

Some Problems in Functional Differential Equations *

Manuel Pinto

Abstract.

Functional differential systems close to ordinary differential systems, which are an h -system in variations, are studied. We obtain existence results and asymptotic formulae for their solutions. Several explicit examples and applications are shown.

1 Systems of functional differential equations close to systems of ordinary differential equations.

In [1], Bellman proposed to investigate conditions on the lag r to know the behavior of solutions of the functional differential equation

$$u'(t) + au(t - r(t)) = 0, \quad a \text{ constant} \quad (1)$$

when $r(t) \rightarrow 0$ as $t \rightarrow \infty$. In [2], Cooke proves that if $r \in L_1([0, \infty))$ then any solution u of (1) satisfies

$$u(t) = e^{at}[c + o(1)], \quad t \rightarrow \infty$$

for some constant c . In [3], Cooke generalizes this result to linear systems of functional differential equations asymptotically autonomous. Grossman and Yorke [4] consider the one-dimensional functional differential equation

$$u'(t) = a(t)u(t - r(t)).$$

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We consider systems of functional differential equations which behave asymptotically as an ordinary h-system [5, 6]. That is to say, let $P : [0, \infty) \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ a continuous function with derivative $P_x = P_x(t, x)$ continuous for which the system

$$x' = P(t, x) \quad (2)$$

is an h-system in variation. We recall that (2) or the null-solution of (2) is an h-system in variation [5,6] if there exist a continuous function $h : [0, \infty) \rightarrow (0, \infty)$ and constants $K \geq 1$, and $\delta > 0$ such that for $0 \leq |x_0| < \delta$ we have

$$|\Phi(t, t_0, x_0)| \leq Kh(t)h(t_0)^{-1} \quad t \geq t_0 \geq 0$$

where $\Phi(t, t_0, x_0)$ is the fundamental matrix of the variational system

$$z' = P_x(t, x(t, t_0, x_0))z$$

with $\Phi(t_0, t_0, x_0) = \text{Id}$ (the identity matrix)

Further, let $F : [0, \infty) \times C_0 \rightarrow \mathbb{R}^n$ for which the system

$$y' = F(t, y_t) \quad (3)$$

verifies

$$|F(t, y_t) - P(t, y)| \leq r(t) \|y_t'\|, \quad (4)$$

where $r \in C([0, \infty), \mathbb{R})$ and $0 \leq r(t) \leq q$. Here $C_0 = C([-q, 0], \mathbb{R}^n)$ and if $y \in C([t-q, t], \mathbb{R}^n)$, we denote y_t the element in C_0 defined by

$$y_t(s) = y(t+s), \quad -q \leq s \leq 0.$$

We define also for $y \in C([t-2q, t], \mathbb{R}^n)$:

$$y_t(s) = y(t+s), \quad -2q \leq s \leq 0.$$

Moreover, we define

$$\|y\| = \sup_{-q \leq s \leq 0} |y(s)|,$$

and

$$\|y\|_2 = \sup_{-2q \leq s \leq 0} |y(s)|$$

Theorem 1.1 Assume

(i) The ordinary differential system (2) is an h-system, with radius of attraction δ

(ii) There exists a continuous and nonnegative function $c(t)$ such that

$$|F(t, g)| \leq c(t) \|g\|$$

for all $t \geq 0$ and all $g \in C_0$.

(iii) There exists a continuous and nonnegative function $r = r(t)$ such that for all continuously differentiable $g \in C_0$ and all $t \geq 0$:

$$|F(t, g) - P(t, g(0))| \leq r(t) \|g'_t\|$$

(iv) $\beta(t)r(t) \|c_t\| \in L_1([0, \infty))$, where $\beta(t) = h(t)^{-1} \|t^h\|_2$.

Then for any solution $y = y(t; t_0, y_{t_0})$ of (3) with $\|y_{t_0}\| \leq \delta$ there exists a solution x of (1) such that $y = x + h \cdot \bar{o}$ (1), where \bar{o} (1) is a function defined on $[t_0, \infty)$ which converges as $t \rightarrow \infty$.

Proof If $|y(t_0)| \leq \delta$, then the solution $x = x(t; t_0, y(t_0))$ is well defined and verifies $|x(t, t_0, y(t_0))| \leq K |y(t_0)| h(t)h(t_0)^{-1}$ for $t \geq t_0 \geq 0$ and $K \geq 1$ a constant. Now, by (ii) $y = y(t, t_0, y_{t_0})$ is defined on $[t_0 - q, \infty)$. By the formula of variation of the constants, we have for $t \geq t_1 \geq t_0$

$$y(t) = x(t; t_1, y(t_1)) + \int_{t_1}^t \Phi(t, s, y(s)) [F(s, y_s) - P(s, y(s))] ds. \quad (5)$$

Then, by (i) and (ii)

$$|y(t)| \leq K |y(t_1)| h(t)h(t_1)^{-1} + Kh(t) \int_{t_1}^t h(s)^{-1} r(s) \|y'_s\| ds$$

or

$$h(t)^{-1} |y(t)| \leq Kh(t_1)^{-1} |y(t_1)| + K \int_{t_1}^t r(s)h(s)^{-1} \|y'_s\| ds.$$

Thus $z(t) = h(t)^{-1} |y(t)|$ satisfies

$$z(t) \leq Kz(t_1) + \int_{t_1}^t Kr(s)h(s)^{-1} \|y'_s\| ds. \quad (6)$$

For $u \in I = [-q, 0]$ and $s \geq t_1$, by (ii), we have

$$|y'_s(u)| = |F(s+u, y_{s+u})| \leq c_s(u) \|y_{s+u}\| = c_s(u) |y(v)|$$

for some $v = v(s) \in [s - 2q, s]$. Further,

$$c(s+u)h(s)^{-1} |y(v)| = c(s+u)h(s)^{-1}h(v)z(v) \leq \beta(s)c(s+u)z(v).$$

Thus denoting $m(t) = \max\{z(u) : t_0 - 2q \leq u \leq t\}$ we get

$$h(s)^{-1} \|y'_s\| \leq \beta(s) \|c_s\| m(s). \quad (7)$$

Substituting this into (6) we obtain

$$z(t) \leq Kz(t_1) + \int_{t_1}^t Kr(s)\beta(s) \|c_s\| m(s) ds. \quad (8)$$

Since the right member of (8) is increasing as a function in t , we have $m(t) \leq Kz(t_1) + \int_{t_1}^t Kr(s)\beta(s) \|c_s\| m(s) ds$. Then by (iv), Gronwall's inequality implies

that m and hence z are bounded. Moreover, for any t fixed $\Phi(t, s, y(s))[F(s, y_s) - P(s, y(s))] \in L_1([0, \infty))$ as a function of s because by (i), (iii), (iv) and (7) we get

$$\begin{aligned} |\Phi(t, s, y(s))[F(s, y_s) - P(s, y(s))]| &\leq Kh(t)h(s)^{-1}r(s) \|y'_s\| \leq \\ &\leq K_1h(t) \|c_s\| r(s)\beta(s)m(s) \leq K_2h(t)r(s)\beta(s) \|c_s\| \in L_1([0, \infty)). \end{aligned}$$

Then the integral in (5) can be written as $h(t) \cdot \bar{o}(1)$, where $\bar{o}(1)$ denotes a function of t which has a limit as $t \rightarrow \infty$. ■

Theorem 1 includes the interesting type of equations as:

$$y' = F(t, y(t) - y(t - r(t))) \quad (9)$$

For this equation, system (2) becomes $x' = 0$ and (iii) becomes

$$|F(t, g)| \leq r(t) \|g'\| \quad (10)$$

Thus here $h \equiv 1, \beta \equiv 1$ and we have

Corollary 1.2 Let us assume (ii), (iv) with $\beta = 1$ and (iii) with (9) instead of (3). Then for any solution $y = y(t; t_0, y_{t_0})$ of (9) there exists a constant vector such that

$$y = y(t_0) + v + o(1)$$

as $t \rightarrow \infty$. In particular, any solution of (9) is asymptotically constant. ■

For equations $y' = y^3(t) - y^3(t - r(t))$ or $y' = [y(t) - y(t - r(t))]^3$ condition (4) becomes

$$|F(t, g)| \leq Kr(t)w(\|g'\|) \quad (11)$$

Thus from lemma 1, [5] we obtain:

Corollary 1.3 Assume (ii), (iv) and (iii) with (11) instead of (4). Then there exists a constant $\delta > 0$ such that any solution $y = y(t; t_0, y_{t_0})$ with $\|y_{t_0}\| \leq \delta$ is defined on $[t_0 - q, \infty)$ and

$$y = y(t_0) + v(t_0) + o(1), \quad t \rightarrow \infty$$

where $v = v(t_0)$ is a constant vector such that $v(t_0) \rightarrow 0$ as $t_0 \rightarrow \infty$. Moreover, $\delta = \delta(t_0)$ verifies $\delta(t_0) \rightarrow \infty$ as $t_0 \rightarrow \infty$. Then if t_0 is chosen large enough for any initial function φ there exists t_0 large enough such that the solution $y = y(t, t_0, \varphi)$ verifies the above property. ■

Corollary 1.4 If $\int_t^s a(u)du \leq K$, K constant, for $s - 2q \leq t \leq s$ and $a \|a_t\| \cdot r \in L_1([0, \infty))$, then the solutions of the scalar equation $y'(t) = a(t)y(t - r(t))$, satisfy

$$y(t) = \exp\left(\int_0^t a(s)ds\right)[c + o(1)], \quad c \text{ constant.}$$

Thus, in particular, the solutions of

$$y'(t) = -ty(t - e^{-3t}) \text{ and}$$

$$y'(t) = e^t y(t - e^{-2t})$$

satisfy respectively

$$y = e^{-\frac{t}{2}} [c + o(1)], \quad c \text{ constant and}$$

$$y = e^t [c + o(1)], \quad c \text{ constant}$$

■

Corollary 1.5 If A is an stable matrix, then any solution of

$$y' = Ay(t - r(t)), \quad r \in L_1([0, \infty))$$

satisfies

$$y = e^{tA} x_0 + e^{-\alpha t} \cdot \bar{o}(1)$$

where x_0 is a constant vector, $0 > \alpha > \max \operatorname{Re} \lambda$ with λ an eigenvalue of A and $\bar{o}(1)$ is a convergent vector as $t \rightarrow \infty$. ■

Corollary 1.6 If the system

$$x' = A(t)x$$

is an h -system strong and $r \cdot \|A\| \|A_t\| \in L_1([0, \infty))$, then any solution y of

$$y' = A(t)y(t - r(t))$$

satisfies

$$y = \Phi[y_0 + o(1)] \text{ as } t \rightarrow \infty$$

where y_0 is a constant vector and Φ is a fundamental matrix of (12). ■

2 Asymptotic formulae for the solutions of

$$y'' + c(t)y(t - r(t)) = 0$$

Consider the functional differential equation

$$y'' + c(t)y(t - r(t)) = 0 \quad (1)$$

where $c : [0, \infty) \rightarrow \mathbb{R}$ and $r : [0, \infty) \rightarrow [0, \infty)$ are continuous functions. For $r = r(t)$ small, in some sense which will be precised, we hope that the solutions y of (1) behave asymptotically as the solutions z of the ordinary differential equation.

$$z'' + c(t)z(t) = 0 \quad (2)$$

In fact, we will prove that any solution y of (1) are defined on all of $I = [0, \infty)$ and it satisfies as $t \rightarrow \infty$:

$$\begin{aligned} y &= (\delta_1 + o(1))z_1 + (\delta_2 + o(1))z_2 \\ y' &= (\delta_1 + o(1))z_1' + (\delta_2 + o(1))z_2' \end{aligned} \quad (3)$$

where $\{z_1, z_2\}$ is a fundamental system of solutions of Eq(2) and $\{\delta_1, \delta_2\}$ are constants.

Suppose $r(t) \leq q$ and consider the Banach space $C_o = C([-q, 0], \mathbb{R})$ with the norm

$$\|\varphi\| = \sup_{-q \leq s \leq 0} |\varphi(s)|, \quad \varphi \in C_o.$$

Furthermore, for $y \in C([0, \infty), \mathbb{R})$, we define y_t the useful element in C_0 given by

$$y_t(s) = y(t+s), \quad -q \leq s \leq 0$$

Let

$$y(t) = A(t)z_1(t) + B(t)z_2(t) \quad (4)$$

under the condition

$$A'z_1 + B'z_2 = 0 \quad (5)$$

Then, we have $y' = Az_1' + Bz_2'$ and $y'' = A'z_1' + B'z_2' + Az_1'' + Bz_2''$. Thus $y'' = A'z_1' + B'z_2' - c(Az_1 + Bz_2)$. Therefore

$$A'z_1' + B'z_2' = c(t)[y(t) - y(t-r(t))] \quad (6)$$

Solving Eqs. (5) and (6), we get

$$\begin{aligned} A' &= -w^{-1}z_2.c(t)[y(t) - y(t-r(t))] \\ B' &= w^{-1}z_1.c(t)[y(t) - y(t-r(t))] \end{aligned} \quad (7)$$

where w is the Wronskian of system $\{z_1, z_2\}$. Now, we have

$$\begin{aligned} |y(t) - y(t-r(t))| &= \left| \int_{t-r(t)}^t y'(s) ds \right| = \left| \int_{-r(t)}^0 y'(t+s) ds \right| \\ &= \left| \int_{-r(t)}^0 y_t'(s) ds \right| = \left| \int_{-r(t)}^0 (Az_1' + Bz_2')_t(s) ds \right|. \end{aligned}$$

Thus

$$|y(t) - y(t-r(t))| \leq r(t) \max_{i=1,2} \|z_{it}'\| \cdot (\|A_t\| + \|B_t\|)$$

Then, by system (7), the vector $x = (A, B)$ satisfies a system of functional differential equations of the type.

$$x' = F(t, x_t) \quad (8)$$

satisfying the conditions (i) $F : I \times C_0 \rightarrow \mathbb{R}$ is a continuous function, (ii) $|F(t, \varphi)| \leq \lambda(t) \|\varphi\|, (t, \varphi) \in I \times C_0$.

In this point, we need the following Theorem concerning the asymptotic behavior of system (8).

Theorem 2.1 Assume conditions (i), (ii) where $\lambda \in C(I, \mathbb{R})$ satisfy $\lambda(t) \in L_1(I)$. Then the solutions of Eq(8) are defined on all of I and they converge as $t \rightarrow \infty$.

The proof of this theorem is omitted because it is similar to Theorem 1.1. ■
Thus, we get:

Theorem 2.2 Assume that $r(t) | c(t) | \cdot | z_i(t) | \cdot \| z_{it} \| \in L_1(I) \quad i = 1, 2$. Then formulae (3) hold.

Proof The application of Theorem 1 implies that A and B converge as $t \rightarrow \infty$. The formulae (3) follow by (4) and (5). ■

Corollary 2.3 If $r \in L_1(I)$, then any solution y of the functional differential equation

$$y'' + ay(t - r(t)) = 0, \quad a > 0 \text{ constant}$$

satisfies for $t \rightarrow \infty$,

$$y = (\delta_1 + o(1)) \sin at + (\delta_2 + o(1)) \cos at$$

$$y' = a(\delta_1 + o(1)) \cos at - a(\delta_2 + o(1)) \sin at.$$

■
Corollary 2.4 If $c(t) \in C^2(I)$, $c > 0$ and $c^{-3/2}c''$, $r(t) \cdot |c^{-3/4}(t)| \|c_1^{-1/4}\| \in L_1(I)$ then any solution y of the functional differential equation

$$y'' + c(t)y(t - r(t)) = 0$$

satisfies for $t \rightarrow \infty$

$$y = c(t)^{-1/4} [(\delta_1 + o(1)) \exp(i \int^t c^{1/2}(s) ds) + (\delta_2 + o(1)) \exp(-i \int^t c^{1/2}(s) ds)]$$

$$y' = c(t)^{1/4} [i(\delta_1 + o(1)) \exp(i \int^t c^{1/2}(s) ds) - i(\delta_2 + o(1)) \exp(-i \int^t c^{1/2}(s) ds)].$$

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Dirección del autor:

Manuel Pinto

Depto. de Matemáticas. Fac de Ciencias. Universidad de Chile
Casilla 653. Santiago. Chile