Nonlinear Impulsive Differential Systems*

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Abstract

Using Schauder fixed point theorem we prove the asymptotic equilibrium of nonlinear differential equations with impulse action.

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1 Introduction

Let $\nu = \{t_i\}_{i=1}^\infty \subset [0,\infty) = I$, $t_i < t_{i+1} \to \infty$ as $i \to \infty$ the fixed moments of impulsive effects of the system:

$$x'(t) = F(t, x(t)), \quad t \neq t_i$$

$$\Delta x(t_i) = G_i(x(t_i)), \quad t = t_i$$
(1)

 $\Delta x(\iota_i) = G_i(x(\iota_i)), \ \iota = \iota_i$

where $\Delta x(t_i) = x(t_i^+) - x(t_i^-)$. As usual, $x(t_i^+)$ and $x(t_i^-)$ denote respectively, the right and the left lateral limit of x(t) as $t \to t_i$.

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The theory of impulsive differential equations has developed over the last ten years (see [1, 4-8]). These process appear as a natural description of many models in Medicine, Biology, optimal control models in Economics, etc.

Let U be an open subset of \mathbb{C}^n containing the origin. Assume the following

(F) The function $F:[0,\infty)\times U\to \mathbb{C}^n$ satisfies

$$|F(t,x)| \le \lambda(t)|f(x)|,$$

$$|F(t,x_1) - F(t,x_2)| \le \lambda(t)|f(x_1) - f(x_2)|$$

where $f: U \to \mathbb{C}^n$ is a continuous function.

(G) The functions $G_i: U \to \mathbb{C}^n \ (i=1,2,\cdots)$ satisfy

$$|G_i(x)| \leq \beta_i |g(x)|,$$

$$|G_i(x_1) - G_i(x_2)| \le \beta_i |g(x_1) - g(x_2)|$$

where $g:U\to {\bf C}^n$ is a continuous function.

(I) The function $\lambda:[0,\infty)\to[0,\infty)$ is an integrable function and $\beta:\mathbf{N}\to[0,\infty)$ is an absolutely summable sequence.

Among those equations we have the interesting systems

$$x'(t) = A(t)F(x(t)),$$

 $\Delta x(t_i) = B_i g(x(t_i)).$
(2)

Let $B_r = B[0, r] \subseteq U$ a closed ball. Define

$$||f||_{B_r} = \sup_{x \in B_r} |f(x)|$$
 (3)

and for $t_0 \ge 0$

$$\alpha(t_0) = \|f\|_{B_r} \cdot \int_{t_0}^{\infty} \lambda(s)ds + \|g\|_{B_r} \cdot \sum_{(t_0,\infty)} \beta_i,$$
 (4)

where

$$\sum_{(t_0,t)} \beta_i := \sum_{i,t_i \in (t_0,t)} \beta_i.$$

Let be (μ, t_0) satisfying

$$\mu + \alpha(t_0) \le r \tag{5}$$

We will prove that for $|x_0| \le \mu$, any solution $x = x(t, t_0, x_0)$ of Eq. (1) is defined and bounded on $[t_0, \infty)$ and it satisfies

$$x(t) = \xi + O(\Lambda(t)) \tag{6}$$

where $\xi \in \mathbb{C}^n$ is constant and

$$\Lambda(t) = \int_{t}^{\infty} \lambda(s)ds + \sum_{(t,\infty)} \beta_{i}. \qquad (7)$$

Moreover, $x(t_0) \neq 0$ implies $\xi \neq 0$ whenever t_0 is sufficiently large. Conversely, given $\xi \in U$ there exist t_0 sufficiently large and a solution x defined on $[t_0, \infty)$ a neighborhood of infinity such that (6) holds. Moreover, if $\xi \neq 0$ then there exists such a solution x of Eq.(1) satisfying $x(t) \neq 0$ for any $t \in [t_0, \infty)$.

2 Preliminary Facts

Let $C^+_{\nu}(\mathbf{I})$, $I=[0,\infty)$, be the vectorial space formed by the continuous functions $x:I-\nu\to \mathbf{C}^n$ such that $x(t_i^-)=x(t_i)$ and $x(t_i^+)$ exist for $t_i\in \nu$. Consider $\mathcal{V}_{\nu^+}(I)$ the bounded functions x in $C^+_{\nu}(I)$. \mathcal{V}_{ν^+} is a Banach space with the supremun-norm:

$$||x|| = \sup_{t \in I} |x(t)|.$$

Lemma 1 Any $S \subset V_{\nu^+}([a,b])$ bounded and equicontinuous in $t \neq t_i$ is relatively compact in $V_{\nu^+}([a,b])$.

Proof: Let $\{t_1,t_2,\cdots,t_m\}$ be a finite number of $t_i\in \nu$ contained in [a,b]. Next, the result will follow from Arzela-Ascoli theorem in this way. i) By applying it on any $l_i=[t_i,t_{i+1}]$ ($1\leq i\leq m$) where we consider $x(t_i):=x(t_i^+)$ ii) $N_x=max_{1\leq i\leq m}|\Delta x(t_i)|$ is uniformly bounded and hence they forme a totally bounded set in \mathbb{R} .

Definition 1 $S \subset V_{\nu^+}([a,\infty))$ is called an equiconvergent set if any $x \in S$ converges to x_{∞} as $t \to \infty$ and for any $\varepsilon > 0$ there exists T (big enough) such that

$$|x(t) - x_{\infty}| \le \varepsilon$$
 for $t \ge T$

for every $x \in S$

Lemma 2 If $S \subset V_{\nu^+}([a, \infty))$ is bounded, equicontinuous in $t \notin \nu$ and equiconvergent, then S is relatively compact.

Proof: Given $\varepsilon > 0$, there exists $T = T(\varepsilon)$ such that $|x(t) - x_{\infty}| \le \varepsilon$ for $t \ge T$ and every $x \in S$. The set $S_{\infty} = \{x_{\infty}/x \in S\}$ is contained in a ball $B(0,\rho) \subset {\bf C}^n$ and consequently S_{∞} is totally bounded. Finally on [a,T] we apply Lemma 1. So the proof is complete.

Consider the operator H given by

$$(\mathcal{H}x)(t) = x_0 + \int_{t_0}^t F(s, x(s))ds + \sum_{(t_0, t)} G_i(x(t_i)).$$

Lemma 3 Under conditions (F), (G) and (I), the operator \mathcal{H} is completely continuous.

Proof: Let D=D(O,r) a ball in \mathcal{V}_{ν^+} . Assume that $\mathcal{H}x$ is defined for $x\in D$. By conditions (F), (G) and (I), the operator \mathcal{H} is well defined and

$$\mathcal{H}:D \to \mathcal{V}_{\nu^+}([t_0,\infty)).$$

Now, we will prove that $\mathcal{F}=\mathcal{H}(D)$ is equiconvergent. In fact, for any $x\in D$, $y=\mathcal{H}x$ is convergent to ξ as $t\to\infty$, where

$$\xi = x_0 + \int_{t_0}^{\infty} F(s, x(s)) ds + \sum_{(t_0, \infty)} G_i(x(t_i)).$$
 (8)

Moreover,

$$|y(t) - \xi| \le \int_{t}^{\infty} |F(s, x(s))| ds + \sum_{(t, \infty)} |G_{i}(x(t_{i}))| = 0(\Lambda(t)),$$
 (9)

where

$$\Lambda(t) = \int_{t}^{\infty} \lambda(s)ds + \sum_{(t,\infty)} \beta_{i}$$

So, \mathcal{F} is equiconvergent, and by Lemma 2 \mathcal{F} is relatively compact. On the other hand, $\mathcal{H}:D\to \mathcal{V}_{\nu}$ is continuous. Suppose $x_n\to x$ in \mathcal{V}_{ν} . We get

$$\begin{split} |(\mathcal{H}x_n)(t) - (\mathcal{H}x)(t)| &\leq \int_{t_0}^t |F(s,x_n(s)) - F(s,x(s))| ds \\ &+ \sum_{(t_0,t)} |G_i(x_n(t_i)) - G_i(x(t_i))| \\ &\leq \int_{t_0}^{\infty} \lambda(s) |f(x_n(s)) - f(x(s))| ds \\ &+ \sum_{(t_0,\infty)} \beta_i |g(x_n(t_i)) - f(x(t_i))| \end{split}$$

and the continuity of the operator \mathcal{H} follows at once from the Lebesgue's theorem.

Remark 1: If F and G_i $(i = 1, 2, \cdots)$ are continuous functions then the second inequalities in (F) and (G) are not necessary to prove the continuity of the operator \mathcal{H} .

3 Main Results

Theorem 1 Assume that conditions (F), (G) and (I) are fulfilled. Let be (μ, t_0) satisfying (5), where r will be especified below. Then for $|x_0| \le \mu$ any solution $x = x(t, t_0, x_0)$ of Eq. (I) is defined and bounded on $|t_0, \infty\rangle$ and it satisfies (6). Moreover, $x(t_0) \ne 0$ implies $\xi \ne 0$ whenever t_0 is sufficiently large.

Proof: Since $0 \in U$ there exists r > 0 such that $B = B(0, r) \subset U$. For this r, let be μ, t_0 satisfying (5). We define

$$D = D(0,r) = \{x \in \mathcal{V}_{\nu^+}([t_0,\infty))/\|x\|_\infty \le r\}$$

For $x \in D$ we define the operator

$$(\mathcal{H}x)(t) = x_0 + \int_{t_0}^t F(s, x(s))ds + \sum_{t_i \in (t_0, t)} G_i(x(t_i))$$

for $t \geq t_0$. For $x \in D$ and $|x_0| \leq \mu$ by (F) and (G) we have $||\mathcal{H}x|| \leq \mu + \alpha(t_0) \leq r$ and hence $\mathcal{H}: D \to D$. The operator \mathcal{H} is continuous by Lemma 3. Moreover, $\mathcal{H}(D)$ is compact by Lemma 3. Then the hypothesis of Schauder-Tichonov fixed point theorem is satisfied and hence the equation $\mathcal{H}x = x$ has a solution x in D. Since $y = \mathcal{H}x$ satisfies

$$y'(t) = F(t, x(t)),$$
 $t \neq t_i$

$$\Delta y(t_i) = G_i(x(t_i)),$$
 $t = t_i$

this fixed point is a solution of Eq (1) and it satisfies (6) by (9).

Finally, we will prove that for any x with $x(t_0) \neq 0$ there exists t_0 sufficiently large such that (6) is satisfied with $\xi \neq 0$. This follows from (8) taking $x(t_0) = x_0 \neq 0$ and t_0 large enough so that

$$\left| \int_{t_0}^{\infty} F(x, x(s)) ds + \sum_{(t_0, \infty)} G_i(x(t_i)) \right| \le |x_0|/2.$$

Theorem 2 Assume that conditions (F), (G) and (I) are fulfilled. Then for any $\xi \in U$ there exist t_0 sufficiently big and a solution x of (I) defined on $[t_0, \infty)$ such that (G) holds. Moreover, if $\xi \neq 0$ then there exists such a solution x of Eq. (I) verifying $x(t) \neq 0$ for any $t \in [t_0, \infty)$.

Proof: Let $\xi \in U$, then there is r > 0 so that the closed ball $B = B[\xi, r] \subset U$. For this r let be t_0 such that

$$\alpha(t_0) = \|f\|_r \cdot \int_{t_0}^{\infty} \lambda(s)ds + \|g\|_r \cdot \sum_{i=1}^{\infty} \beta_i \le r, \tag{10}$$

where $||f||_r = max\{|f(s)|/x \in B\}$. Let

$$D = D(\xi, r) = \{x \in \mathcal{V}_{\nu}([t_0, \infty)) / \|x - \xi\|_{\infty} \le r\}.$$

For $x \in D$, we define the operator

$$(\mathcal{A}x)(t) = \xi - \int_t^{\infty} F(s, x(s))ds - \sum_{t_i \ge t} G_i(x(t_i)), \quad t \ge t_0$$

where t_0 verifies (10). Since

$$|(\mathcal{A}x)(t) - \xi| \le \alpha(t_0) \le r, \quad t \ge t_0 \tag{11}$$

we get $\mathcal{A}: D \to D$. We will now prove that \mathcal{A} is continuous. The functions f and g are uniformly continuous on B, hence given $\varepsilon > 0$ there exists $\delta > 0$ such that $|x_1 - x_2| < \delta$ implies $|f(x_1) - f(x_2)| \le \varepsilon$ and $|g(x_1) - g(x_2)| \le \varepsilon$. Let $x_n \to x$ in D. Then there is N such that

$$\sup_{t \in [t_0,\infty)} |x_n(t) - x(t)| \le \delta$$

for $n \geq N$. Thus $|x_n(t)-x(t)| \leq \delta$ for every $t \geq t_0$ and $n \geq N$. Therefore $|f(x_n(t))-f(x(t))| \leq \varepsilon$ for any $t \geq t_0$ and $n \geq N$. The same is true for the function g. Thus for $n \geq N$, we get

$$\|Ax_n - Ax\|$$
 = $sup_{t \in [t_0, \infty)}|Ax_n(t) - Ax(t)|$
 $\leq \int_{t_0}^{\infty} \lambda(s)|f(x_n(s)) - f(x(s))|ds$
 $+ \sum_{i=1}^{\infty} \beta_i|g(x_n(t_i)) - g(x(t_i))|$
 $\leq \varepsilon(\int_{t_0}^{\infty} \lambda(s)ds + \sum_{i=1}^{\infty} \beta_i)$

from where the continuity of A follows. Furthermore, D is a bounded, closed and convex set in V_{ν^+} . Since A(D) is equiconvergent by Lemma 2, A is a compact operator in V_{ν^+} .

Then the Schauder-Tichonov fixed point theorem implies that there exists a solution $x \in D$ of the equation x = Ax. This function x is solution of Eq.(1) on $[t_0, \infty)$.

Finally, if $\xi \neq 0$ then taking r small enough, as for instance $r = |\xi|/2$, from (11) we obtain that $x(t) \neq 0$ for every $t \geq t_0$.

Remark 2: The second inequalities in (F) and (G) are used in the last proof to prove the continuity of the operator A. Since we can use also the method of the proof of Lemma 1, by Remark 1, Theorems 1 and 2 are true if F and G_i $(i = 1, 2, \cdots)$ are continuous functions satisfying only the first inequalities in (F) and (G).

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