# On Elastic Mechanical Stratified Slabs (frictional or no brake-lining) 

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Summary. - In that paper are analitically definied the geometricalstructuristic index of the agglomerated materials - artificially builded when they to the remarkable stresses are subject. That results to attain the best realizations of the thermo-piezo-mix, with a great yielding, can be gained.

Riassunto. - Vengono qui definite analiticamente le incidenze geo-metrico-strutturistiche sulle ripercussioni meccaniche di resistenza dei materiali composti (artificialmente realizzati con mix-piezotermici), quando sono sollecitate da adeguate forze.

Da qui l'opportunità d'avvalersi di questi risultati al fine di risalire, (per dati tipi standard di sollecitazioni meccaniche), a prassi d'agglomerazione costruttive di maggior efficienza, ferme restando le componenti chi-mico-fisiche dei compositi isotropi.

Résumé. - On a ici défini analytiquement les indices géometriquestructuristiques des materiaux agglomérés artificiellement construits, lorsque ils sont assojettis à remarquables contraints.

Il s'ensuit qu'on peut utiliser ces résultats, à fin d'arriver aux meil. leurs possibles realisations de thermo-piezo-mix, à fort rendement.

1.     - The lining compounded with dry or wet fibre, granules, organic and inorganic dustes (various components, more or less accidentally oriented, mutually strenghtened, interweaved), appear isotrop with regard to their mechanical properties, the frictional ones included.

The friction from the tip to the root $\mu_{2}$ is greater than the friction $\mu_{1}$ from the root to the tip. Is defined the "directional coefficient"
$\delta=\left(\mu_{2}-\mu_{1}\right) /\left(\mu_{2}+\mu_{1}\right)$, profoundly affected by the presence of liquids pH (acid and alkaline solutions). Increase $\delta$ is a corresponding change in the "felting", greater in acids and alkali than in neutral solutions.

It is necessary to point out, though on the whole, specially in view of the making of brake-linings, deformations, performances, and some of the most important anisotropometrical aspects. It is valid the Hooke law (though partially), for the elastic fibres isorientated in the " postcure" mixtures.


Fig. 1

Effect of reduction in feed dimensions on orientation of fibres. " A material with fibres heterogeneously distribued is made to flow through a straight channel, the tendency will be to straighten out or orientate the fibres parallel with the direction of flow ".


Fig. $1 a$

Impact Low Flexibility Low Unoriented Unstretched

Impact High
Flexibility High
Oriented
Stretched

Orientation by mechanical working of molecule chains of polymerized vinylidene cloride.

It is valid the elastadesive property among elastically different ingredients, and are valid the rheological laws for components "polymers", organic and inorganic. All that requires complex distributions of stress in the manufactured material, according to the static load and those fluctuating applied, and the physic-chemical-mechanical geometrical structures of support.

Rayon threads


| Rubber threads | $\mid / \\|$ |
| :--- | :--- |
| Under tension | $\\|$ |$|$

Microscopic appearance fibres Longitudinal view.


Cross-sectional View

Fig. $1 b$
An external load $P$, working on a vehicle brake-blocks, will place itself among the single members of the lining, proportionally to the elastic modules, to the bearing sections, with transferts of partial loads due to adhesivity: $A_{a, e}$ elastic, in subordinate relation to the quantities:

$$
\begin{equation*}
A_{a, e}=\frac{k P \sum\left(E_{i+1}-E_{i}\right)}{\left(S_{i} E_{i}+S_{i+1} \times E_{i+1}\right)}, \tag{1}
\end{equation*}
$$

with $K_{i}$ coefficient, produced by the bearing areas: $S_{i} \cdot S_{i+1}$, divided by the sum of such products by the relative elastic mod. $\sum S_{i} E_{i}$. The eventual "elastic inadhesivities" are made up for by the "chemical adhesivities", "absorptions", inner mechanisms "between the phatses". Only one type of organic polymer therefore will be able to alloy differently (bond degree) according to the visco-elastic heterogeneity of the matrix.
"Fibrous materials" increase mechanical strength, stiffness, impact resistance, dimensional stability, and are often one-bi-more-direc-
tional properties (direction of the reinforcement). Fibres are flexibility and finesses (ultimate tensile strength of chrysotile fibres and various types of asbestos is approximately 50000 psi , with an extremely large surface area value-which is a very important property).

Comparison of average tensile strengths of various materials, give 155000 psi for carbon steel, against $100-2000$ glass fibre, 80000 to 200000 chrysotile asbestos, 10000 to 300 crocidolite, 1000 to 8000 tremolite asbestos.

It must not be undervalued the "Heat resistance" on the strength of fibres, showing the chrysotile a "breaking strength " nearly steady up to $400^{\circ}-500^{\circ}$, unlike other fibres (amianthus or glass fibres) more resistent up to the $T=200^{\circ}$ (breaking temperature).

Electron micrographs of the asbesto-fibres have indicated that they may exist as hollow tubes several hundred angstromes in diameter.

Thereafter we should consider, post-cure, preferencial or principal directions of fibre-reinforced, substratificated ortotropic structures (balanced or not, following the number of the fibres, steady or not, in each direction).

Anyway the elastic-plastic-resistent properties can differ, post-cure, in the various directions.

Once fixed a load (static of fluctuating), working for the moment with a steady mean direction (viz. vertical), we want to find out how the mechanical reactions place themself on the slabs, isotrop and not, subject to stresses (fibrous anisotropy).

The mod. of elasticity $E$, the shearing modulus $G$ (in isotropic bodies), remain steady in any direction, and so "the stress $\sigma$, the shearing stress $\tau$, caused constants strain $\varepsilon$ and $\gamma(\varepsilon=\sigma / E, \gamma=\tau / G)$, and constant $\varepsilon_{T}=v_{E} \quad(y=$ Poissons's ratio).

With transverse strains (contraction or dilation), in anisotropic e.g. "orthotropic materials", occurs to reconstruct stress-strain diagrams, hence to find the elastic modulus in the longitudinal $L$ in the trasversal $T$ directions ( $E_{L}, E_{T}$ ), the shearing modulus $G_{L T}$ associated with these directions; the Poissons's ratio $\nu_{L T}$ caused by transverse strain a stress in $L$ direction, $v_{L T}$ idem in the $T$ direction. So that the modulus at any intermediate angle is $E_{1}$ (in function of $\alpha, E_{L}, E_{T}, G_{L T}$, $\nu_{L T}$ ), and if $\sigma_{1}$ is a stress applied in the 1 -direction at an angle $\alpha$ with $\sigma_{1}-L \rightarrow 0^{\circ} ; T \rightarrow 90^{\circ}-$, we have the most simple case of anisotropy. This is a particularly important point: the fibrous layer is not undamaged, when it is subejected to a strain, by its mean orientation with regard to a fixed direction (viz. the direction of a static or fluctuating
agent load), it influences in fact the quantities relative to the mechanical deformations, though the sperimental data $E_{L}, E_{T}, G_{L T}$ remain unchanged.

As the "cure piezo-termics" affect the frictiograms, on the coefficient $\mu$ and other mechanical (with the same combination of the packing's ingredients), thus the "cure" mix, extrusive, to which the fibrous layers are bound, affect the anisotropic pecularities of the lining, sometimes with remarkable incidences, as we can see afterwards.

We relate in the meantime, as a proof of what we stated, some comparative graphics of the functional quantities: $E_{1} / E_{L} ; G_{12} / G_{L T}$ (functions of the angle between direction of stress and the longitudinal axis of the material).


Fig. 2

The mod. $E_{L}, E_{T}$ are known, and therefore we have as a result of the graphic in Fig. 2, the unkown $E_{1}\left(\alpha, E_{L}\right)$; likewise, when the mod. $G_{L T}, \nu_{L T}, \nu_{T L 2}$ are measured in the directions $L$ (longitudinal) and $T$ (transversal), we have as a result $G_{12}$ etc...

The ratio $E_{1} / E_{L}$ is made up of the sum of three terms:
$\cos ^{4} \alpha \quad$ (directional term),
$E_{L} \cdot \operatorname{sen}^{4} \alpha \quad$ (mixed geometric-mechanical term),
$1 / 4\left(E_{L} / E_{T}-2 v_{L T}\right) \operatorname{sen}^{2} 2 \alpha$ (mixed term).
Therefore $E_{1} / E_{L}$ engages all the elastic terms relative to the fibres $E_{L}, E_{T}, G_{L T}, \nu_{L T}$, as well as the joined "directionalities".

Angle $\alpha=0^{\circ}$ is longitudinal direction, angle $\alpha-90^{\circ}$ is transverse direction, $\alpha E_{1} / E_{L}$, read on the graphic of Fig. 2, allows to obtain the $\bmod . E$, mod. of elasticity in any reference direction.

The ratio $E_{1} / E_{L}$ is symmetrical with regard to the ordinate crossing angle $a=45^{\circ}$ (Fig. 2), with " balanced orthotropic material o.m.b.", while for "unbalanced orthotropic material", and for $\alpha=90^{\circ}, E_{1} / E_{L}$ $\alpha \rightarrow$ to asymptotic minimum (evident dissymmetry).

Thus $G_{12} / G_{L T}$ ( $G_{L T}$ is the shearing modulus associated with $L$ and $T$ directions), is symmetrical to $45^{\circ}$, unlike $E_{1} / E_{L}$ in the cases "o.m.b." and "o.m.u." (v. Fig. 2a).

Two factores $m_{1}, m_{2}$ (eaused by shear and direct stresses respectively) showing symmetrical but different behaviours, have been introduced.


Fig. $2 a$

The ratio $E_{L} / E_{1}$ depends on $\alpha, E, G, \nu_{L T}$, as well as $G_{L T} / G_{12}$, $v_{12}$ depend on $a, E, E, v_{L T}$, all quantities which can be measured in advance.

In these considerations we have voluntarily left out "plastic states" of the material, so that the bending moment of the structure comes out to be higher even of the $50 \%$ with regard to the elastic limit moment:

$$
M y(M p=k M y) ; \quad k=1,5 \quad \text { (for rectangular sections). }
$$

In a laminar solid, Fibreglass-Ru-Re-Fillers, $E_{L} / E_{T}=10$, where only $\mathrm{Ru}, E_{T}$ (according to the hardness) can go down to $120-1300 \mathrm{psi}$; being $E_{L}=5.106, E_{T}=0,5.10^{6}, G_{L T}=0,55.10^{6} \mathrm{psi}, \nu_{L T}=\nu_{o}=0,45$, $\nu_{T L}=\nu_{300}=0,045$.


Fig. 3
The tensile stress $\sigma_{1}$, acting on the small plate at the top, is $10^{1} \mathrm{psi}$; the shear stress $\tau_{12}=4000 \mathrm{psi}$.

The stress $\sigma_{1}$, applied in the 1 -direction (Fig. 9) causes a strain $\varepsilon_{1}=\sigma_{1} / E_{1}$. A transverse strain $\varepsilon_{2}$ is cansed by $\sigma_{1}$, where $\varepsilon_{2}=-v_{12} \varepsilon$. Unlike isotropic materials, stress $\sigma_{1}$, when applied at any angle axcept $0^{\circ}$ and $90^{\circ}$, causes shear distortion and the shear strain $\gamma_{12}=-m_{1} \sigma_{1} / E_{L}$, where $m_{1}=m_{1}\left(a, v_{L T}, E_{L}, E_{T}, G_{L T}\right)$.

A shearing stress $\tau_{12}$ applied in 1-2 directions (r. Fig. 7) causes a shear strain $\gamma_{12}=\tau_{12} / G_{12}$, where $G_{12}=G_{12}\left(a, G_{L T}, \nu_{L T}, E_{L}, E_{T}, \nu_{L T}\right)$.

Consequently, strain caused by $\sigma_{1}$ are $\varepsilon_{1}, \varepsilon_{2}, \gamma_{12}$; strain caused by $\tau_{12}$ are $\varepsilon_{1}^{\prime}, \varepsilon_{\varepsilon}^{\prime}, \gamma_{2}^{\prime}$; total strain being $\varepsilon_{1}+\varepsilon_{i}^{\prime}, \varepsilon_{2}+\varepsilon_{0}^{\prime}, \gamma_{2}+\gamma_{2}^{\prime}$.

The diagrams showed above (Fig. 1 and $2 a$ ), which join these mechanical quantities to the angle amu st be prepared each time according to the materials ( $E_{L}, E_{T}, G_{L T}, \nu_{L T}$ ).

Thanks to them we obtain the "strains" caused by $\sigma_{1}$, and the "strains" caused by $\tau_{12}$, as we can see here following:

$$
\left\{\begin{array}{l}
\sigma_{1} \rightarrow \varepsilon_{1}=\sigma_{1} / E_{1}, \quad \varepsilon_{2}=--v_{12} \varepsilon_{1}, \quad \gamma_{12}=-m_{1} \sigma_{1} / E_{L}  \tag{2}\\
\tau_{12} \rightarrow \varepsilon_{1}^{\prime}=-m_{1} \tau_{12} / E_{L}, \quad \varepsilon_{2}^{\prime}=-m_{2} \tau_{12} / E_{L}, \quad \gamma_{12}^{\prime}=\tau_{12} / G_{12}
\end{array}\right.
$$

The quantities $E_{L}^{i} E_{1}(\alpha), G_{L T}^{1} G_{12}(\alpha), \nu_{12}(\alpha)$, for small variations of the "stifiness factor $E I$ ", "section modulus" for outermost fibre,
"bending and shear stress". can lead to great differences in the results. As for the structures $0 . m . b$. or u.m.b., the variations in the same stresses $\sigma_{1}, \tau_{12}\left(\Delta \varepsilon_{1}, \Delta \varepsilon_{2}, \Delta \gamma_{12}\right)$ are remarkably different. In both we can note negative minimum for $\varepsilon_{2}\left(a \sim 30^{\circ}\right)$, and positive minimum for $\gamma_{12}\left(\alpha \sim 30^{\circ}\right)$. The deformation $\varepsilon_{1}$, is max. for $\alpha=45^{\circ} 0 . m$.b., while the u.m.b. always increases with a strong gradient, also after $\alpha=30^{\circ}$, and has no max.

The deformations $\varepsilon_{1}$, due to traction (in the direction of $\sigma_{1}$ ) in all eases, go constantly through either max. or other values, because the directional anisotropy increases according to the direction of the agent stress. The $\varepsilon_{2}$, compressives (usually at the direction $\sigma_{1}$ ), in all cases, they no reach max. too different from a order of quantity generally $<\varepsilon_{1}$. The shear deformations $\gamma_{12}$ reach minimum at $30^{\circ}$, and appear very like, either with o.m.b. or with u.m.b., both in their behaviour and in their absolute values.
"Particular directionalities" appear mainly at $30^{\circ}$ and $45^{\circ}$, including our openings of lining (usually inferior to $80^{\circ}$ ).

Superposing several thin plates, at crossed directions, those effect of fibrousity will be attenuated (pseudo-isotropy).
2. - Fibrous glass or asbestos reinforced plastics may be "composite and non-isotropic ".

Composite structure: various layers may be oriented at different angles with respect to each other, in order to provide the best combination to resist loading condition. Outside loads applied result in "internal stresses", different individual layers (meeting to the layer's fibrousity). Strains and stresses are induced in each layer: external stresses may result not only in internal stresses, but in internal shear stresses. Extermal shear stresses may result in internal stresses as well as internal shear stresses. The " composite structure", the most elementary, is the bi-layer. Internal stresses $\sigma_{1 a}, \sigma_{1 b}, \tau_{12 a}, \tau_{12 b}$, can be found in order that the sums of the internal stresses in the 1 and 2 directions must equal the external stresses in these directions, and the strains must be the same in all layers. As the layers are firmly bonded together, the strains are the same in $a$ and $b$ layers, and are equal to the strains n the whole structure. Therefore the fundamental conditions (in which the hypothesis is traslated) are:

$$
\left\{\begin{array}{l}
\varepsilon_{1 a}=\varepsilon_{1 b}=\varepsilon_{1} ; \quad \varepsilon_{2 a}=\varepsilon_{2 b}=\varepsilon_{2} ; \quad \gamma_{12 a}=\gamma_{12 b}=\gamma_{12}  \tag{3}\\
\sigma_{1 a} t_{a}+\sigma_{1 b} t_{b}=\sigma_{1} t ; \quad \sigma_{2 a} t_{a}+\sigma_{2 b} t_{b}=\sigma_{2} t \\
\tau_{12 a} t_{a}+\tau_{12 b} t_{b}=\tau_{12} t
\end{array}\right.
$$

where $t=$ total thickness of the bi-layer $=$ sum of $t_{a}$ and $t_{b}$, thicknesses of the horizontal superposed $a, b$, of different orthotropic materials oriented at arbitrary angles $\alpha$ and $\beta$. with respect to applied stresses $\sigma_{1}, \sigma_{2}, \tau_{12}$ ( $\sigma_{1}$ acting in direction $1 ; \sigma_{2}$ in the lower layer - acting in direction 2).

The "sandwich" is realized in the linings also under the "piezocure" (specially with remarkable thicknesses), because of the "plastic working of non-metallic materials", which decreases exponentially with the depth in the bonded layer.

The compressive stress between punch and die distorts the sheet and gives a stratigraphy (slip-plane movements).

Materials $a$ and $b$ have respectively longitudinal $L_{a}$ and $L_{b}$, and transverse directions $T_{a}, T_{b}$. The rational hypotesis done on the kind which we are studying (sandwich) impose:

$$
\begin{align*}
& \varepsilon_{1}=\varepsilon_{1 a}=c_{1 b}=f_{1}\left(\sigma_{1 a}, \widetilde{\sim}_{2 a}, E_{1 a}, E_{2 a}, F_{L a}, v_{21 a}, \tau_{12 a}, m_{1 a}\right), \\
& \varepsilon_{2}=\varepsilon_{2 a}=\varepsilon_{2 b}=f_{2}\left(\sigma_{1 a}, \sigma_{2 a}, E_{1 a}, E_{2 a}, E_{L b}, v_{12 a}, v_{12 b}, m_{2 b}\right) . \tag{4}
\end{align*}
$$

Solutions of the foregoing "linear equations", leads the three simultaneous equations, give the unknown: $\sigma_{1 a}, \sigma_{2 a}, \tau_{12 a}$.

The linear equations with three unknown $\sigma_{1 a}, \sigma_{2 a}, \tau_{12 a}$, can be more easily employed, also without solution:

$$
\left.\begin{array}{l}
\left\{\begin{array}{l}
t_{a} t_{b} / t\left(A_{11} \sigma_{1 a}+A_{12} \sigma_{2 a}+A_{13} \tau_{12 a}\right)=\sigma_{1} / E_{1 b}-v_{21} \sigma_{2} / E_{2 b}-m_{1 b} \tau_{12} / E_{L b} \\
t_{a} t_{b} / t\left(A_{21} \sigma_{1 a}+A_{22} \sigma_{2 a}+A_{23} \tau_{12 a}\right)=-\gamma_{12 b} \sigma_{1} / E_{13}+\sigma_{2} / E_{2 b}-m_{2 b} \tau_{12} / E_{L b} \\
t_{a} t_{b} / t\left(A_{31} \sigma_{1 a}+A_{32} \sigma_{2 a}+A_{33} \tau_{12 a}\right)=-m_{1 b} \sigma_{1} / E_{13}-m_{23} \sigma_{2} / E_{L b}+\tau_{12} / G_{12 b}
\end{array}\right. \\
A_{11}=1 / E_{1 a} t_{a}+1 / E_{1 b} t_{b} ; A_{22}=1 / E_{2 a} t_{a}+1 / E_{2 b} t_{b} ; A_{33}=1 / G_{12 a} t_{a}+1 / G_{12 b} t_{b} ;
\end{array}\right\} \begin{aligned}
& A_{21}=-v_{21 a} / E_{2 a} t_{a}-v_{21 b} / E_{2 b} t_{b} ; A_{13}=A_{31}=-m_{1 a} / E_{L a} t_{a}-m_{1 b} / E_{L b} t_{b} ; \\
& A_{23}=A_{32}=-m_{2 a} / E_{L a} t_{b}-m_{2 b} / E_{L b} t_{b} .
\end{aligned}
$$

In fact the coefficient $A_{i 1}, A_{j i}$ been known $E_{1 a}, E_{1 b}, E_{2 a}, E_{2 b}, E_{L a}$, $E_{L b}, G_{1 a}, G_{2 b}$ can be reduced, and moreover:

$$
A_{21}=A_{21} ; \quad A_{31}=A_{13}, \quad A_{32}=A_{23}
$$

We must use the diagrams of Fig. 2 and ga etc... likewise we work over a layer, of course been known $E_{1 a}, E_{1 b}, E_{2 a}, E_{2 b}$ which may, f. e., be equal to each other, and equal to $E_{L}\left(E_{L}=E_{T}\right)$ at the conditions $\alpha=0^{\circ}$, hence the relations $E_{1} / E_{L}=1$, or they are equal to each other at the conditions

$$
E_{800}, E_{300}\left(E_{1 a}=E_{1 b}=E_{300}\right) ; E_{2 a}=E_{2 b}=E_{600} ; \nu_{L T} / \nu_{T L}=E_{L} / E_{T}
$$

The other three equations for $\sigma_{1 b}, \sigma_{2 b}, \tau_{12 b}$, come from:

$$
\begin{equation*}
\sigma_{1 b} t_{b}=\sigma_{1} t-\sigma_{1 a} t_{a} ; \sigma_{2 b} t_{b}=\sigma_{2} t-\sigma_{2 a} t_{a} ; \tau_{12 b} t_{b}=\tau_{12} t-\tau_{12 a} \tag{6}
\end{equation*}
$$

3.     - For computing stresses, stiffness, for the "composite structures", some modifications of the standard formulas, which below we relate:

Isotropic materials


Non-isotropic materlals

| Moment of Inertia <br> Cross section composite beam $I_{i}=b d_{i}{ }^{3} / 12$ | Stiffness Factor $E_{i}, A_{i}, x_{i}$ <br> are mod. of el., cross sectional area $b d i=A i$ and distance from the bottom of cross section, to the centre of gravity of any particular layer. | Bending Stress <br> $E_{y}=\bmod$. el. for the layer at $y$ point. The max. bending stress not necessarily occur at the ontermost (bottom) fibre, as it does in isotropic materials. | Shear Stress <br> $v$ is the total shear on the cross section, $\tau=$ shear stress intensity along some horizontal plane, $Q^{\prime}$ is the weighted statical moment $E_{i} A_{i} y^{\prime}$ about the n.a. of the portions of the c.s. between the horizontal plane and the bottom of the c.s. |
| :---: | :---: | :---: | :---: |

A plane packing with "adherent and composite slab":


Fig. 5
For a unit bending moment $M=1$ in-lb:

| Plane | $y$ | $\begin{gathered} E_{y} \\ (\text { noti }) \end{gathered}$ | $\begin{gathered} \sigma_{y}=y E_{y} / E I \\ \text { in-lb } \end{gathered}$ | $\sigma / \sigma_{y}$ in-lib | M |
| :---: | :---: | :---: | :---: | :---: | :---: |
| (a-a) | 0,77" | $10.10^{6} \mathrm{psi}$ | $7,7 / 0,45=1,7$ | $(40000 \mathrm{psi}) / 1,7=$ | 2400 in-lb |
| (b-b) | 0,27" | $1.10^{6} \mathrm{psi}$ | $0,27 / 0,45=0,6$ | $(20000 \mathrm{psi}) / 0,6=$ | 33000 in-lb |
| (c-c) | 0,23" | $1.10^{6} \mathrm{psi}$ | $0,23 / 0,45=0.5$ | $(20000 \mathrm{psi}) / 0,5=$ | 40000 in-lb |



Fig. 6

Here appear a "critical plane" not "interstratified" but the bottom of the "bi-composite". The "internal moment" or " moment of resistance " $M=E I / R=E / R \sum a y^{2}$, in the "isotrops ", is inversily proportional to the bending radius, in the "composites" is no more proportional " to the square of the depth, but to the 1.89 power of the depth". In Fig. 6, we study the aase of 6 layers horizontal superposed, with different elastic modulus, and different thickness, of which we have calculated the resistence's moments $\sigma y=F_{y} y / E I ; E I=\sum E_{i} I_{i}$ : (Fig. 6).

## Internal Moment.

The length of the horizontal line (dash and point) gives the value of $M$ in in-lb (max. $10.200 \mathrm{inl-b}$, min. $3500 \mathrm{in}-\mathrm{lb}$ ) and we can note how the material is differently stresses inside.
4. - Let us consider at last the situation of a plane superficial element of "lining" (Fig. 7), a real shape of which, with a given strain $p$, we


Fig. 7
have the "circumferential stress" $\sigma_{1}=p r_{0}$ and the "longitudinal stress" $\sigma_{2}=1 / 2 \sigma_{1}$ that is half value.

We can see different fibrous orientations, concerning the two superposed planes; the parallel to 1 (circumferential direction) $-T_{a}$ perpendicular, $L_{b}$ parallel to $2, T_{b}$ normal, circumferential and axials directions 1,2 (intertwisted); or $L_{a}$ at $45^{\circ}$ with $1, T_{a}$ normal, $L_{b}$ parallel underlying to $T_{a}$, and $T_{b}$ parallel to $L_{a}$; being $t_{a} \geq t_{b}$ in any case. The
angle $\alpha\left(L_{a 1}\right)$ can be anyone, and the angle $\beta\left(L_{b}, 1\right)(\alpha=\beta, \alpha \neq \beta)$ too. The calculus become easier as:
$E_{1 a}=E_{1 b}=E_{2 a}=E_{2 b} \quad ; \nu_{12 a}=v_{21 a}=v_{12 b}=\gamma_{21 b} ; m_{1 a}=m_{1 b}=m_{2 a}=m_{2 b}=0$
$A_{12}=A_{21} \quad ; A_{13}=A_{31}=A_{32}=A_{23}=0$
$A_{11}=1 / E_{1 a} t_{a}+1 / E_{1 b} t_{b} ; A_{11}=A_{22}$
$A_{22}=1 / E_{2 a} t_{a}+1 / E_{2 b} t_{b}$
values which must be introduced in the three fundamental equations hence these become:

$$
\left\{\begin{array}{l}
A_{11} \sigma_{1 a}+A_{12} \sigma_{2 a}=\frac{t}{t_{a} \tau}\left(\sigma_{1} / E_{1 b}-v_{12} \sigma_{2} / E_{2 b}\right) \\
A_{21} \sigma_{1 a}+A_{22} \sigma_{2 a}=\frac{t}{t_{a} t_{b}}\left(-v_{12 b} \sigma_{1} / E_{1 b}+\sigma_{2} / E_{2 b}\right) ; A_{33} \tau_{12}=0 \tag{8}
\end{array}\right.
$$

from where we get our unknowns:

$$
\sigma_{1 a}=\sigma_{1 b}=\sigma_{1} ; \quad \sigma_{2 a}-\sigma_{2 b}=\sigma_{2} ; \quad \tau_{12 a}=\tau_{12 b}-\hat{v}
$$

internal stresses, which become equal to the external strains, with no shear internal stresses, also for shear strains different from zero.

The symmetry of the orientations of the fibres with regard to the main directions of the stresses 1-2, cause the internal stresses $\sigma_{1 a}, \sigma_{1 b}$, $\sigma_{2}, a \sigma_{2 b}$ to be equal the external stresses imposed $\sigma_{1}, \sigma_{2}$ and annul the internal stress shear, although we impose external stresses shear.

For:

$$
\begin{align*}
& E_{1 a}=E_{1 b}=E_{500}=E_{600}=E_{2 a}=E_{2 b} \\
& G_{12 a}=G_{12 b} ; \quad \nu_{12 a}=\nu_{12 b}=v_{300}=v_{600}=v_{21 a}-v_{21 b} \\
& m_{1 a}=m_{300} ; \quad m_{1 b}=-m_{1 a} \\
& m_{2 a}=m_{600} ; \quad m_{2 b}=-m_{2 b}
\end{align*}
$$

the fundamental equations will be different from the previous only in the $3^{\text {tu }}$ (the first two remain same, showing that the internal stresses are equal to those imposed)

$$
\begin{equation*}
A_{33} \tau_{12 a}=\frac{t}{t_{a} t_{b}}\left(-m_{1 b} \sigma_{1} / E_{1 b}-m_{2 b} \sigma_{2} / E_{1 b}\right) . \tag{10}
\end{equation*}
$$

Therefore being $\sigma_{1 a}=\sigma_{1 b}=\sigma_{1} ; \sigma_{2 a}=\sigma_{2 b}=\sigma_{2}$, from the third equation we get $\tau_{12 a} \neq 0$. Remarkable stresses shear appear when the layers are so oriented "even if there are no external shear stresses". The shear stresses in layers $b$ are oriented in the opposite direction to the shear stresses in layers $a$.
5. - We determine at this point the position of the max. pressure and the distribution of the pressure on the lining (rigid shoe calculation).


Fig. 8
In Fig. 8, there is the "centre of drag ", point where act the resultant of the forces of the shoe on the drum $s$. The centre of the drum



Fig. 9
with radius $r$ is remarked by $0 ; \overline{A B}$ is the arch of contact of the shoepacking; $C_{1}$ is the centre point of the shoe pivot.

We can also the max. pressure $\bar{O} Q_{1}$ "pressure distribution ". and resultant line of pressure $\overline{O G} \bar{G}_{1}$; the angle of friction $\Phi$, the brake force for shoe $F_{1}$.


Fig. 10

More types of construction for " composites", can be easily studied: layers $a$ and $b$ with the $L$ and $T$ direction laid in the circumferential and axial directions; the layers are laid at $\alpha=10^{\circ}, 20^{\circ}, 30^{\circ}, 45^{\circ}$, to the
axis of the cylinder, e.g. alternate $30^{\circ}$ angles in left-hand and righthand spirals. For the position $\alpha=0^{\circ}, 45^{\circ}, 90^{\circ}$, we have:

$$
\begin{cases}E_{1 a} / E_{L}=1 ; \quad E_{1 b} / E_{L}=1 ; & E_{2 a} / E_{L}=1 ; \quad E_{2 b} / E_{L}=1 \\ m_{1 a}=m_{1 b}=m_{2 a}-m_{2 b}=0 ; & v_{12 a}-v_{21 a}=v_{12 b}=v_{21 b}=v_{L T}\end{cases}
$$

and therefore:

$$
\sigma_{1 a}--_{i j}=\vec{v}_{1}, \quad \sigma_{2 a}=\sigma_{2 b}=\sigma_{2} ; \quad \tau_{12 a}=\tau_{12 b}=\hat{v} .
$$



Fig. 10a

For the remaining $\alpha$, we obtaine:

$$
\left\{\begin{array}{l}
E_{1 a}=E_{1 b}=E_{300}=E_{000}=\bar{m}_{\mathrm{s}: i}=E_{2 b}=E_{L}  \tag{13}\\
G_{12 a}=G_{12 b}=G_{L T} \\
v_{L T}=v_{T L}
\end{array}\right.
$$

The first two fundamental equations do not change, however:

$$
\begin{equation*}
\sigma_{1 a}=\sigma_{1 b}=\sigma_{1} ; \quad \sigma_{2 a}=\sigma_{2 \Delta}=\sigma_{2} \tag{14}
\end{equation*}
$$

while the third becomes:

$$
\begin{equation*}
\tau_{12 a}\left(1 / G_{12 a} t_{b}+1 / G_{12 b} t_{b}\right)=\frac{t_{=}}{t_{a} i_{b}}\left(-m_{1 b} \sigma_{1} / E_{L b}-m_{2 b} \sigma_{2} / E_{L b}\right) \tag{15}
\end{equation*}
$$

from which

$$
\begin{equation*}
\tau_{12 a} \neq 0 \tag{16}
\end{equation*}
$$

Therefore being $\alpha=0^{\circ}, \alpha=-45^{\circ}, \alpha=90^{\circ}$, the shear deformations disappear, while such shear deformations appear again being $\alpha=10^{\circ}$, $20^{\circ}, 30^{\circ}, 40^{\circ}, 60^{\circ}, 70^{\circ}, 80^{\circ}, 90^{\circ}$, with max. values for $\alpha=25^{\circ}$ and $\alpha=65^{\circ}$.

While reckoning the stresses internal to the fibrous or no packing, we must, of course, keep into consideration the variation of the loads (Fig. 9) which give the $\sigma_{1}$ and $\tau_{12}$ measurable or obtainable, and therefore, going away from the zone of max. pressure, also the joining affects possible fibrousities of the fibrous lining, with mono or multi-structure, will fade. We have studied then the main principal possible incidences (Figg. 10-10a), keeping unchanged the constitutive formulas (qualitative and quantitative) of the ingredients and load-stress, on the deformations of the brake-lining (isotrop, anisotrop, fibrous and stratiform structures).

