$$

Finally, (14) and (15) yield

$$
\begin{equation*}
\bar{A}_{i j}^{k}-A_{i j}^{k}=\phi_{(i} \delta_{j)}^{k}-\phi_{s} P_{l}^{s} A_{(i}^{l} Q_{j)}^{q} \tilde{A}_{q}^{k} . \tag{16}
\end{equation*}
$$

This completes the proof of Proposition 4.
Suppose that a pair of $P Q^{\epsilon}$-projective metrics $g$ and $\bar{g}$ is given. It follows from Proposition 4 that for every integer $k$ the metrics $g \stackrel{(k)}{=} g A^{k}$ and $\bar{g}(k) \stackrel{\text { def }}{=} g A^{k}$ are $P_{k} Q_{k}$-projective, where $P_{k} \stackrel{\text { def }}{=} P A^{k}$ and $Q_{k} \stackrel{\text { def }}{=} A^{-k} Q$. Indeed, suppose that $g^{(l)}$ and $\bar{g}^{(l)}$ are $P_{l} Q_{l}$-projective. It follows from formula (4) that $A\left(g^{(l)}, \bar{g}^{(l)}\right)=A$ and $A\left(\bar{g}^{(l)}, g^{(l)}\right)=A^{-1}$. Applying Proposition 4 to the pair $g^{(l)}$ and $\bar{g}^{(l)}$ we obtain that $g^{(l+1)}$ and $\bar{g}^{(l+1)}$ are $P_{l+1} Q_{l+1}$-projective. Similarly, applying Proposition 4 to the pair $\bar{g}^{(l)}$ and $g^{(l)}$ we obtain that $g^{(l-1)}$ and $\bar{g}^{(l-1)}$ are $P_{l-1} Q_{l-1}$-projective.

Definition 6. The sequence of pairs $g^{(k)}$ and $\bar{g}^{(k)}(k=0, \pm 1, \ldots)$ are called $P Q^{\epsilon}$-hierarchy corresponding to the pair $g$ and $\bar{g}$ of $P Q^{\epsilon}$-projective metrics.

The $P Q^{6}$-hierarchy is an analog of the geodesic hierarchy considered in [11]. Proposition 4 is an analog of the Sinyukov transformation in the theory of geodesically equivalent metrics (see $[19,20]$ ). We will describe the $P Q^{\epsilon}$ hierarchy by the next formal scheme

where the horizontal arrows mean that the metrics $g^{(k)}$ and $\bar{g}^{(k)}$ are $P_{k} Q_{k^{-}}$ projective.

## 3 Involutivity of the family of the integrals

In the present section we prove that the integrals given by Proposition 3 are in involution.

Theorem 3. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. Suppose in addition that the operators $A+c_{1} 1$ and $A+c_{2} 1$ are non-degenerate on $M^{m}$ where $c_{1}$ and $c_{2}$ are some fixed real numbers. Then the quadratic forms $K_{c_{1}}(g, \bar{g})$ and $K_{c_{2}}(g, \bar{g})$, given by formula (5), are in involution with respect to the symplectic structure $\omega_{g} \stackrel{\text { def }}{=} \mathrm{FL}_{g}^{*} \omega$, where $\omega$ denotes the canonical symplectic structure on the cotangent bundle $T^{*} M^{m}$ and $F L_{g}: T M^{m} \rightarrow$ $T^{*} M^{m}$ is the Legendre transformation corresponding to the metric $g$.
Proof of Theorem 3. Suppose that the metrics $g$ and $\bar{g}$ are $P Q^{\epsilon}$-projective. Proposition 2 shows that the metrics $g$ and $\bar{g}_{c_{1}} \stackrel{\text { def }}{=}\left|\operatorname{det}\left(A+c_{1} \mathbf{1}\right)\right|^{-1 /(1-\epsilon)} g(A+$ $\left.c_{1} 1\right)^{-1}$ are $P Q^{\epsilon}$-projective as well. Consider the corresponding $P Q^{\epsilon}$-hierarchy


A simple calculation shows that $A\left(g, \bar{g}_{c_{1}}\right)=A+c_{1} 1$, and $A\left(\bar{g}_{c_{1}}, g\right)=(A+$ $\left.c_{1} \mathbf{1}\right)^{-1}$. Hence, $\bar{g}_{c_{1}}^{(2)} \stackrel{\text { def }}{=} \bar{g}_{c_{1}} A\left(g, \bar{g}_{c_{1}}\right)^{2}=\left|\operatorname{det}\left(A+c_{1} \mathbf{1}\right)\right|^{-1 /(1-\epsilon)} g\left(A+c_{1} \mathbf{1}\right)$. It is clear that $A\left(\bar{g}_{c_{1}}^{(2)}, g_{c_{1}}^{(2)}\right)=\left(A+c_{1} \mathbf{1}\right)^{-1}$. Suppose that the non-zero real number $(-\alpha)$ is not an eigenvalue of the operator $\left(A+c_{1} 1\right)^{-1}$. It follows from Proposition 3 that the quadratic form $K_{\alpha}\left(\bar{g}_{c_{1}}^{(2)}, g_{c_{1}}^{(2)}\right)$ is an integral of the geodesic flow of the metric $\bar{g}_{c_{1}}^{(2)}$. Applying the inverse to the Legendre transformation corresponding to the metric $\bar{g}_{c_{1}}^{(2)}$, we obtain that the forms

$$
\begin{equation*}
\left(\bar{g}_{c_{1}}^{(2)}\right)^{-1}=\left|\operatorname{det}\left(A+c_{1} 1\right)\right|^{1 /(1-\epsilon)}\left(A+c_{1} 1\right)^{-1} g^{-1} \tag{17}
\end{equation*}
$$

and

$$
\begin{aligned}
\left(\mathrm{FL}_{\bar{g}_{c_{1}}^{(2)}}^{-1}\right)^{*}\left(K_{\alpha}\right) & \stackrel{\operatorname{def}}{=}\left|\operatorname{det}\left(\left(A+c_{1}\right)^{-1}+\alpha\right)\right|^{1 /(1-\epsilon)}\left(\left(A+c_{1}\right)^{-1}+\alpha\right)^{-1}\left(\bar{g}_{c_{1}}^{(2)}\right)^{-1} \\
& =c(\alpha)\left|\operatorname{det}\left(A+\left(c_{1}+1 / \alpha\right)\right)\right|^{1 /(1-\epsilon)}\left(A+\left(c_{1}+1 / \alpha\right)\right)^{-1} g^{-1}
\end{aligned}
$$

considered as functions on the cotangent bundle $T^{*} M^{m}$, are in involution with respect to the canonical symplectic structure $\omega$ on $T^{*} M^{m}$. Finally, applying the Legendre transformation corresponding to the metric $g$, we obtain that the forms $K_{c_{1}}(g, \bar{g})$ and $K_{c_{1}+\frac{1}{\alpha}}(g, \bar{g})$ are in involution with respect to $\omega_{g}$. Theorem 3 is proved.

## 4 Functional independence of the integrals

Here we prove Theorem 1 formulated in the Introduction.
Proof of Theorem 1. We follow the idea of the proof of Theorem 2 in [11].

In what follows we use the next convention. If $V$ is a complex vector space we assume that all linear maps and subspaces are complex linear, all tensor products are over $\mathbf{C}$, and the word "dimension" means the complex dimension.

Let $V$ be a real (or complex) vector space of dimension $m$. Consider a non-degenerate symmetric bilinear form $s \in \operatorname{Symm}\left(V^{*} \otimes V^{*}\right)$ and a linear self-adjoint with respect to $s$ operator $L \in \operatorname{End}(V)$. Denote by $r(L)$ the degree of the minimal polynomial of the operator $L$. Let $\delta$ be a fixed real number. Consider the curves

$$
\gamma: t \rightarrow|\operatorname{det}(L-t \mathbf{1})|^{\delta} s(L-t \mathbf{1})^{-1} \in \operatorname{Symm}\left(V^{*} \otimes V^{*}\right)
$$

and

$$
\gamma_{\xi}: t \rightarrow|\operatorname{det}(L-t \mathbf{1})|^{\delta} s\left((L-t \mathbf{1})^{-1} \xi, .\right) \in V^{*},
$$

where $\xi \in V$ is a fixed vector in $V, \mathbf{1}$ is the identity operator, and the parameter $t$ is defined in an open set $U$ in $\mathbf{R}$ (or $\mathbf{C}$ ), $U \cap \operatorname{Spect}(L)=\emptyset$. Remark that we admit three possibilities: $V$ is real and $t$ is real, $V$ is complex and $t$ is complex or real. Given a curve $l: D \rightarrow W$, where $W$ is a vector space and $D$ is an open domain in $\mathbf{R}$ or $\mathbf{C}$, denote by $\operatorname{dim}_{D} l$ the dimension of the linear subspace spanned on the vectors $\{l(t) \mid t \in D\}$. Following our convention, if $W$ is a complex vector space, $\operatorname{dim}_{D} l$ denotes the complex dimension of the complex linear subspace spanned on $\{l(t) \mid t \in D\}$.

## Lemma 4.

(a) $\operatorname{dim}_{U} \gamma=r(L)$;
(b) $\operatorname{dim}_{U} \gamma_{\xi} \leq r(L)$ and there exists an open and dense subset $\Sigma \subset V$ such that for every $\xi \in \Sigma, \operatorname{dim}_{U} \gamma_{\xi}=r(L)$;
(c) if $t_{1}, \ldots, t_{r(L)} \in U, t_{i} \neq t_{j}(i \neq j)$, then $\gamma\left(t_{1}\right), \ldots, \gamma\left(t_{r(L)}\right)$ are linearly independent.

Proof of Lemma 4. Consider the case when $V$ is a real vector space and the parameter $t$ is real, $t \in U \subset \mathbf{R}, U \cap \operatorname{Spect}(L) \neq \emptyset$. The case of complex vector space is considered similarly. It follows from the non-degeneracy of the metric $s$ that $\operatorname{dim}_{U} \gamma=\operatorname{dim}_{U} \tilde{\gamma}$ and $\operatorname{dim}_{U} \gamma_{\xi}=\operatorname{dim}_{U} \tilde{\gamma}_{\xi}$, where $\tilde{\gamma}(t) \stackrel{\text { def }}{=} \operatorname{det}(L-t \mathbf{1})(L-t \mathbf{1})^{-1}$ and $\tilde{\gamma}_{\xi}(t) \stackrel{\text { def }}{=} \operatorname{det}(L-t \mathbf{1})(L-t \mathbf{1})^{-1} \xi$. It is clear that $\tilde{\gamma}(t)=L_{m-1} t^{m-1}+\ldots+L_{0}, L_{k} \in \operatorname{End}(V), L_{m-1}=(-1)^{m-1} 1$. Using the non-degeneracy of the Vandermonde determinant we obtain that $\operatorname{dim}_{U} \bar{\gamma}=\operatorname{rk}\left\{L_{m-1}, \ldots, L_{0}\right\}$ and $\operatorname{dim}_{U} \bar{\gamma}_{\xi}=\operatorname{rk}\left\{L_{m-1} \xi, \ldots, L_{0} \xi\right\}$. Denote by $V^{\mathrm{C}}$ the complexification of $V$. Let $L^{\mathrm{C}}, L_{k}^{\mathrm{C}} \in \operatorname{End}\left(V^{\mathrm{C}}\right)$ be the complexifications of the real operators $L$ and $L_{k}(k=0, \ldots, m-1)$. Denote by $r_{0}$ the number $r_{0} \stackrel{\text { def }}{=} \max _{\xi \in V} \operatorname{rk}\left\{L_{m-1} \xi, \ldots, L_{0} \xi\right\}$.

## Lemma 5.

(i) $\operatorname{rk}\left\{L_{m-1}, \ldots, L_{0}\right\}=\operatorname{rk}_{\mathbf{C}}\left\{L_{m-1}^{\mathrm{C}}, \ldots, L_{0}^{\mathrm{C}}\right\}$;
(ii) $r_{0}=\max _{\xi \in V^{\mathbf{C}}} \mathrm{rk}_{\mathbf{C}}\left\{L_{m-1}^{\mathbf{C}} \xi, \ldots, L_{0}^{\mathbf{C}} \xi\right\}$;
(iii) there exists an open dense subset $\Sigma \subset V$ such that for every $\xi \in \Sigma$, $r_{0}=\operatorname{rk}\left\{L_{m-1} \xi, \ldots, L_{0} \xi\right\}$.

Proof of Lemma 5. Item (i) of the lemma is obvious. Let us prove (iii). Taking a basis in $V$, denote by $\left(\xi_{1}, \ldots, \xi_{m}\right)$ the coordinates of the vectors of $V$. Consider the $m \times m$ matrix $T$ formed of the coordinates of the vectors $L_{m-1} \xi, \ldots, L_{0} \xi$. The elements of this matrix are linear polynomials of the variables $\xi_{1}, \ldots, \xi_{m}$. It is clear that there exists a non-zero minor $T_{r_{0}} \in \mathbf{R}^{r_{0}}\left[\xi_{1}, \ldots, \xi_{m}\right]$ of the matrix $T$. The set $\Sigma \stackrel{\text { def }}{=}\left\{\xi \in V \mid T_{r_{0}}(\xi) \neq 0\right\}$ satisfies the statement of item (iii). The assumption that the variables $\xi_{1}, \ldots, \xi_{m}$ take complex values doesn't change the rank of the matrix $T$. This proves item (ii). Lemma 5 is proved.

Consider the curves $\tilde{\gamma}^{\mathbf{C}}(\lambda) \stackrel{\text { def }}{=}\left(L^{\mathbf{C}}-\lambda \mathbf{1}\right)^{-1}$ and $\tilde{\gamma}_{\xi}^{\mathbf{C}}(\lambda) \stackrel{\text { def }}{=} \operatorname{det}\left(L^{\mathbf{C}}-\lambda \mathbf{1}\right)^{-1} \xi$, where $\lambda \in \mathbf{C} \backslash \operatorname{Spect}(L), \xi \in V^{\mathbf{C}}$, and $\mathbf{1}$ denotes the identity operator in
$V^{\mathrm{C}}$. As above, using the non-degeneracy of the Vandermonde determinant, we obtain that $\operatorname{dim}_{\mathrm{C} \backslash \operatorname{Spect}(L)} \tilde{\gamma}^{\mathrm{C}}=\operatorname{rk}_{\mathrm{C}}\left\{L_{m-1}^{\mathrm{C}}, \ldots, L_{0}^{\mathrm{C}}\right\}$ and $\operatorname{dim}_{\mathrm{C} \backslash \operatorname{Spect}(L)} \tilde{\gamma}_{\xi}^{\mathrm{C}}=$ $\mathrm{rk}_{\mathrm{C}}\left\{L_{\mathrm{m}-1}^{\mathrm{C}} \xi, \ldots, L_{0}^{\mathrm{C}} \xi\right\}$. Lemma 5 shows that $\operatorname{dim}_{U} \gamma=\operatorname{dim}_{\mathbf{C} \backslash \operatorname{Spect}(L)} \tilde{\gamma}^{\mathrm{C}}$ and $r_{0}=\max _{\xi \in V^{\mathrm{C}}} \operatorname{dim}_{\mathrm{C} \backslash \operatorname{Spect}(L)} \tilde{\gamma}_{\xi}^{\mathrm{C}}$. Without loss of generality we can suppose that the operator $L^{\mathrm{C}}$ is given in a Jordan's basis. Using the explicit form of $L^{\mathrm{C}}$, it is not hard to see that

$$
\operatorname{dim}_{\mathrm{C} \backslash \operatorname{Spect}(L)} \tilde{\gamma}^{\mathrm{C}}=r(L)
$$

and

$$
\max _{\xi \in V^{\mathrm{C}}} \operatorname{dim}_{\mathrm{C} \backslash \operatorname{Spect}(L)} \tilde{\gamma}_{\xi}^{\mathrm{C}}=r(L) .
$$

The first equality proves item (a). The second one shows that $r_{0}=r(L)$. Applying Lemma 5 (iiii) we prove (b). To prove item (c) remark that instead of the curves $\gamma\left(t_{1}\right), \ldots, \gamma\left(t_{r(L)}\right)$ it is sufficient to prove the linear independence over C of the curves $\tilde{\gamma}^{\mathrm{C}}\left(t_{1}\right), \ldots, \tilde{\gamma}^{\mathrm{C}}\left(t_{r(L)}\right)$, where the operator $L^{\mathrm{C}}$ is given in a Jordan's basis. Using the simple form of these curves we prove item (c). Lemma 4 is proved.

Let us return to the proof of Theorem 1. Suppose that $g$ and $\bar{g}$ are $P Q^{c}$-projective metrics given on the connected manifold $M^{m}$. Denote by $r$ the rank of the pair $g$ and $\bar{g}$, and let $D \subset M^{m}$ be an open set with compact closure in $M^{m}$. Without loss of generality we can suppose that $D$ is connected. Taking $r$ different real numbers $c_{1}, \ldots, c_{T}$ such that $\left|c_{k}\right|>m_{D}, m_{D} \stackrel{\text { def }}{=}$ $\sup _{x \in D} \max _{\lambda \in \text { Spect }^{\left(\left.A\right|_{x}\right)}}|\lambda|$, consider the quadratic forms $B_{i}^{D} \stackrel{\text { def }}{=} K_{c_{i}}(g, \bar{g})$ $(i=1, \ldots, r)$. The forms $B_{i}^{D}$ are well-defined on $D$. Considered as functions of the tangent bundle $T D, B_{i}^{D}(i=1, \ldots, r)$ are pairwise commuting integrals of the geodesic flow of the metric $g$ (Theorem 3).

Definition 7. A point $x_{0} \in M^{m}$ is called stable iff the rank $r(g, \bar{g})(x)$ of the pair of $P Q^{c}$-projective metrics $g$ and $\bar{g}$ is equal to some constant $q$ in an open neighborhood of the point $x_{0}$. We say that $x_{0}$ is a stable point of rank $q$.

Definition 8. A point $x_{0} \in M^{m}$ is called singular iff it is not stable.
Denote the set of stable points by $\mathcal{M}(g, \bar{g})$ and the set of singwlar points by $\mathcal{S}(g, \bar{g})$.

Lemma 6. The set of stable points $\mathcal{M}(g, \bar{g})$ is open and dense in $M^{m}$.
Proof of Lemma 6. The set $\mathcal{M}(g, \bar{g})$ is open by its definition. It follows from Lemma 4 that for every $x \in M^{m}$ there exists an open neighborhood $U(x)$ such that if $y \in U(x)$ then $r(g, \bar{g})(y) \geq r(g, \bar{g})(x)$. Indeed, taking $p=$ $r(g, \bar{g})(x)$ different real numbers $t_{1}, \ldots, t_{p},\left(-t_{i}\right) \notin \operatorname{Spect}\left(\left.A\right|_{x}\right)$, we see (item (c), Lemma 4) that the forms $\left.K_{t_{1}}\right|_{x}, \ldots,\left.K_{t_{p}}\right|_{x} \in \operatorname{Symm}\left(T_{x}^{*} M^{m} \otimes T_{x}^{*} M^{m}\right)$ are linearly independent. There exists an open neighborhood $U(x)$ such that if $y \in U(x)$ then $\left.K_{t_{1}}\right|_{y}, \ldots,\left.K_{t_{p}}\right|_{y}$ are linearly independent. Finally, applying item (a) of Lemma 4 we obtain that $r(g, \bar{g})(y) \geq r(g, \bar{g})(x)$.

Therefore, if $x_{0}$ is a singular point, then every open neighborhood of $x_{0}$ contains a point $y$ such that $r(g, \bar{g})(y)>r(g, \bar{g})\left(x_{0}\right)$.

Let us prove that the set of stable points $\mathcal{M}(g, \bar{g})$ is dense in $M^{m}$. Suppose that there exists an open set $Y \subset M^{m}$ that consists of singular points. Take a point $y_{1} \in Y, r(g, \bar{g})\left(y_{1}\right)=r_{1}$. The point $y_{1}$ is singular, and therefore there exists a point $y_{2} \in Y$ such that $r(g, \bar{g})\left(y_{2}\right)=r_{2}>r_{1}$. Applying this argument several times we find a (singular!) point $y_{l} \in Y$ of maximal rank $m$. From another side, the points of maximal rank $m$ are stable. This contradiction proves Lemma 6.

Lemma 7. Let $x_{0}$ be a stable point of rank $q \leq r, x_{0} \in D$. Then there exists an open neighborhood $U\left(x_{0}\right) \subset D$ such that:
(a) the quadratic in velocities functions $B_{1}^{D}(\xi), \ldots, B_{q}^{D}(\xi)$ are functionally independent on $T U\left(x_{0}\right)$. For every fixed $x \in U\left(x_{0}\right)$ the set of the points $\xi \in T_{x} M^{m}$ where the differentials $d_{\xi} B_{1}^{D}, \ldots, d_{\xi} B_{q}^{D}$ are linearly independent is open and dense in $T_{x} M^{m}$;
(b) if $c$ is a real constant such that $(A+c \mathbf{1})$ is non-degenerate on $U\left(x_{0}\right)$, then there exist constants $\alpha_{1}, \ldots, \alpha_{q}$ such that

$$
K_{c}(g, \bar{g})(\xi)=\sum_{k=1}^{q} \alpha_{k} B_{k}^{D}(\xi), \quad \xi \in T U\left(x_{0}\right)
$$

Proof of Lemma 7. Lemma 4 (c) shows that the forms $\left.B_{1}^{D}\right|_{x_{0}},\left.\ldots B_{q}^{D}\right|_{x_{0}}$, considered as elements of $\operatorname{Symm}\left(T_{x_{0}}^{*} M^{m} \otimes T_{x_{0}}^{*} M^{m}\right)$, are linearly independent. There exists an open neighborhood $U\left(x_{0}\right)$ of the point $x_{0}$ such that for every
$y \in U\left(x_{0}\right)$ the forms $\left.B_{1}^{D}\right|_{y},\left.\ldots B_{q}^{D}\right|_{y}$ are linearly independent and $r(g, \bar{g})(y)=$ q. Hence, there exist smooth functions $\alpha_{1}, \ldots, \alpha_{q} \in C^{\infty}\left(U\left(x_{0}\right)\right)$ such that

$$
K_{c}(g, \bar{g})(\xi)=\sum_{k=1}^{q} \alpha_{k}(y) B_{k}^{D}(\xi)
$$

where $\xi \in U\left(x_{0}\right), y=\pi(\xi)$, and $\pi: T M^{m} \rightarrow M^{m}$ is the projection on the base $M^{m}$. Denote by $E_{g}$ the "energy" integral $E_{g}(\xi) \stackrel{\text { def }}{=} \frac{1}{2} g(\xi, \xi)$ and let $\{. .\}_{g}$ be the Poisson bracket corresponding to the symplectic structure $\omega_{g}$. Using that $B_{1}^{D}(\xi), \ldots, B_{q}^{D}(\xi)$ and $K_{c}(\xi)$ are integrals of the geodesic flow of the metric $g$, we obtain $0=\left\{E_{g}, K_{c}\right\}_{g}=\sum_{k=1}^{q}\left\{E_{g}, \alpha_{k}\right\}_{g} B_{k}^{D}(\xi)$ for every $\xi \in T U\left(x_{0}\right)$. The linear independence of the forms $\left.B_{1}^{D}\right|_{y}, \ldots,\left.B_{q}^{D}\right|_{y}$ for every fixed $y \in U\left(x_{0}\right)$ shows that $\left\{E_{g}, \alpha_{k}\right\} \equiv 0$ on $T U\left(x_{0}\right)$, and therefore $\alpha_{k}$ are constants. Item (b) of Lemma 7 is proved.

Denote by $\left.B_{k}^{D}\right|_{T_{x} M^{m}}$ the restriction of the function $B_{k}^{D}(\xi)$ on the fiber $T_{z} M^{m} \hookrightarrow T M^{m}$. Taking a point $\xi \in T_{x} M^{m}$, we obtain $d_{\xi}\left(\left.B_{k}^{D}\right|_{T_{x} M^{m}}\right)(\eta)=$ $\left.2 B_{k}^{D}\right|_{z}(\xi, \eta)$, where $\eta \in T_{x} M^{m} \cong T_{\xi}\left(T_{x} M^{m}\right)$. It follows from Lemma 4 (b) that for every point $x \in U\left(x_{0}\right)$ there exists an open and dense in $T_{x} M^{m}$ subset $\Sigma_{z} \subset T_{x} M^{m}$ such that if $\xi \in \Sigma_{x}$ then $\left.B_{1}^{D}\right|_{x}\left(\xi,{ }_{\alpha}\right), \ldots,\left.B_{q}^{D}\right|_{x}(\xi,.) \in$ $T_{x}^{*} M^{m}$ are linearly independent. Therefore, the functions $B_{1}^{D}(\xi), \ldots, B_{q}^{D}(\xi)$ are functionally independent in $T U\left(x_{0}\right)$. Lemma 7 is proved.

Let us prove that the functions $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi)$ are functionally independent in TD. According to Lemma 6 and Lemma 7, it is sufficient to prove that the stable points in $D$ have rank $r$. Assume that there exists a stable point $y_{0} \in D$ having rank $r_{0}<r$. Without loss of generality we can suppose that the open set $D$ contains a stable point $x_{0} \in D$ of rank r. Assume for simplicity that the points $x_{0}$ and $y_{0}$ can be connected by a geodesic line $t \rightarrow \gamma(t) \in D, \gamma(0)=x_{0}, \gamma(1)=y_{0}$. Let us take neighborhoods $U\left(x_{0}\right)$ and $V\left(y_{0}\right)$ of the points $x_{0}$ and $y_{0}$ respectively, such that the conditions of Lemma 7 are satisfied. We can suppose that the differentials $d_{w} B_{1}^{D}, \ldots, d_{w} B_{r}^{D}$ are linearly independent at the point $w \stackrel{\text { def }}{=} \dot{\gamma}(0)$ (If not, we take $w^{\prime} \in T_{x_{0}} M^{m}$ such that $d_{w^{\prime}} B_{1}^{D}, \ldots, d_{w^{\prime}} B_{r}^{D}$ are linearly independent and $\exp w^{\prime} \in V\left(y_{0}\right)$ (see Lemma $\left.7(a)\right)$ ). Denote by $\zeta_{t}(\xi), \xi \in T M^{m}$, the one-parameter family of local diffeomorphisms of $T M^{m}$ corresponding to the geodesic flow of the metric $g$. Using the fact that the functions $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi)$ are integrals of the geodesic flow of $g$, we obtain that the differentials $d_{v} B_{1}^{D}, \ldots, d_{v} B_{r}^{D}, v \stackrel{\text { def }}{=} \zeta_{1}(w)$, are linearly independent. ¿From
another side, Lemma $7(b)$ shows that $B_{r_{0}+1}^{D}(\xi)=\sum_{k=1}^{r_{0}} \alpha_{k} B_{k}^{D}(\xi)$ where $\xi$ lies in $T V\left(y_{0}\right)$ and $\alpha_{k}$ are some constants. Hence, for every $\xi \in T V\left(y_{0}\right)$, $d_{\xi} B_{r_{0}+1}^{D}=\sum_{k=1}^{r_{0}} \alpha_{k} d_{\xi} B_{k}^{D}$. This contradiction proves that the stable points $x \in D$, that can be connected by a geodesic line $\gamma(t)$ lying in $D$ with another stable point $y \in D$ of rank $r$, are also of rank $r$. By assumption D is connected. Therefore, the stable points in $D$ have rank $r$. Item (a) of Theorem 1 is proved. Item (b) easily follows from Lemma 7 (b). Theorem 1 is proved.

## $5 P Q^{(-1)}$-projective hermitian metric

Let $M^{n}$ be a complex manifold of complex dimension $n$. Denote by $J$ the complex structure of $M^{n},\left(M^{2 n}, J\right) \cong M^{n}$. Consider a pair of $P Q^{(-1)}$. projective hermitian metrics $s$ and $\tilde{s}(\epsilon=-1$ and $P Q=-\mathbf{1})$. Denote by $K_{c}(s, \bar{s})$ the local family of pairwise commuting integrals of the geodesic flow of the metric $s$ (Theorem 3). In our case $\epsilon=-1$ and we obtain that $K_{c}(s, \tilde{s}) \stackrel{\operatorname{def}}{=}|\operatorname{det}(A+c \mathbf{1})|^{1 / 2} s(A+c \mathbf{1})^{-1}$, where $A=A(s, \tilde{s})$.

Fixing a complex chart $\left\{\left(z^{1}, \ldots, z^{n}\right)\right\}$ consider the hermitian matrices $S \stackrel{\text { def }}{=}\left(s_{\alpha \bar{\beta}}\right)$ and $\tilde{S} \stackrel{\text { def }}{=}\left(\tilde{s}_{\alpha \bar{\beta}}\right)$ related to the metrics $d s^{2}=2 s_{\alpha \bar{\beta}} d z^{\alpha} d \bar{z}^{\beta}$ and $d \bar{s}^{2}=2 \bar{s}_{\alpha \bar{\beta}} d z^{\alpha} d \bar{z}^{\beta}$ respectively. As usual, we omit the summation symbols in the formulas. Define the operator $\mathcal{A} \stackrel{\text { def }}{=} \mathcal{A}_{\beta}^{\alpha} \frac{\partial}{\partial z^{\alpha}} \otimes d z^{\beta}$, where

$$
\begin{equation*}
\mathcal{A}_{\beta}^{\alpha} \stackrel{\operatorname{def}}{=}\left|\frac{\operatorname{det} \tilde{S}}{\operatorname{det} S}\right|^{\frac{1}{n+1}} \tilde{s}^{\alpha \tilde{\nu}} s_{\nu \bar{\nu}}, \tag{18}
\end{equation*}
$$

and $\tilde{s}^{\alpha \bar{\nu}} \tilde{s}_{D \beta}=\delta_{\beta}^{\alpha}$. By definition $\mathcal{A}$ is a smooth section of the vector bundle $\operatorname{End}_{\mathbf{C}}\left(T^{(1,0)} M^{n}\right)$, where $T^{(1,0)} M^{n}$ denotes the bundle of the holomorphic tangent vectors to $M^{n}$. Fixing a point $x \in M^{n}$, denote by $\rho(s, \tilde{s})(x)$ the minimal polynomial of the operator $\left.\mathcal{A}\right|_{x}$.

Definition 9. The number $\rho(s, \bar{s}) \stackrel{\text { def }}{=} \max _{x \in M^{n}} \rho(s, \tilde{s})(x)$ is called hermitian rank of the pair of $P Q^{(-1)}$-projective hermitian metrics.

Theorem 4. Suppose that the complex manifold $M^{n}$ is connected and let the hermitian rank of the pair of $P Q^{(-1)}$-projective hermitian metrics $s$ and $\bar{s}$ be $r$. Then there exist $r$ hermitian forms $B_{1}, \ldots, B_{r}$ such that:
(a) considered as functions of the tangent bundle $T M^{n}$, the quadratic forms $B_{1}(\xi), \ldots, B_{r}(\xi)$ are functionally independent pairwise commuting integrals of the geodesic flow of the metric s;
(b) for every fixed real constant $c$, the integral $K_{c}(s, \tilde{s})(\xi)$ is well-defined and

$$
K_{c}(s, \tilde{s})(\xi)=\sum_{k=1}^{r} \alpha_{k} B_{k}(\xi),
$$

where $\alpha_{k}$ are some constants.
The functions $B_{1}(\xi), \ldots, B_{r}(\xi)$ can be taken in the form $B_{k}=K_{c_{k}}(s, \tilde{s})$, where $c_{k}$ are appropriately chosen constants.

Proof of Theorem 4. Fixing a complex chart $\left\{\left(z^{1}, \ldots z^{n}\right)\right\}$ we have $s=$ $s_{a \beta}\left(d z^{\alpha} \otimes d \bar{z}^{\beta}+d \bar{z}^{\beta} \otimes d z^{\alpha}\right)$ and $\tilde{s}=\tilde{s}_{\alpha \bar{\beta}}\left(d z^{\alpha} \otimes d \bar{z}^{\beta}+d \bar{z}^{\beta} \otimes d z^{\alpha}\right)$, where $S \stackrel{\text { def }}{=}\left(s_{\alpha \bar{\beta}}\right)$ and $\tilde{S} \stackrel{\text { def }}{=}\left(\tilde{s}_{\alpha \bar{\beta}}\right)$ are hermitian matrices. Denote by $[s]$ and $[\tilde{s}]$ the Gramians of the metrics $s$ and $\tilde{s}$ respectively, i.e.

$$
[s]=\left[\begin{array}{ll}
0 & S \\
\bar{S} & 0
\end{array}\right]
$$

and

$$
[\tilde{s}]=\left[\begin{array}{cc}
0 & \tilde{S} \\
\overline{\tilde{S}} & 0
\end{array}\right]
$$

It follows from the definition of the operator $A(s, \tilde{s})$ (formula (4)) that in the fixed complex chart we have

$$
A(s, \tilde{s}) \stackrel{\operatorname{def}}{=}\left|\frac{\operatorname{det}[\tilde{s}]}{\operatorname{det}[s]}\right|^{\frac{1}{2(n+1)}}[\tilde{s}]^{-1}[s]=\left|\frac{\operatorname{det} \tilde{S}}{\operatorname{det} S}\right|^{\frac{1}{n+1}}[\tilde{s}]^{-1}[s] .
$$

Hence, $A(s, \tilde{s})=\mathcal{A}_{\beta}^{\alpha} \frac{\partial}{\partial z^{\alpha}} \otimes d z^{\beta}+\mathcal{A}_{\bar{\beta}}^{\bar{\alpha}} \frac{\partial}{\partial \bar{z}^{\alpha}} \otimes d \bar{z}^{\beta}$, where $\mathcal{A}_{\beta}^{\alpha}$ is given by formula (18) and $\mathcal{A}_{\bar{\beta}}^{\bar{\alpha}}$ coincides with the complex conjugation of $\mathcal{A}_{\beta}^{\alpha}$ (i.e. $\mathcal{A}_{\bar{\beta}}^{\bar{\alpha}}=\overline{\mathcal{A}}_{\beta}^{\alpha}$ ). As usual, we identify the operator $\mathcal{A}$ with the square matrix $\left(\mathcal{A}_{\beta}^{\alpha}\right)$.

Lemma 8. The degree of the minimal polynomial of the operator $\mathcal{A}(s, \tilde{s})$ coincides with the degree of the minimal polynomial of the operator $A(s, \tilde{s})$.

Proof of Lemma 8. A simple calculation shows that

$$
\mathcal{A}-\bar{\lambda} \mathbf{1}=\tilde{S}^{-1}(\mathcal{A}-\lambda)^{*} \tilde{S}
$$

where (. $)^{*}$ denotes the hermitian conjugation of a matrix. Hence, for every integer $k$ we have $(\mathcal{A}-\bar{\lambda} \mathbf{1})^{k}=\bar{S}^{-1}\left[(\mathcal{A}-\lambda)^{k}\right]^{\bullet} \tilde{S}$. Consider the Jordan's normal form of the operator $\mathcal{A}$. The last equalities show that the Jordan's decompositions corresponding to the eigenvalues $\lambda$ and $\bar{\lambda}$ coincide. Finally, we conclude the statement of the lemma from the formula $A(s, \tilde{s})=\mathcal{A}_{\beta}^{\alpha} \frac{\partial}{\partial z^{\circ}} \otimes$ $d z^{\beta}+\overline{\mathcal{A}}_{\beta}^{\alpha} \frac{\partial}{\partial z^{a}} \otimes d \bar{z}^{\beta}$. Lemma 8 is proved.

It follows from Lemma 8 that the rank $r(s, \tilde{s})$ of the pair $s$ and $\tilde{s}$ coincides with their hermitian rank, i.e. $r=r(s, \tilde{s})=\rho(s, \tilde{s})$.

Let us fix an arbitrary real constant $c$. Denote by $\mathcal{K}_{c}(s, \tilde{s})$ the hermitian matrix of the form $K_{c}(s, \tilde{s})$. A simple calculation shows that

$$
\begin{aligned}
\mathcal{K}_{c}(s, \tilde{s}) & =\operatorname{det}(\overline{\mathcal{A}}+c \mathbf{1}) S(\overline{\mathcal{A}}+c \mathbf{1})^{-1} \\
& =\mathcal{I}_{n-1}(s, \tilde{s}) c^{n-1}+\ldots+\mathcal{I}_{0}(s, \tilde{s})
\end{aligned}
$$

The last formula is valid in every fixed complex chart. Therefore, there exist well-defined on the whole $M^{n}$ hermitian forms $I_{n-1}, \ldots, I_{0}$ such that $K_{c}=I_{n-1} c^{n-1}+\ldots+I_{0}$. Denote by $I_{n-1}(\xi), \ldots, I_{0}(\xi)$ the corresponding smooth functions of the tangent bundle $T M^{n}$. We obviously have

$$
\begin{equation*}
K_{c}(\xi)=I_{n-1}(\xi) c^{n-1}+\ldots+I_{0}(\xi), \tag{19}
\end{equation*}
$$

where $I_{j} \in C^{\infty}\left(T M^{n}\right)$. Denote by $\mathcal{I}(s, \tilde{s})$ the vector space spanned on the functions $I_{j} \in C^{\infty}\left(T M^{n}\right)(j=0, \ldots, n-1)$. Take a basis $B_{1}(\xi), \ldots, B_{r^{\prime}}(\xi)$ of the linear space $\mathcal{I}(s, \tilde{s})$. Let us fix an open set $D \subset M^{n}$ with compact closure in $M^{n}$ and consider the quadratic forms $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi)$ given by Theorem 1. Item (b) of Theorem 1 and formula (19) show that $\left.B_{k}\right|_{T D} \in$ $\operatorname{Span}\left(\left.B_{1}^{D}\right|_{T D}, \ldots,\left.B_{r}^{D}\right|_{T D}\right)\left(k=1, \ldots, r^{\prime}\right)$ where $\operatorname{Span}\left(\left.B_{1}^{D}\right|_{T D}, \ldots,\left.B_{r}^{D}\right|_{T D}\right)$ denotes the vector space spanned on the restrictions of the functions $B_{k}^{D}(\xi)$ on $T D$. ¿From another side, $B_{k}^{D}(\xi) \stackrel{\text { def }}{=} K_{c_{\psi}}(s, \bar{s})(\xi)$. Using formula (19) again we obtain that $\left.B_{k}^{D}\right|_{T D} \in \operatorname{Span}\left(\left.B_{1}\right|_{T D}, \ldots,\left.B_{r}\right|_{T D}\right)(k=1, \ldots, r)$. Therefore, $r=r^{\prime}$. The functions $B_{1}^{D}(\xi), \ldots, B_{r}^{D}(\xi)$ are functionally independent on $T D$. Hence, the functions $B_{1}(\xi), \ldots, B_{r}(\xi)$ are functionally independent as well. Finally, recall that the set $D$ was taken arbitrary. Theorem 4 is proved.

Remark 6. In the present section we don't use essentially the integrability of the complex structure $J$. Therefore, Theorem 4 still holds if $\left(M^{2 n}, J\right)$ be an almost complex manifold of real dimension $2 n$.

## 6 Examples. Integrable systems on $\mathrm{CP}^{n}$

The aim of the present section is to find a family of completely integrable systems on the complex projective space $\mathbf{C P}^{n}$. Denote by $\left\{\left(z_{0}: \ldots: z_{n}\right)\right\}$ the homogeneous coordinates of $\mathbf{C P}^{n}$ and consider the affine chart $\mathbf{C}^{n} \ni$ $\left(z_{1}, \ldots, z_{n}\right) \mapsto\left(1: z_{1}: \ldots: z_{n}\right) \in \mathbf{C P}^{n}$. In coordinates $\left\{\left(z_{1}, \ldots, z_{n}\right)\right\}$, the Fubini metrics are given by the formula

$$
\begin{equation*}
d g^{2} \stackrel{\text { def }}{=} 2 \frac{\sum_{\alpha=1}^{n} \epsilon_{\alpha}\left|d z_{\alpha}\right|^{2}+\frac{K}{2}\left(\left(\sum_{\alpha=1}^{n} \epsilon_{\alpha}\left|z_{\alpha}\right|^{2}\right)\left(\sum_{\alpha=1}^{n} \epsilon_{\alpha}\left|d z_{\alpha}\right|^{2}\right)-\left|\sum_{\alpha=1}^{n} \epsilon_{\alpha} \bar{z}_{\alpha} d z_{\alpha}\right|^{2}\right)}{\left(1+\frac{K}{2} \sum_{\alpha=1}^{n} \epsilon_{\alpha}\left|z_{\alpha}\right|^{2}\right)^{2}} \tag{20}
\end{equation*}
$$

where $K \neq 0$ and the "signs" $\epsilon_{\alpha}= \pm 1(\alpha=1, \ldots, n)$ ape fixed. Consider the hermitian form $Q(\xi, \bar{\eta}) \stackrel{\text { def }}{=} \xi_{0} \bar{\eta}_{0}+\frac{K}{2} \sum_{\alpha=1}^{n} \epsilon_{\alpha} \xi_{\alpha} \bar{\eta}_{\alpha}, \xi, \eta \in \mathbf{C}^{n+1}$. The hypersurface $A b s \hookrightarrow \mathbf{C P}^{n}$ given in homogeneous coordinates by $A b s \stackrel{\text { def }}{=}$ $\{Q(z) \stackrel{\text { def }}{=} Q(z, \bar{z})=0\}$ is called absolute of the corresponding Fubini metric. The Fubini metrics are smoothly defined on $\mathbf{C P}^{n} \backslash A b s$. If $K>0$ and $\epsilon_{\alpha}=1$ then $A b s=\emptyset$, and the corresponding Fubini metric is a smooth Riemannian metric on $\mathrm{CP}^{n}$. The Fubini metrics are usually considered only on the subset $F \stackrel{\text { def }}{=}\{Q(z)>0\} \subset \mathbf{C P}^{n}$. Nevertheless, it will be more convenient for us to think of the Fubini metrics as metrics defined on the whole CP ${ }^{n}$ and having "singularities" in Abs. The Fubini metrics are hermitian and the corresponding hermitian matrices are $g_{\alpha \bar{\beta}}=\frac{\epsilon_{\alpha} \delta_{\alpha \beta}}{Q(z)}-\frac{K}{2} \frac{\left(\epsilon_{\alpha} \bar{z}_{\alpha}\right)\left(\epsilon_{\beta} z_{\beta}\right)}{Q(z)^{2}}$. It is well-known that the Fubini metrics are Kählerian metrics.

Denote by $\nabla$ the Levi-Civita connection corresponding to the Fubini metric $g$. The connection $\nabla$ can be extended in a natural way to a connection on the complexification of the tangent bundle. It can be easily seen that the corresponding Christoffel symbols are given by the formula $\Gamma_{p q}^{\alpha}=-\frac{\kappa}{2 q(z)}\left(\delta_{p}^{\alpha} \epsilon_{q} \bar{z}_{q}+\delta_{q}^{\alpha} \epsilon_{p} \bar{z}_{p}\right), \Gamma_{\bar{p} \bar{q}}^{\dot{\alpha}}=\bar{\Gamma}_{p q}^{\alpha}$, and the other components of the Christoffel symbols vanish (see [15], $\S 5$, for the case $\epsilon_{\alpha}=1$ ).

Let $\mu_{L}: \mathbf{C P}^{n} \rightarrow \mathbf{C P}^{n}$ be a projective transformation induced by some (complex)linear transformation $L: \mathrm{C}^{n+1} \rightarrow \mathrm{C}^{n+1}$ given in matrix form by the non-degenerate complex matrix $L \in G L_{n+1}(\mathbf{C})$. Denote by $\tilde{g}$ the pull-back $\mu_{L}^{*} g$.

Proposition 5. The metrics $g$ and $\bar{g}$ are $h$-projective Kählerian metrics.
Proof of Proposition 5. Let $L_{2}$ be a complex 2-plane in $\mathbf{C}^{n+1}$. The set of complex lines lying in $L_{2}$ gives a natural embedding of the complex projective line $\mathbf{C P}^{1}$ in $\mathbf{C P}^{n}$. We call such embeddings projective lines. Proposition 5 easily follows from the next simple lemma.

Lemma 9. A smooth curve $\gamma(t) \in \mathbf{C P}^{n} \backslash$ Abs is holomorphically planar with respect to a fixed Fubini metric iff $\gamma(t)$ lies in a projective line.

Proof of Lemma 9. Consider the affine chart $\left\{\left(z_{1}, \ldots, z_{n}\right)\right\}$ and suppose that $\gamma(t)=\left(\gamma^{1}(t), \ldots, \gamma^{n}(t)\right)$. The condition that $\gamma(t)$ is holomorphically planar with respect to a fixed Fubini metric $g$ is equivalent to the equation

$$
\frac{\nabla \dot{\gamma}^{\alpha}}{d t}(t)=\rho(t) \dot{\gamma}^{\alpha}(t), \alpha=1, \ldots, n
$$

where $\rho(t)$ is a smooth complex-valued function of the real parameter $t$ and $\frac{\nabla j^{\alpha}}{d t}$ are the components of the "holomorphic" part of the real vector $\frac{\nabla \gamma}{d t}$. Using the explicit form of the Christoffel symbols of the Fubini metric $g$ we obtain

$$
\begin{aligned}
\frac{\nabla \dot{\gamma}^{\alpha}}{d t}(t) & =\frac{d^{2} \gamma^{\alpha}}{d t^{2}}+\Gamma_{p q}^{\alpha} \dot{\gamma}^{p} \dot{\gamma}^{q} \\
& =\frac{d^{2} \gamma^{\alpha}}{d t^{2}}-\frac{K}{Q}\left(\epsilon_{p} \bar{z}_{p} \dot{\gamma}^{p}\right) \dot{\gamma}^{\alpha} .
\end{aligned}
$$

Therefore, the curve $\gamma(t)$ is holomorphically planar if and only if $\frac{d^{2} \gamma^{\alpha}}{d t^{2}}=$ $\rho_{1}(t) \frac{d \gamma^{a}}{d t}$, where $\rho_{1}(t)$ is a smooth complex-valued function of $t$. This completes the proof of Lemma 9.
Finally, Proposition 5 follows from the fact that $\mu_{L}: \mathbf{C P}^{n} \rightarrow \mathbf{C P}^{n}$ maps projective lines to projective lines. Proposition 5 is proved.

An analog of Lemma 9 in the case of positive definite Fubini metrics is proved in [15], $\S 6$.

$$
\begin{equation*}
\mathcal{A}_{\beta}^{\alpha}=\rho_{\beta}^{-1} \delta_{\beta}^{\alpha}-\frac{K}{2 Q}\left(\left(1-\rho_{\alpha}\right) z_{\alpha} / \rho_{\alpha}\right)\left(\epsilon_{\beta} \bar{z}_{\beta}\right) \tag{22}
\end{equation*}
$$

Denote by $\mathcal{A}$ the matrix with elements $\mathcal{A}_{\beta}^{\alpha}$. Consider the sequences of hermitian matrices $\left\{G^{(l)}\right\}_{l \in \mathbf{Z}}$ and $\left\{\tilde{G}^{(l)}\right\}_{l \in \mathbf{Z}}$ defined by the formulas $G^{(l)} \stackrel{\text { def }}{=}$ $G \overline{\mathcal{A}}^{l}$ and $\tilde{G}^{(l)} \stackrel{\text { def }}{=} \tilde{G} \overline{\mathcal{A}}^{l}$. Denote by $g^{(l)}$ and $\tilde{g}^{(l)}$ the hermitian metrics

$$
\begin{equation*}
d g^{(l)^{2}} \stackrel{\text { del }}{=} 2 g_{\alpha \bar{\beta}}^{(l)} d z_{\alpha} d \bar{z}_{\beta} \tag{23}
\end{equation*}
$$

and

$$
\begin{equation*}
d \tilde{g}^{(l)^{2}} \stackrel{\text { def }}{=} 2 \bar{g}_{\alpha \bar{\beta}}^{(l)} d z_{\alpha} d \bar{z}_{\beta}, \tag{24}
\end{equation*}
$$

where $g_{\alpha \bar{\beta}}^{(l)}$ and $\tilde{g}_{\alpha \bar{\beta}}^{(l)}$ are the elements of the hermitian matrices $G^{(l)}$ and $\tilde{G}^{(l)}$ respectively.

Consider the operators $\mathcal{P}_{l}, \mathcal{Q}_{l} \in \Gamma\left(\operatorname{End}_{\mathbf{C}}\left(T^{(1,0)}\left(\mathbf{C P}^{n} \backslash A b s\right)\right)\right)$ given in coordinates by the matrices $i \mathcal{A}^{l}$ and $i \mathcal{A}^{-l}$ respectively and define the "real" operators $P_{l} \stackrel{\text { def }}{=} \mathcal{P}_{l}+\overline{\mathcal{P}}_{l}$ and $Q_{l} \stackrel{\text { def }}{=} \mathcal{Q}_{l}+\overline{\mathcal{Q}}_{l}$. The next theorem follows from the results proved in Sect.2.4.

Theorem 5. For every fixed integer $l \in \mathbf{Z}$ the hermitian metrics $g^{(l)}$ and $\tilde{g}^{(l)}$ given by formulas (23) and (24) are $P_{l} Q_{l}^{(-1)}$-projective hermitian metrics.

The sequence of metrics $g^{(l)}$ and $\tilde{g}^{(l)}(l \in \mathbf{Z})$ given by Theorem 5 is called CP ${ }^{n}$-hierarchy.

Let us consider the one-parameter groups of transformations of $\mathrm{CP}^{n}$ given in coordinates by the formulas

$$
T_{k}(\phi):\left(z_{1}, \ldots, z_{k}, \ldots, z_{n}\right) \mapsto\left(z_{1}, \ldots, \exp (i \phi) z_{k}, \ldots, z_{n}\right)
$$

It follows from (20) and (21) that $T_{k}(\phi)$ preserve the metrics $g$ and $\tilde{g}$, and therefore they preserve the whole $\mathbf{C P}^{n}$-hierarchy. Denote by $T_{k}$ the corresponding Killing symmetries,

$$
\begin{equation*}
T_{k} \stackrel{\text { def }}{=} i\left(z_{k} \frac{\partial}{\partial z_{k}}-\bar{z}_{k} \frac{\partial}{\partial \bar{z}_{k}}\right) . \tag{25}
\end{equation*}
$$

Consider the "complex" impulses $p_{k} \stackrel{\text { def }}{=} \frac{1}{2}\left(p_{x_{k}}-i p_{y_{k}}\right)$ and $\bar{p}_{k} \stackrel{\text { def }}{=} \frac{1}{2}\left(p_{x_{k}}+\right.$ $\left.i p_{y_{k}}\right)(k=1, \ldots, n)$, where $p_{x_{k}}$ and $p_{y_{k}}$ are the impulses corresponding to the chart $\left\{\left(x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right)\right\}, z_{k} \stackrel{\text { def }}{=} x_{k}+i y_{k}$. The chart $\left\{\left(p_{1}, \ldots, p_{n} ; z_{1}, \ldots, z_{n}\right)\right\}$ is a complex chart of $T^{*} \mathrm{CP}^{n}$. The canonical symplectic structure $\omega$ on $T^{*} \mathrm{CP}^{n}$ is given by the formula $\omega=\sum_{k=1}^{n} d p_{k} \wedge d z_{k}+\sum_{k=1}^{n} d \bar{p}_{k} \wedge d \bar{z}_{k}$.

Theorem 6. For every fixed integer $l \in \mathbf{Z}$ the functions $\mathcal{I}_{n-1}^{(l)}(p), \ldots, \mathcal{I}_{0}^{(l)}(p)$ given by the expansion

$$
\begin{align*}
\mathcal{K}_{c}^{(l)}(p) & \stackrel{\text { def }}{=} \operatorname{det}(\mathcal{A}+c \mathbf{1})\left\langle(\mathcal{A}+c \mathbf{1})^{-1} \mathcal{A}^{l} \bar{G}^{-1} \bar{p}, p\right\rangle \\
& =\mathcal{I}_{n-1}^{(l)}(p) c^{n-1}+\ldots+\mathcal{I}_{0}^{(l)}(p), \tag{26}
\end{align*}
$$

where $p \stackrel{\text { def }}{=}\left(p_{1}, \ldots, p_{n}\right), \bar{p} \xlongequal{\text { def }}\left(\bar{p}_{1}, \ldots, \bar{p}_{n}\right)$ and $\langle X, Y\rangle \stackrel{\text { def }}{=} \sum_{k=1}^{n} X_{k} Y_{k}$, are in involution with respect to the canonical symplectic structure $\omega$ on the cotangent bundle $T^{*} \mathrm{CP}^{n}$. If $\rho_{\alpha} \neq \rho_{\beta}(\alpha \neq \beta)$ then the functions $\mathcal{I}_{n-1}^{(l)}(p), \ldots, \mathcal{I}_{0}^{(l)}(p)$ are functionally independent on $T^{*}\left(\mathbf{C P}^{n} \backslash \mathrm{Abs}\right)$. Adding to the functions $\mathcal{I}_{\mathrm{n}-1}^{(n)}(p), \ldots, \mathcal{I}_{0}^{(l)}(p)$ the Noether integrals $T_{k}(p) \stackrel{\text { def }}{=} i\left(z_{k} p_{k}-\bar{z}_{k} \bar{p}_{k}\right)(k=1, \ldots, n)$ corresponding to the Killing symmetries (25), we obtain a complete system of functionally independent functions in involutions on $T^{*}\left(\mathbf{C P}^{n} \backslash \mathrm{Abs}\right)$.

Proof of Theorem 6. It follows from formula (22) that $\mathcal{A}_{\beta}^{\alpha}(0)=\rho_{\beta}^{-1} \delta_{\beta}^{\alpha}$. Hence, if $\rho_{\alpha} \neq \rho_{\beta}(\alpha \neq \beta)$ then the hermitian rank of the pair $g^{(l)}$ and $\tilde{g}^{(l)}$ is $n$. Finally, the statement of the theorem follows from Theorem 4, Sect.5, applied to the pair $g^{(-l)}$ and $\tilde{g}^{(-l)}$ from the CP-hierarchy. Theorem 6 is proved.

Corollary 2. Provided $\rho_{\alpha} \neq \rho_{\beta}(\alpha \neq \beta)$, the geodesic flows of the metrics $g^{(l)}$ and $\tilde{g}^{(l)}$ from the $\mathbf{C P}^{n}$-hierarchy are completely integrable.

Remark 7 Taking $l=0$ and $\epsilon_{\alpha}=1$, we obtain a complete family of pairuise commuting integrals of the geodesic flow of the standard Fubini metric on $\mathrm{CP}^{n}$ (see [12, 13]). Our theorem gives an infinite family of metrics on $\mathrm{CP}^{n}$ with completely integrable geodesic flows.

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